

Quantum Mechanics of rf Spin Echo in Nuclear magnetic resonance

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The quantum mechanics is used to understand the essential points for the spin echo method of nuclear magnetic resonance (NMR). A static magnetic field is applied along a nuclear spin with angular momentum $\hbar\hat{I}$ and the magnetic moment $\gamma\hbar\hat{I}$, where γ is the gyromagnetic ratio. The static magnetic field is applied along the z axis. The radio frequency (r.f.) field magnetic field is applied along the plane perpendicular to the z axis. Here we consider the case of spin 1/2 system.

1. Gyromagnetic ratio of nuclear spin

(a) Electron

Orbital angular momentum and orbital magnetic moment

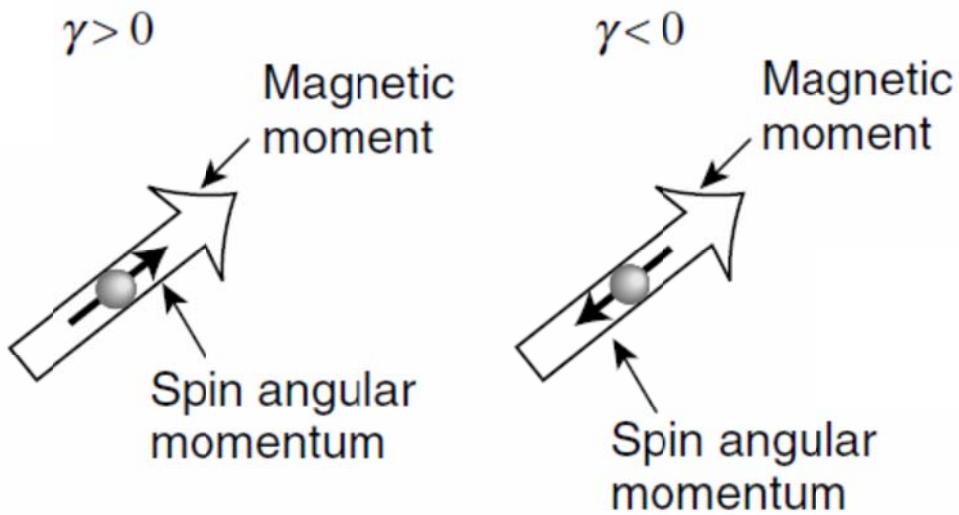
$$\gamma_L = \frac{\boldsymbol{\mu}_L}{\mathbf{L}} = \frac{-\mu_B \frac{\mathbf{L}}{\hbar}}{\mathbf{L}} = -\frac{\mu_B}{\hbar} = -\frac{e}{2mc}$$

Spin angular momentum and spin magnetic moment

$$\gamma_S = \frac{\boldsymbol{\mu}_S}{\mathbf{S}} = \frac{-g_e \mu_B \frac{\mathbf{S}}{\hbar}}{\mathbf{S}} = -\frac{g_e \mu_B}{\hbar} = -g_e \frac{e}{2mc}$$

where $g = 2.0023193043617(15)$.

(b) Proton (neutron); nuclear spin



The gyromagnetic ratio is defined by

$$\gamma_N = \frac{\mu_I}{\hbar I} = \frac{g_n \mu_N I}{\hbar I} = \frac{g_n \mu_N}{\hbar} = g_n \frac{e}{2m_p c}$$

where $\hbar I$ is the angular momentum.

Table-1: Gyromagnetic ratio

Nucleus	$(10^6 \text{ rad s}^{-1} \text{ T}^{-1})$	(MHz T^{-1})
^1H	267.513	42.577 478 92(29)
^2H	41.065	6.536
^3He	-203.789	-32.434
^7Li	103.962	16.546
^{13}C	67.262	10.705
^{14}N	19.331	3.077
^{15}N	-27.116	-4.316
^{17}O	-36.264	-5.772
^{19}F	251.662	40.052
^{23}Na	70.761	11.262
^{27}Al	69.763	11.103
^{29}Si	-53.190	-8.465
^{31}P	108.291	17.235
^{57}Fe	8.681	1.382
^{63}Cu	71.118	11.319
^{67}Zn	16.767	2.669
^{129}Xe	-73.997	-11.777

2. Spin recession

(a) Classical treatment

The magnetic moment of nuclear spin with angular momentum $\hbar I_z$ -s given by

$$\mu_I = \gamma \hbar I_z$$

When a static magnetic field is applied along the z axis, the Hamiltonian has the form of the Zeeman energy, given by

$$H = -\boldsymbol{\mu}_I \cdot \mathbf{B} = -\gamma \hbar \mathbf{I} \cdot \mathbf{B}$$

We consider the equation of motion for the angular momentum

$$\hbar \frac{d\mathbf{L}}{dt} = \boldsymbol{\tau} = \boldsymbol{\mu} \times \mathbf{B} = \gamma \hbar \mathbf{I} \times \mathbf{B}$$

$$\frac{d\mathbf{I}}{dt} = \gamma (\mathbf{I} \times \mathbf{B})$$

When the magnetic field is applied along the $+z$ axis,

$$\dot{I}_z = 0, \quad \dot{I}_x = \gamma BI_y, \quad \dot{I}_y = -\gamma BI_x$$

leading to the equation

$$\frac{d}{dt}(I_x + iI_y) = \gamma BI_y - i\gamma BI_x = -i\gamma B(I_x + iI_y)$$

or

$$I_x + iI_y = I_0 \exp(-i\gamma B t) = I_0 e^{i\omega_0 t}$$

where

$$\omega_0 = -\gamma B$$

(clockwise for $\gamma > 0$ and counter clockwise for $\gamma < 0$).

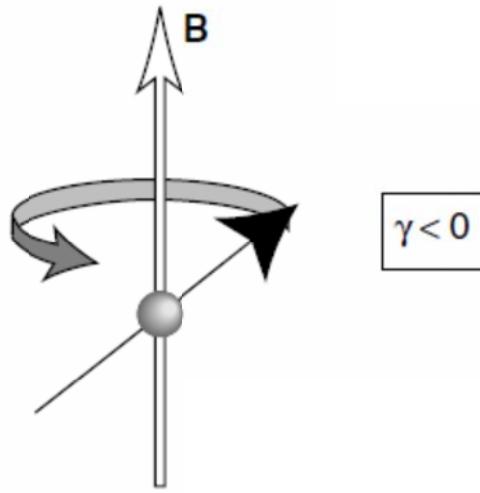


Fig. Precession of nuclear spin. $\omega^0 = -\gamma B > 0$ for $\gamma < 0$. (Counter-clockwise direction). The r.f. field $\mathbf{B}_{res}^{RF}(t)$ with $\omega_{ref} > 0$.

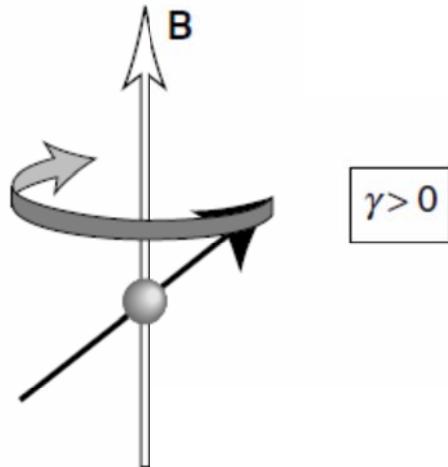


Fig. Precession of nuclear spin. $\omega^0 = -\gamma B < 0$ for $\gamma > 0$. (Clockwise direction). The r.f. foeld $\mathbf{B}_{res}^{RF}(t)$ with $\omega_{ref} < 0$

(b) Spin precession using quantum mechanics

The time evolution operator is defined by $\hat{T} = \exp(-\frac{i}{\hbar} \hat{H} t)$. When a static magnetic field is applied along the z axis (in the absence of the r.f. field), the Hamiltonian is given by

$$\hat{H} = -\gamma \hbar \hat{I}_z B = \hbar \omega_0 \hat{I}_z$$

where $\omega_0 = -\gamma B$ and $\hat{I}_z = \frac{1}{2} \hat{\sigma}_z$. The state vector at the time t_2 is related to the state vector at the time t_1 through the time evolution operator as

$$\begin{aligned} |\psi(t_2)\rangle &= \exp(-\frac{i}{\hbar} \hat{H} \tau) |\psi(t_1)\rangle \\ &= \exp(-\frac{i}{\hbar} \hbar \omega_0 \hat{I}_z \tau) |\psi(t_1)\rangle \\ &= \exp(-i \omega_0 \tau \hat{I}_z) |\psi(t_1)\rangle \\ &= \exp(-i \frac{\omega_0 \tau}{2} \hat{\sigma}_z) |\psi(t_1)\rangle \end{aligned}$$

Here we define the rotation operator as

$$\hat{R}_z(\phi) = \exp(-\frac{i}{2} \phi \hat{\sigma}_z) = \begin{pmatrix} \exp(-\frac{i\phi}{2}) & 0 \\ 0 & \exp(\frac{i\phi}{2}) \end{pmatrix}$$

This means that spin rotates around the z axis through the angle $\phi = \omega_0 \tau$.

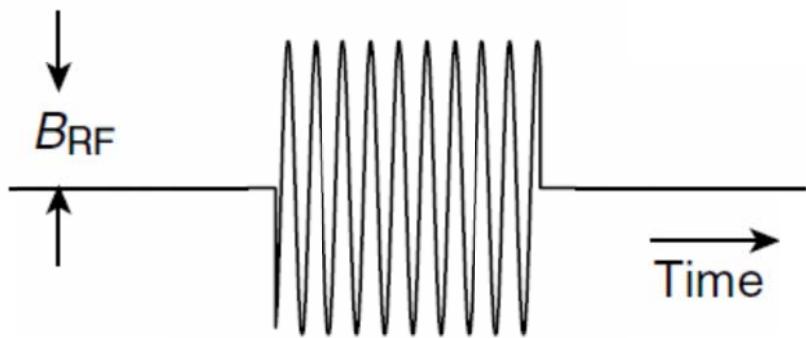
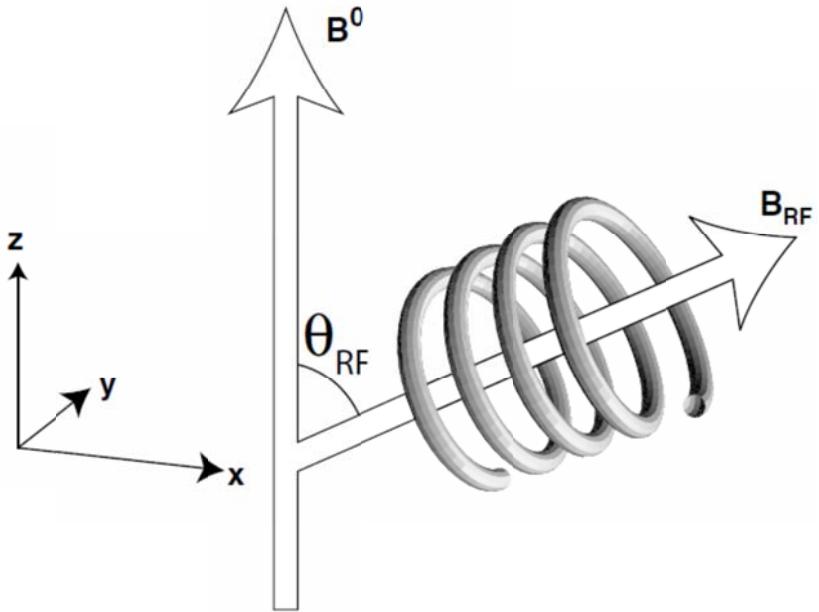
We note that

$$\hat{R}_z(\frac{\pi}{2}) |+x\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} e^{-i\pi/4} & 0 \\ 0 & e^{i\pi/4} \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \frac{1}{\sqrt{2}} e^{-i\pi/4} \begin{pmatrix} 1 \\ i \end{pmatrix} = e^{-i\pi/4} |+y\rangle$$

$$\hat{R}_z(\pi) |+x\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} e^{-i\pi/2} & 0 \\ 0 & e^{i\pi/2} \end{pmatrix} \begin{pmatrix} 1 \\ 1 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} e^{-i\pi/2} \\ e^{i\pi/2} \end{pmatrix} = \frac{1}{\sqrt{2}} e^{-i\pi/2} \begin{pmatrix} 1 \\ -1 \end{pmatrix} = e^{-i\pi/2} |-x\rangle$$

3. r.f. magnetic field

The r.f. coil generates a field \mathbf{B}_{RF} along the tilted axis in Fig. During an r.f. pulse on a single spectrometer channel, the magnitude of this field oscillates at the spectrometer reference angular frequency ω_{ref} . Between pulses, the r.f. field is equal to zero. If the pulse is perfectly rectangular, then the r.f. field has the form:



The r.f. field is given by

$$\begin{aligned}\mathbf{B}_{RF}(t) &= B_{RF}(\cos \theta_{RF} \mathbf{e}_z + \sin \theta_{RF} \mathbf{e}_x) \cos(\omega_{ref} t + \phi_p) \\ &= \mathbf{B}_{res}^{RF}(t) + \mathbf{B}_{non-res}^{RF}(t) + \mathbf{B}_{long}^{RF}(t)\end{aligned}$$

during an r.f. pulse. The r.f. field consists of a longitudinal component proportional to $\cos\theta_{RF}$ plus a transverse component proportional to $\sin\theta_{RF}$. It turns out to be useful to imagine that the transverse oscillating field is actually a sum of two rating components. Both components rotae in the xy -plane, at the same frequency, but in opposite directions. Note that

$$\mathbf{B}_{res}^{RF}(t) = \frac{1}{2}B_{RF} \sin\theta_{RF} [\mathbf{e}_x \cos(\omega_{ref}t + \phi_p) + \mathbf{e}_y \sin(\omega_{ref}t + \phi_p)]$$

$$\mathbf{B}_{non-res}^{RF}(t) = \frac{1}{2}B_{RF} \sin\theta_{RF} [\mathbf{e}_x \cos(\omega_{ref}t + \phi_p) - \mathbf{e}_y \sin(\omega_{ref}t + \phi_p)]$$

$$\mathbf{B}_{long}^{RF}(t) = B_{RF} \cos\theta_{RF} \mathbf{e}_z \cos(\omega_{ref}t + \phi_p)$$

where

$$\omega_0 = -\gamma B$$

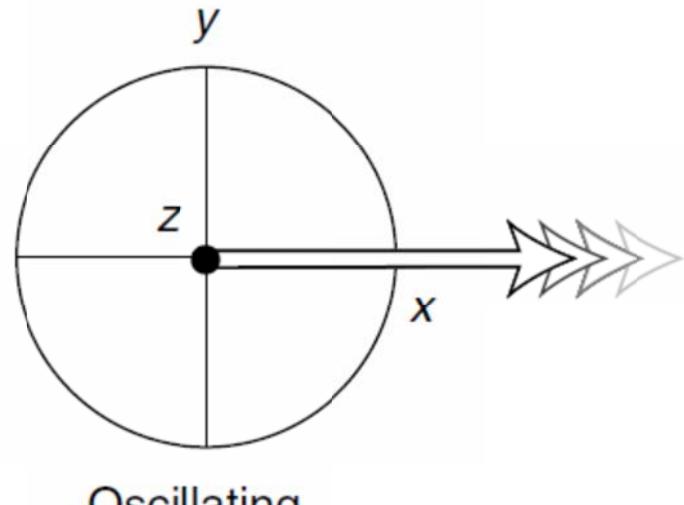
For positive γ , the angular frequency ω_{ref} is negative (clockwise), and for negative γ , the angular frequency ω_{ref} is positive (counter-clock wise). The transverse part of the spin Hamiltonian is approximated as

$$\begin{aligned}\hat{H}_L &= -\gamma\hbar\hat{\mathbf{I}} \cdot \mathbf{B}_{res}^{RF}(t) \\ &= -\frac{1}{2}\gamma\hbar B_{RF} \sin\theta_{RF} [\hat{I}_x \cos(\omega_{ref}t + \phi_p) + \hat{I}_y \sin(\omega_{ref}t + \phi_p)]\end{aligned}$$

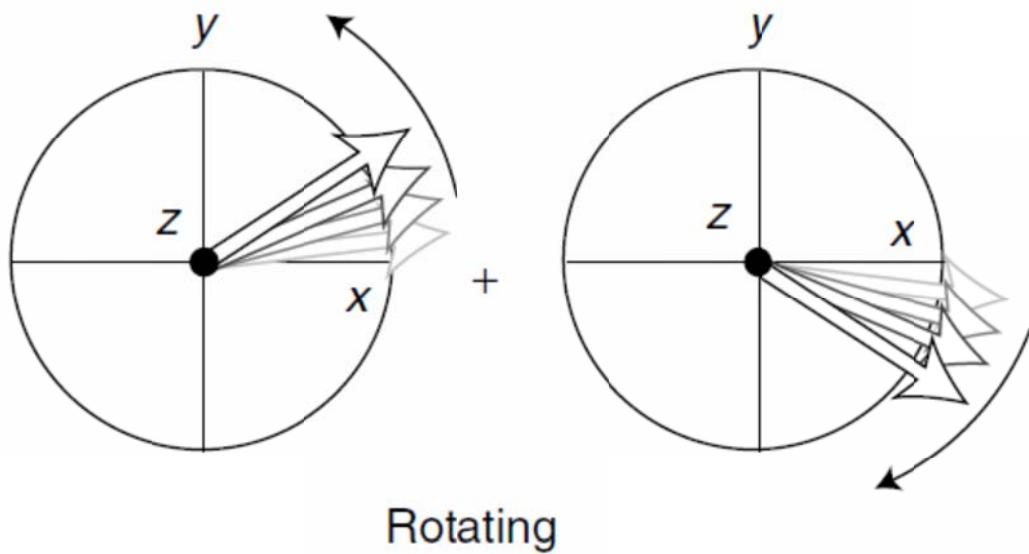
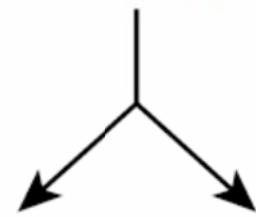
Note that

$$\omega_{nut} = \left| \frac{1}{2}\gamma\hbar B_{RF} \sin\theta_{RF} \right|$$

is the nutation angular frequency.



Oscillating



4. State vector in the rotation frame and Laboratory frame

$$|+x'\rangle = \hat{R}_z(\Phi) |+x\rangle$$

$$|+x\rangle = \hat{R}_z(-\Phi)|+x'\rangle$$

Here we use the notations

$$|+x\rangle = |+x'\rangle_R \quad \text{Rotating frame}$$

$$|+x'\rangle = |+x\rangle_L \quad \text{Laboratory frame}$$

Then we have

$$|+x'\rangle_R = \hat{R}_z(-\Phi)|+x\rangle_L$$

This relationship may be generalized. Any spin state, viewed from the rotating frame, is related to the spin state, viewed from the fixed frame through

$$|\psi\rangle_R = \hat{R}_z(-\Phi)|\psi\rangle, \quad |\psi\rangle = \hat{R}_z(\Phi)|\psi\rangle_R$$

Now we consider the Schrödinger equation in the laboratory frame,

$$i\hbar \frac{\partial}{\partial t}|\psi\rangle = \hat{H}|\psi\rangle$$

$$\begin{aligned} i\hbar \frac{\partial}{\partial t}|\psi\rangle_R &= i\hbar \frac{\partial}{\partial t}\hat{R}_z(-\Phi)|\psi\rangle \\ &= i\hbar \left[\frac{\partial}{\partial t}\hat{R}_z(-\Phi) \right] |\psi\rangle + \hat{R}_z(-\Phi)i\hbar \frac{\partial}{\partial t}|\psi\rangle \end{aligned}$$

Here we note that

$$\hat{R}_z(-\Phi) = \exp\left(\frac{i}{\hbar}\hat{J}_z\Phi\right) = \exp(i\Phi\hat{I}_z)$$

where

$$\hat{J}_z = \hbar\hat{I}_z = \frac{\hbar}{2}\hat{\sigma}_z, \quad \hat{I}_z = \frac{1}{2}\hat{\sigma}_z$$

The derivative of $\hat{R}_z(-\Phi)$ with respect to t ;

$$\begin{aligned}
\frac{\partial}{\partial t} \hat{R}_z(-\Phi) &= \frac{\partial}{\partial t} \exp(i\Phi \hat{I}_z) \\
&= i\hat{I}_z \frac{d\Phi}{dt} \exp(i\Phi \hat{I}_z) \\
&= i\omega_{ref} \hat{I}_z \hat{R}_z(-\Phi)
\end{aligned}$$

where

$$\frac{d\Phi}{dt} = \omega_{ref}, \quad \Phi = \omega_{ref}t + \phi_{ref}$$

Thus we have

$$\begin{aligned}
i\hbar \frac{\partial}{\partial t} |\psi\rangle_R &= -\hbar \omega_{ref} \hat{I}_z \hat{R}_z(-\Phi) |\psi\rangle + \hat{R}_z(-\Phi) i\hbar \frac{\partial}{\partial t} |\psi\rangle \\
&= -\hbar \omega_{ref} \hat{I}_z \hat{R}_z(-\Phi) |\psi\rangle + \hat{R}_z(-\Phi) \hat{H}_L |\psi\rangle \\
&= -\hbar \omega_{ref} \hat{I}_z |\psi\rangle_R + \hat{R}_z(-\Phi) \hat{H}_L \hat{R}_z(\Phi) |\psi\rangle_R \\
&= [-\hbar \omega_{ref} \hat{I}_z + \hat{R}_z(-\Phi) \hat{H}_L \hat{R}_z(\Phi)] |\psi\rangle_R \\
&= \hat{H}_R |\psi\rangle_R
\end{aligned}$$

The Schrödinger equation in the rotating frame is given by

$$i\hbar \frac{\partial}{\partial t} |\psi\rangle_R = \hat{H}_R |\psi\rangle_R$$

with the Hamiltonian in the rotating frame,

$$\hat{H}_R = -\hbar \omega_{ref} \hat{I}_z + \hat{R}_z(-\Phi) \hat{H}_L \hat{R}_z(\Phi)$$

5. Precession in the rotating frame

The spin Hamiltonian in the static field is

$$\hat{H}_L = \hbar \omega_0 \hat{I}_z.$$

So the rotating-frame Hamiltonian is

$$\begin{aligned}
\hat{H}_R^0 &= -\hbar\omega_{ref}\hat{I}_z + \hat{R}_z(-\Phi)\hbar\omega_0\hat{I}_z\hat{R}_z(\Phi) \\
&= \hbar(\omega_0 - \omega_{ref})\hat{I}_z \\
&= \hbar\Omega_0\hat{I}_z
\end{aligned}$$

where

$$\Omega_0 = (\omega_0 - \omega_{ref})$$

Note that

$$\hat{R}_z(-\Phi)\hat{I}_z\hat{R}_z(\Phi) = \hat{I}_z\hat{R}_z(-\Phi)\hat{R}_z(\Phi) = \hat{I}_z$$

6. Rotating-frame Hamiltonian

In the presence of a static field along the z axis, the Hamiltonian is given by

$$\hat{H}_0 = \hbar\omega^0\hat{I}_z = \frac{\hbar\omega^0}{2}\hat{\sigma}_z$$

with

$$\hat{I}_z = \frac{1}{2}\hat{\sigma}_z$$

$$\omega_0 = -\gamma B$$

The Hamiltonian due to the r.f. field in the x - y plane is

$$\begin{aligned}
\hat{H}_{RF} &= -\gamma\hbar\hat{\mathbf{I}} \cdot \mathbf{B}_{res}^{RF}(t) \\
&= -\frac{1}{2}\gamma\hbar B_{RF} \sin\theta_{RF} [\hat{I}_x \cos(\omega_{rf}t + \phi_p) + \hat{I}_y \sin(\omega_{rf}t + \phi_p)]
\end{aligned}$$

where

$$\Phi_p = \omega_{rf}t + \phi_p,$$

Then the resulting Hamiltonian is

$$\begin{aligned}\hat{H}_L &= \hat{H}_0 + \hat{H}_{RF} \\ &= \hbar\omega_0 \hat{I}_z - \frac{1}{2} \gamma \hbar B_{RF} \sin \theta_{RF} [\hat{I}_x \cos(\Phi_p) + \hat{I}_y \sin(\Phi_p)]\end{aligned}$$

The Hamiltonian in the rotating frame is

$$\begin{aligned}\hat{H}_R &= -\hbar\omega_{ref} \hat{I}_z + \hat{R}_z(-\Phi) \hat{H}_L \hat{R}_z(\Phi) \\ &= -\hbar\omega_{ref} \hat{I}_z + \hbar\omega_0 \hat{R}_z(-\Phi) \hat{I}_z \hat{R}_z(\Phi) - \frac{1}{2} \gamma \hbar B_{RF} \sin \theta_{RF} \hat{R}_z(-\Phi) [\hat{I}_x \cos \Phi_p + \hat{I}_y \sin \Phi_p] \hat{R}_z(\Phi) \\ &= \hbar(\omega_0 - \omega_{ref}) \hat{I}_z - \frac{1}{2} \gamma \hbar B_{RF} \sin \theta_{RF} \hat{R}_z(-\Phi + \Phi_p) \hat{R}_z(-\Phi_p) [\hat{I}_x \cos \Phi_p + \hat{I}_y \sin \Phi_p] \hat{R}_z(\Phi_p) \hat{R}_z(\Phi - \Phi_p) \\ &= \hbar(\omega_0 - \omega_{ref}) \hat{I}_z - \frac{1}{2} \gamma \hbar B_{RF} \sin \theta_{RF} \hat{R}_z(-\Phi + \Phi_p) \hat{I}_x \hat{R}_z(\Phi - \Phi_p)\end{aligned}$$

where

$$\hat{R}_z(-\Phi_p) [\hat{I}_x \cos \Phi_p + \hat{I}_y \sin \Phi_p] \hat{R}_z(\Phi_p) = \hat{I}_x$$

$$\hat{R}_z(-\Phi + \Phi_p) \hat{R}_z(-\Phi_p) = \hat{R}_z(-\Phi)$$

$$\hat{R}_z(\Phi_p) \hat{R}_z(\Phi - \Phi_p) = \hat{R}_z(\Phi)$$

((Formula))

$$\hat{R}_z(\Phi_p) \hat{I}_x \hat{R}_z(-\Phi_p) = \cos(\Phi_p) \hat{I}_x + \sin(\Phi_p) \hat{I}_y$$

$$\hat{R}_z(\Phi_p) \hat{I}_y \hat{R}_z(-\Phi_p) = -\sin(\Phi_p) \hat{I}_x + \cos(\Phi_p) \hat{I}_y$$

or

$$\hat{I}_x = \hat{R}_z(-\Phi_p) [\cos(\Phi_p) \hat{I}_x + \sin(\Phi_p) \hat{I}_y] \hat{R}_z(\Phi_p)$$

$$\hat{I}_y = \hat{R}_z(-\Phi_p) [-\sin(\Phi_p) \hat{I}_x + \cos(\Phi_p) \hat{I}_y] \hat{R}_z(\Phi_p)$$

Thus we have

$$\hat{H}_R = \hbar\Omega_0\hat{I}_z - \frac{1}{2}\gamma\hbar B_{RF} \sin\theta_{RF} \hat{R}_z(-\phi_{ref} + \phi_p) \hat{I}_x \hat{R}_z(\phi_{ref} - \phi_p)$$

Note that

$$\Omega_0 = \omega_0 - \omega_{ref}$$

$$\Phi = \omega_{ref}t + \phi_{ref}, \quad \Phi_p = \omega_{rf}t + \phi_p$$

Ω_0 is the resonance offset. Note that the time dependence has vanished from this expression. This is the point of the rotating frame. It transforms a time-dependent quantum-mechanical problem into a time-independent one.

((Note))

For $\gamma < 0$, $\phi_{ref} = 0$ (definition)

$$\begin{aligned} \hat{H}_R &= \hbar\Omega^0\hat{I}_z - \frac{1}{2}\gamma\hbar B_{RF} \sin\theta_{RF} \hat{R}_z(\phi_p) \hat{I}_x \hat{R}_z(-\phi_p) \\ &= \hbar\Omega^0\hat{I}_z - \frac{1}{2}\gamma\hbar B_{RF} \sin\theta_{RF} (\cos\phi_p \hat{I}_x + \sin\phi_p \hat{I}_y) \end{aligned}$$

For $\gamma < 0$, $\phi_{ref} = \pi$ (definition)

$$\begin{aligned} \hat{H}_R &= \hbar\Omega^0\hat{I}_z - \frac{1}{2}\gamma\hbar B_{RF} \sin\theta_{RF} \hat{R}_z(-\pi + \phi_p) \hat{I}_x \hat{R}_z(\pi - \phi_p) \\ &= \hbar\Omega^0\hat{I}_z + \frac{1}{2}\gamma\hbar B_{RF} \sin\theta_{RF} (\cos\phi_p \hat{I}_x + \sin\phi_p \hat{I}_y) \end{aligned}$$

where

$$\hat{R}_z(\phi_p) \hat{I}_x \hat{R}_z(-\phi_p) = \cos\phi_p \hat{I}_x + \sin\phi_p \hat{I}_y$$

and

$$\begin{aligned}\hat{R}_z(-\pi + \phi_p)\hat{I}_x\hat{R}_z(\pi - \phi_p) &= \cos(\phi_p - \pi)\hat{I}_x + \sin(\phi_p - \pi)\hat{I}_y \\ &= -(\cos\phi_p\hat{I}_x + \sin\phi_p\hat{I}_y)\end{aligned}$$

Combining these two equations, we get the final result

$$\hat{H}_R = \hbar\Omega^0\hat{I}_z + \hbar\omega_{nut}(\cos\phi_p\hat{I}_x + \sin\phi_p\hat{I}_y)$$

where

$$\omega_{nut} = \left| \frac{1}{2} \gamma \hbar B_{RF} \sin \theta_{RF} \right|$$

For $\gamma > 0$

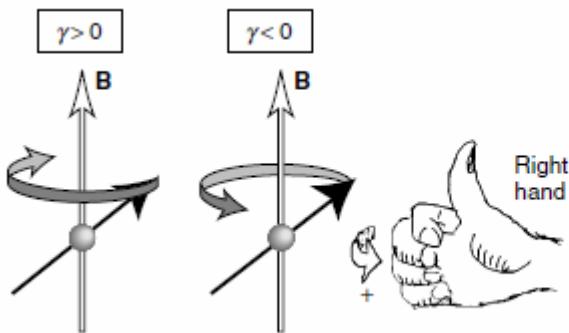


Figure 2.13

Using one's right hand to determine the sense of precession.

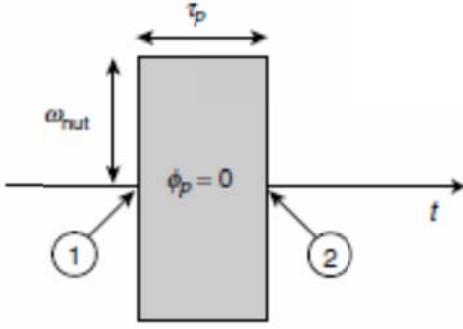
((Note))

$$\phi_{ref} = \pi \quad \text{for } \gamma > 0$$

$$\phi_{ref} = 0 \quad \text{for } \gamma < 0$$

7. x-pulse

We Consider a strong pulse of frequency ω_{ref} , duration τ_p and phase $\phi_p = 0$ (an ‘x-pulse’, in the usual NMR jargon). The amplitude of the pulse is specified through the nutation frequency ω_{nut} .



The Hamiltonian in the rotation-frame is

$$\hat{H}_R = \hbar\Omega_0 \hat{I}_z + \hbar\omega_{nut}(\cos\phi_p \hat{I}_x + \sin\phi_p \hat{I}_y)$$

For $\phi_p = 0$ and $\Omega_0 = \omega_0 - \omega_{ref} = 0$ (resonance), the rotating-frame Hamiltonian during the time $\tau_p = t_2 - t_1$,

$$\hat{H}_R = \hbar\omega_{nut} \hat{I}_x$$

$$|\psi(t_2)\rangle_R = \hat{R}_x(\beta_p) |\psi(t_1)\rangle_R$$

with

$$\tau_p = t_2 - t_1.$$

and

$$\hat{R}_x(\beta_p) = \exp\left(-\frac{i}{\hbar}\hbar\omega_{nut}\tau_p \hat{I}_x\right) = \exp(-i\omega_{nut}\tau_p \hat{I}_x) = \exp(-i\beta_p \hat{I}_x)$$

or

$$\hat{R}_x(\beta_p) = \begin{pmatrix} \cos\frac{\beta_p}{2} & -i\sin\frac{\beta_p}{2} \\ -i\sin\frac{\beta_p}{2} & \cos\frac{\beta_p}{2} \end{pmatrix}$$

where

$$\beta_p = \omega_{nut} \tau_p$$

Now we start with

$$|\psi(t_1)\rangle_R = \hat{R}_z[\Phi(t_1)]|\psi(t_1)\rangle$$

$$|\psi(t_2)\rangle_R = \hat{R}_z[\Phi(t_2)]|\psi(t_2)\rangle$$

$$\tau_p = t_2 - t_1,$$

where

$$\Phi = \omega_{ref}t,$$

Thus we get

$$|\psi(t_2)\rangle_R = \hat{R}_x(\beta_p)|\psi(t_1)\rangle_R$$

or

$$\hat{R}_z[-\Phi(t_2)]|\psi(t_2)\rangle = \hat{R}_x(\beta_p)\hat{R}_z[\Phi(t_1)]|\psi(t_1)\rangle$$

or

$$|\psi(t_2)\rangle = \hat{R}_z[\Phi(t_2)]\hat{R}_x(\beta_p)\hat{R}_z[-\Phi(t_1)]|\psi(t_1)\rangle$$

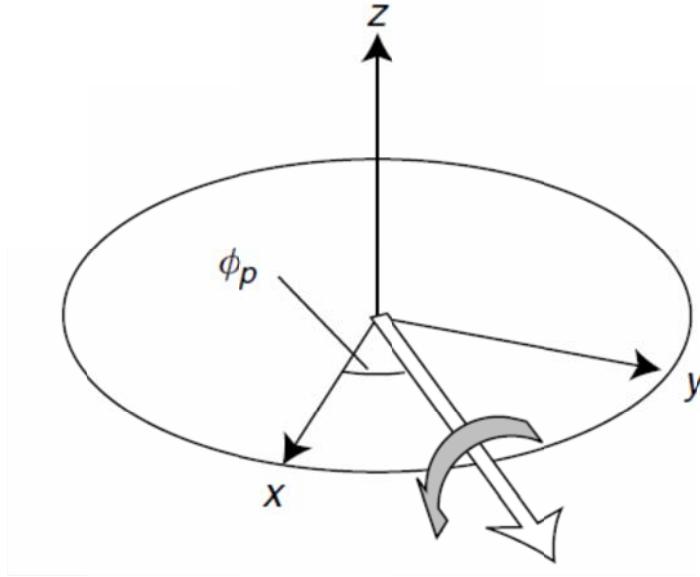
Note that

$$\hat{R}_z(\Phi(t)) = \exp(-i\Phi\hat{I}_z) = \exp(-i\omega_{ref}t\hat{I}_z)$$

Using the **Mathematica**, we get the expression

$$\hat{R}_z[\Phi(t_2)]\hat{R}_x(\beta_p)\hat{R}_z[-\Phi(t_1)] = \begin{pmatrix} e^{-\frac{1}{2}i\tau_p\omega_{ref}} \cos \frac{\beta_p}{2} & -ie^{-\frac{1}{2}i(2t_1+\tau_p)\omega_{ref}} \sin \frac{\beta_p}{2} \\ -ie^{\frac{1}{2}i(2t_1+\tau_p)\omega_{ref}} \sin \frac{\beta_p}{2} & e^{\frac{1}{2}i\tau_p\omega_{ref}} \cos \frac{\beta_p}{2} \end{pmatrix}$$

8. Pulse of general phase



In general, the Hamiltonian in the rotating frame is

$$\hat{H}_R = \hbar\Omega_0\hat{I}_z + \hbar\omega_{nut}(\cos\phi_p\hat{I}_x + \sin\phi_p\hat{I}_y)$$

with $\phi_p \neq 0$. For $\Omega_0 = \omega_0 - \omega_{ref} = 0$ (resonance condition), the rotating-frame Hamiltonian during the time $\tau_p = t_2 - t_1$, is given by

$$\hat{H}_R = \hbar\omega_{nut}(\cos\phi_p\hat{I}_x + \sin\phi_p\hat{I}_y)$$

$$|\psi(t_2)\rangle_R = \hat{R}_{\phi_p}(\beta_p)|\psi(t_1)\rangle_R$$

with

$$\tau_p = t_2 - t_1.$$

and

$$\begin{aligned}\hat{R}_{\phi_p}(\beta_p) &= \exp[-i\beta_p(\cos\phi_p\hat{I}_x + \sin\phi_p\hat{I}_y)] \\ &= \begin{pmatrix} \cos\frac{\beta_p}{2} & -i\sin\frac{\beta_p}{2}e^{-i\phi_p} \\ -i\sin\frac{\beta_p}{2}e^{i\phi_p} & \cos\frac{\beta_p}{2} \end{pmatrix}\end{aligned}$$

where

$$\beta_p = \omega_{nut}\tau_p$$

Now we start with

$$|\psi(t_1)\rangle_R = \hat{R}_z[\Phi(t_1)]|\psi(t_1)\rangle$$

$$|\psi(t_2)\rangle_R = \hat{R}_z[\Phi(t_2)]|\psi(t_2)\rangle$$

$$\Phi(t) = \omega_{ref}t, \quad \tau_p = t_2 - t_1,$$

$$|\psi(\tau_2)\rangle_R = \hat{R}_{\phi_p}(\beta_p)|\psi(t_1)\rangle_R$$

$$\hat{R}_z[-\Phi(t_2)]|\psi(t_2)\rangle = \hat{R}_{\phi_p}(\beta_p)\hat{R}_z[\Phi(t_1)]|\psi(t_1)\rangle$$

or

$$|\psi(t_2)\rangle = \hat{R}_z[\Phi(t_2)]\hat{R}_{\phi_p}(\beta_p)\hat{R}_z[-\Phi(t_1)]|\psi(t_1)\rangle$$

Note that

$$\hat{R}_z(\Phi(t)) = \exp(-i\Phi(t)\hat{I}_z) = \exp(-i\omega_{ref}t\hat{I}_z)$$

Thus we have

$$\hat{R}_z[\Phi(t_2)]\hat{R}_{\phi_p}(\beta_p)\hat{R}_z[-\Phi(t_1)] \\ = \begin{pmatrix} e^{-\frac{1}{2}i(\phi_p + \tau_p \omega_{ref})} [\cos(\beta_p) \cos \frac{\phi_p}{2} + i \sin \frac{\phi_p}{2}] & -ie^{-\frac{1}{2}i(\phi_p + \tau_p \omega_{ref})} \cos \frac{\phi_p}{2} \sin(\beta_p) \\ -ie^{\frac{1}{2}i(\phi_p + \tau_p \omega_{ref})} \cos \frac{\phi_p}{2} \sin(\beta_p) & e^{\frac{1}{2}i(\phi_p + \tau_p \omega_{ref})} [\cos(\beta_p) \cos \frac{\phi_p}{2} - i \sin \frac{\phi_p}{2}] \end{pmatrix}$$

9. Off-Resonance effect

For $\Omega_0 = \omega_0 - \omega_{ref} \neq 0$ (resonance condition), the rotating-frame Hamiltonian during the time $\tau_p = t_2 - t_1$, is given by

$$\hat{H}_R = \hbar \Omega_0 \hat{I}_z + \hbar \omega_{nut} (\cos \phi_p \hat{I}_x + \sin \phi_p \hat{I}_y)$$

with $\phi_p \neq 0$

$$|\psi(t_2)\rangle_R = \hat{R}_{\phi_p}(\beta_p) |\psi(t_1)\rangle_R$$

with

$$\tau_p = t_2 - t_1.$$

and

$$\hat{R}_{off}(\beta_p) = \exp[-i\beta_p(\cos \phi_p \hat{I}_x + \sin \phi_p \hat{I}_y) - i\Omega_0 \tau_p \hat{I}_z] \\ = \begin{pmatrix} \sin(\frac{\tau_p \omega_{eff}}{2}) & -i\beta_p e^{-i\phi_p} \sin(\frac{\tau_p \omega_{eff}}{2}) \\ \cos(\frac{\tau_p \omega_{eff}}{2}) - i\Omega_0 \frac{\sin(\frac{\tau_p \omega_{eff}}{2})}{\omega_{eff}} & \frac{-i\beta_p e^{-i\phi_p} \sin(\frac{\tau_p \omega_{eff}}{2})}{\tau_p \omega_{eff}} \\ -i\beta_p e^{i\phi_p} \sin(\frac{\tau_p \omega_{eff}}{2}) & \cos(\frac{\tau_p \omega_{eff}}{2}) + i\Omega_0 \frac{\sin(\frac{\tau_p \omega_{eff}}{2})}{\omega_{eff}} \end{pmatrix}$$

where

$$\omega_{eff} = \sqrt{\omega_{nut}^2 + (\Omega_0)^2}$$

$$\beta_p = \omega_{nut} \tau_p$$

Now we start with

$$|\psi(t_1)\rangle_R = \hat{R}_z[\Phi(t_1)]|\psi(t_1)\rangle$$

$$|\psi(t_2)\rangle_R = \hat{R}_z[\Phi(t_2)]|\psi(t_2)\rangle$$

$$\tau_p = t_2 - t_1$$

$$|\psi(\tau_2)\rangle_R = \hat{R}_{\phi_p}(\beta_p)|\psi(t_1)\rangle_R$$

$$\hat{R}_z[-\Phi(t_2)]|\psi(t_2)\rangle = \hat{R}_{\phi_p}(\beta_p)\hat{R}_z[\Phi(t_1)]|\psi(t_1)\rangle$$

or

$$|\psi(t_2)\rangle = \hat{R}_z[\Phi(t_2)]\hat{R}_{\phi_p}(\beta_p)\hat{R}_z[-\Phi(t_1)]|\psi(t_1)\rangle$$

Note that

$$\hat{R}_z(\Phi) = \exp(-i\Phi\hat{I}_z)$$

where

$$\Phi = \omega_{ref}t$$

$$\begin{aligned} & \hat{R}_z[\Phi(t_2)]\hat{R}_{\phi_p}(\beta_p)\hat{R}_z[-\Phi(t_1)] \\ &= \begin{pmatrix} e^{-\frac{i}{2}\tau_p\omega_{ref}}[-i\Omega_0\sin(\frac{\omega_{eff}\tau_p}{2}) + \omega_{eff}\cos(\frac{\omega_{eff}\tau_p}{2})] & -i\beta_p\sin(\frac{\omega_{eff}\tau_p}{2})e^{-\frac{i}{2}[2\phi_p+(2t_1+\tau_p)\omega_{ref}+\tau_p\omega_{eff}]} \\ \frac{\omega_{eff}}{-i\beta_p\sin(\frac{\omega_{eff}\tau_p}{2})e^{\frac{i}{2}[2\phi_p+(2t_1+\tau_p)\omega_{ref}]}} & \frac{\tau_p\omega_{eff}}{e^{\frac{i}{2}\tau_p\omega_{ref}}[i\Omega_0\sin(\frac{\omega_{eff}\tau_p}{2}) + \omega_{eff}\cos(\frac{\omega_{eff}\tau_p}{2})]} \end{pmatrix} \end{aligned}$$

10. Rabi formula

Suppose that

$$t_1 = 0, \text{ and } t_2 = t, \quad \tau_p = t$$

$$|\psi(0)\rangle = |+z\rangle$$

$$\begin{aligned} |\psi(t)\rangle &= \hat{R}_z[\Phi(t)]\hat{R}_{\phi_p}(\beta_p)\hat{R}_z[-\Phi(0)]|\psi(0)\rangle \\ &= \begin{pmatrix} e^{-\frac{i}{2}\omega_{ref}t}[-i\Omega^0 \sin(\frac{\omega_{eff}t}{2}) + \omega_{eff} \cos(\frac{\omega_{eff}t}{2})] & -i\beta_p \sin(\frac{\omega_{eff}t}{2})e^{-\frac{i}{2}[2\phi_p + (\omega_{ref} + \omega_{eff})t]} \\ \frac{\omega_{eff}}{-i\beta_p \sin(\frac{\omega_{eff}t}{2})e^{\frac{i}{2}[2\phi_p + \omega_{ref}t]}} & \frac{t\omega_{eff}}{e^{\frac{i}{2}\omega_{ref}t}[i\Omega^0 \sin(\frac{\omega_{eff}t}{2}) + \omega_{eff} \cos(\frac{\omega_{eff}t}{2})]} \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} \\ &= \begin{pmatrix} e^{-\frac{i}{2}\omega_{ref}t}[-i\Omega^0 \sin(\frac{\omega_{eff}t}{2}) + \omega_{eff} \cos(\frac{\omega_{eff}t}{2})] \\ \frac{\omega_{eff}}{-i\beta_p \sin(\frac{\omega_{eff}t}{2})e^{\frac{i}{2}[2\phi_p + \omega_{ref}t]}} \end{pmatrix} \end{aligned}$$

with

$$\beta_p = \omega_{nut}t$$

The probability of finding the system in the state $| -z \rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$,

$$\begin{aligned} \langle -z | \psi(\tau_p) \rangle_L &= (0 \ 1) \begin{pmatrix} e^{-\frac{i}{2}\omega_{ref}\tau_p}[-i\Omega^0 \sin(\frac{\omega_{eff}\tau_p}{2}) + \omega_{eff} \cos(\frac{\omega_{eff}\tau_p}{2})] \\ \frac{\omega_{eff}}{-i\beta_p \sin(\frac{\omega_{eff}\tau_p}{2})e^{\frac{i}{2}[2\phi_p + \omega_{ref}\tau_p]}} \end{pmatrix} \\ &= \frac{-i\beta_p \sin(\frac{\omega_{eff}\tau_p}{2})e^{\frac{i}{2}[2\phi_p + \omega_{ref}\tau_p]}}{\tau_p \omega_{eff}} \end{aligned}$$

$$\left| \langle -z | \psi(\tau_p) \rangle_L \right|^2 = \left| \frac{-i\beta_p \sin(\frac{\omega_{eff}\tau_p}{2}) e^{\frac{i}{2}[2\phi_p + \omega_{ref}\tau_p]}}{t\omega_{eff}} \right|^2$$

$$= \frac{\omega_{nut}^2}{\omega_{nut}^2 + (\Omega^0)^2} \sin^2 \left(\frac{\omega_{eff}\tau_p}{2} \right)$$

where

$$\omega_{eff} = \sqrt{\omega_{nut}^2 + (\Omega^0)^2}$$

11. Density operator:

$$R_x(\beta) = \begin{pmatrix} \cos \frac{\beta}{2} & -i \sin \frac{\beta}{2} \\ -i \sin \frac{\beta}{2} & \cos \frac{\beta}{2} \end{pmatrix}$$

$$|+z\rangle = \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad |-z\rangle = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

The density operator is defined by

$$\hat{\rho} = \overline{|\psi\rangle\langle\psi|} = \begin{pmatrix} \rho_{11} & \rho_{12} \\ \rho_{21} & \rho_{22} \end{pmatrix} = \begin{pmatrix} \overline{C_1^* C_1} & \overline{C_1^* C_2} \\ \overline{C_2^* C_1} & \overline{C_2^* C_2} \end{pmatrix}$$

$$\hat{\rho}^+ = \hat{\rho} \quad \rho_{21}^* = \rho_{12}$$

$$Tr[\hat{\rho}] = 1, \quad \rho_{11} + \rho_{22} = 1$$

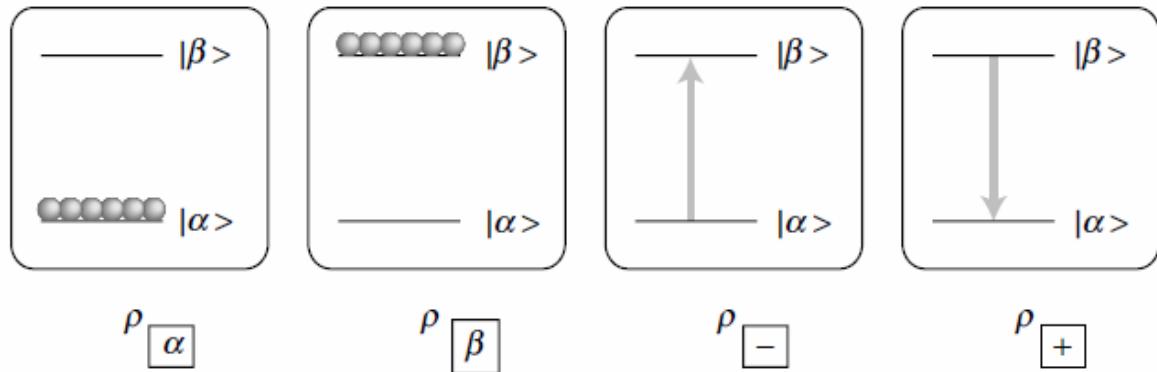
ρ_{11}, ρ_{22} ; Populations of states $|1\rangle$ and $|2\rangle$.

ρ_{11}, ρ_{22} ; Coherences of states $|1\rangle$ and $|2\rangle$.

Note that

$$\rho_{11} = \langle 1 | \hat{\rho} | 1 \rangle, \quad \rho_{12} = \langle 1 | \hat{\rho} | 2 \rangle$$

$$\rho_{21} = \langle 2 | \hat{\rho} | 1 \rangle, \quad \rho_{22} = \langle 2 | \hat{\rho} | 2 \rangle$$



$$\begin{aligned}\langle I_z \rangle &= \text{Tr}[\hat{I}_z \hat{\rho}] \\ &= \frac{1}{2} \text{Tr} \left[\begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \begin{pmatrix} \rho_{11} & \rho_{12} \\ \rho_{21} & \rho_{22} \end{pmatrix} \right] \\ &= \frac{1}{2} \text{Tr} \begin{pmatrix} \rho_{11} & \rho_{12} \\ -\rho_{21} & -\rho_{22} \end{pmatrix} \\ &= \frac{1}{2} (\rho_{11} - \rho_{22})\end{aligned}$$

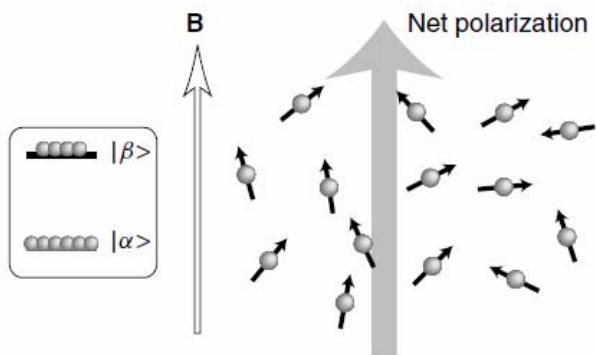


Figure 11.3
Net spin polarization along the field.

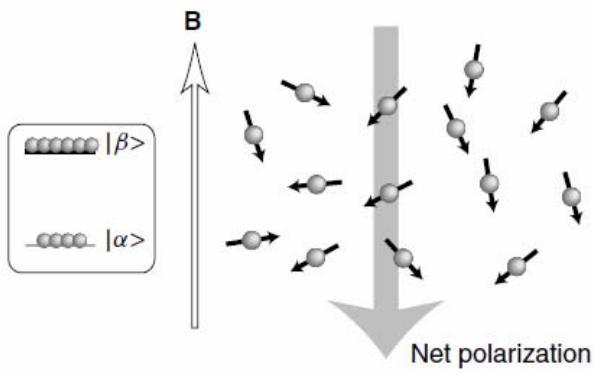


Figure 11.4
Net spin polarization
against the field.

$$\begin{aligned}
 \langle I_x \rangle &= \text{Tr}[\hat{I}_x \hat{\rho}] \\
 &= \frac{1}{2} \text{Tr} \left[\begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \begin{pmatrix} \rho_{11} & \rho_{12} \\ \rho_{21} & \rho_{22} \end{pmatrix} \right] \\
 &= \frac{1}{2} \text{Tr} \begin{pmatrix} \rho_{21} & \rho_{22} \\ \rho_{11} & \rho_{12} \end{pmatrix} \\
 &= \frac{1}{2} (\rho_{21} + \rho_{12}) \\
 &= |\rho_{21}| \cos \phi
 \end{aligned}$$

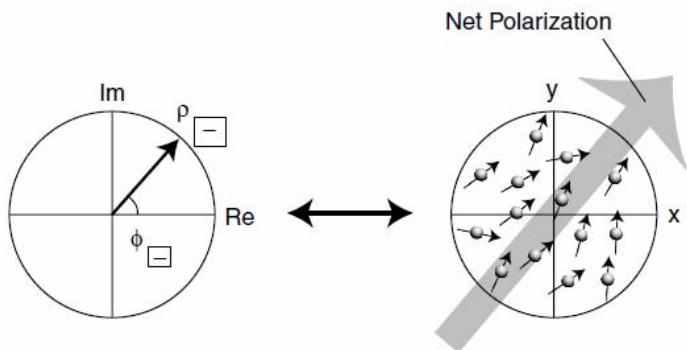


Figure 11.7
Phase of the
(-1)-quantum
coherence and the
direction of the
transverse polarization.

$$\begin{aligned}
\langle I_y \rangle &= Tr[\hat{I}_y \hat{\rho}] \\
&= \frac{1}{2} Tr \left[\begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix} \begin{pmatrix} \rho_{11} & \rho_{12} \\ \rho_{21} & \rho_{22} \end{pmatrix} \right] \\
&= \frac{1}{2} Tr \begin{pmatrix} -i\rho_{21} & -i\rho_{22} \\ i\rho_{11} & i\rho_{12} \end{pmatrix} \\
&= \frac{1}{2} (-i\rho_{21} + i\rho_{12}) \\
&= |\rho_{21}| \sin \phi
\end{aligned}$$

where

$$\rho_{21} = |\rho_{21}| e^{i\phi}$$

12. The density operator in thermal equilibrium

$$\begin{aligned}
\hat{\rho}_{eq} &= \frac{1}{Z} \exp(-\beta \hat{H}) \\
&= \begin{pmatrix} \rho_{11} & 0 \\ 0 & \rho_{22} \end{pmatrix} \\
&= \frac{1}{\exp(\frac{\beta \hbar \omega_0}{2}) + \exp(-\frac{\beta \hbar \omega_0}{2})} \begin{pmatrix} \exp(-\frac{\beta \hbar \omega_0}{2}) & 0 \\ 0 & \exp(\frac{\beta \hbar \omega_0}{2}) \end{pmatrix}
\end{aligned}$$

where

$$\omega_0 = -\gamma B_0$$

$$\hat{H} = -\gamma \hbar \hat{I}_z B_0 = \hbar \omega_0 \hat{I}_z = \frac{\hbar \omega_0}{2} \hat{\sigma}_z$$

with

$$\hat{I}_z = \frac{1}{2} \hat{\sigma}_z$$

$\gamma \hbar \hat{I}_z$ is the magnetic moment of nuclear spin.

$$\hat{H} = \hbar\omega_0 \hat{I}_z = \frac{\hbar\omega_0}{2} \hat{\sigma}_z$$

with

$$\hat{I}_z = \frac{1}{2} \hat{\sigma}_z$$

From the condition that $\text{Tr}[\hat{\rho}] = 1$

$$\rho_{11} + \rho_{22} = 1$$

((Approximation))

$$\begin{aligned}\hat{\rho}_{eq} &= \frac{1}{Z} \exp(-\beta \hat{H}) \\ &\approx \frac{1}{2} \begin{pmatrix} 1 - \frac{\beta \hbar \omega_0}{2} & 0 \\ 0 & 1 + \frac{\beta \hbar \omega_0}{2} \end{pmatrix} \\ &= \frac{1}{2} \hat{1} - \frac{\beta \hbar \omega_0}{4} \hat{\sigma}_z\end{aligned}$$

Here we note that

$$-\beta \hbar \omega_0 = -\beta \hbar (-\gamma B) = \beta \hbar \gamma B$$

Thus we have

$$\hat{\rho}_{eq} = \frac{1}{2} \hat{1} + \frac{\beta \hbar \gamma B}{4} \hat{\sigma}_z = \frac{1}{2} \hat{1} + \frac{\beta \hbar \gamma B}{2} \hat{I}_z = \frac{1}{2} \hat{1} + \frac{1}{2} \tilde{B} \hat{I}_z$$

where

$$\tilde{B} = \beta \hbar \gamma B.$$

13. The density operator in the rotating frame

The rotating frame density operator is defined by

$$\hat{\rho}_R = \overline{|\psi_R\rangle\langle\psi_R|}$$

Using the relations

$$|\psi\rangle_R = \hat{R}_z(-\Phi)|\psi\rangle_L, \quad {}_R\langle\psi| = {}_L\langle\psi|\hat{R}_z(\Phi)$$

The density operator in the rotating frame is related to that in the laboratory frame as

$$\begin{aligned}\hat{\rho}_R &= \overline{\hat{R}_z(-\Phi)|\psi\rangle\langle\psi|\hat{R}_z(\Phi)} \\ &= \hat{R}_z(-\Phi)\overline{|\psi\rangle\langle\psi|}\hat{R}_z(\Phi) \\ &= \hat{R}_z(-\Phi)\hat{\rho}\hat{R}_z(\Phi)\end{aligned}$$

or

$$\hat{\rho} = \hat{R}_z(\Phi)\hat{\rho}_R\hat{R}_z(-\Phi)$$

We have

$$Tr[\hat{\rho}_R] = Tr[\hat{R}_z(-\Phi)\hat{\rho}\hat{R}_z(\Phi)] = Tr[\hat{\rho}] = 1$$

from the property of Tr. Note that

$$\hat{\rho} = \begin{pmatrix} \rho_{11} & \rho_{12} \\ \rho_{21} & \rho_{22} \end{pmatrix}$$

$$\hat{R}_z(\Phi) = \exp\left(-\frac{i}{\hbar}\Phi\hat{I}_z\right) = \exp\left(-\frac{i}{2}\Phi\hat{\sigma}_z\right) = \begin{pmatrix} e^{-\frac{i}{2}\Phi} & 0 \\ 0 & e^{\frac{i}{2}\Phi} \end{pmatrix}$$

$$\hat{R}_z(-\Phi) = \exp\left(\frac{i}{\hbar}\Phi\hat{I}_z\right) = \exp\left(\frac{i}{2}\Phi\hat{\sigma}_z\right) = \begin{pmatrix} e^{\frac{i}{2}\Phi} & 0 \\ 0 & e^{-\frac{i}{2}\Phi} \end{pmatrix}$$

Thus we get

$$\begin{aligned}
\hat{\rho}_R &= \begin{pmatrix} e^{\frac{i}{2}\Phi} & 0 \\ 0 & e^{-\frac{i}{2}\Phi} \end{pmatrix} \begin{pmatrix} \rho_{11} & \rho_{12} \\ \rho_{21} & \rho_{22} \end{pmatrix} \begin{pmatrix} e^{-\frac{i}{2}\Phi} & 0 \\ 0 & e^{\frac{i}{2}\Phi} \end{pmatrix} \\
&= \begin{pmatrix} e^{\frac{i}{2}\Phi} & 0 \\ 0 & e^{-\frac{i}{2}\Phi} \end{pmatrix} \begin{pmatrix} \rho_{11}e^{-\frac{i}{2}\Phi} & \rho_{12}e^{\frac{i}{2}\Phi} \\ \rho_{21}e^{-\frac{i}{2}\Phi} & \rho_{22}e^{\frac{i}{2}\Phi} \end{pmatrix} \\
&= \begin{pmatrix} \rho_{11} & \rho_{12}e^{i\Phi} \\ \rho_{21}e^{-i\Phi} & \rho_{22} \end{pmatrix}
\end{aligned}$$

The thermal equilibrium density operator contains only populations, and is the same in both frames

$$(\hat{\rho}_{eq})_R = \hat{\rho}_{eq},$$

since

$$\hat{\rho}_{eq} = \frac{1}{2}\hat{I} + \frac{1}{2}\tilde{B}\hat{I}_z$$

is diagonal.

14. Free particle without relaxation

Suppose that there is no r.f. field between t_1 and t_2 . We note that

$$|\psi(t)\rangle_R = |\psi(t)\rangle$$

We still assume that ω_{rf} remains unchanged. For $t_2 - t_1 = \tau_p$

$$\hat{H} = \hbar\Omega_0\hat{I}_z$$

Then we have

$$\begin{aligned}
|\psi(t_2 = t_1 + \tau)\rangle &= \exp(-\frac{i}{\hbar} \hat{H}\tau) |\psi(t_1)\rangle \\
&= \exp(-\frac{i}{\hbar} \hbar \Omega_0 \hat{I}_z \tau) |\psi(t_1)\rangle \\
&= \exp(-i \Omega_0 \hat{I}_z \tau) |\psi(t_1)\rangle \\
&= \hat{R}_z(\Omega_0 \tau) |\psi(t_1)\rangle
\end{aligned}$$

Density operator

$$\begin{aligned}
\hat{\rho}(t_2) &= \overline{|\psi(t_2)\rangle\langle\psi(t_2)|} \\
&= \hat{R}_z(\Omega_0 \tau) \overline{|\psi(t_1)\rangle\langle\psi(t_1)|} \hat{R}_z(-\Omega_0 \tau) \\
&= \hat{R}_z(\Omega_0 \tau) \hat{\rho}(t_1) \hat{R}_z(-\Omega_0 \tau)
\end{aligned}$$

where

$$\begin{aligned}
\hat{R}_z(\Omega_0 \tau) &= \exp\left(-\frac{i}{2} \Omega_0 \tau \hat{\sigma}_z\right) = \begin{pmatrix} e^{-\frac{i}{2} \Omega_0 \tau} & 0 \\ 0 & e^{\frac{i}{2} \Omega_0 \tau} \end{pmatrix} \\
\hat{R}_z(-\Omega_0 \tau) &= \exp\left(\frac{i}{2} \Omega_0 \tau \hat{\sigma}_z\right) = \begin{pmatrix} e^{\frac{i}{2} \Omega_0 \tau} & 0 \\ 0 & e^{-\frac{i}{2} \Omega_0 \tau} \end{pmatrix}
\end{aligned}$$

Suppose that

$$\hat{\rho}(t_1) = \hat{\rho}_R(t_1) = \frac{1}{2} \hat{1} + \frac{1}{2} \tilde{B} \hat{I}_z$$

Thus we have

$$\begin{aligned}
\hat{\rho}(t_2) &= \hat{R}_z(\Omega_0\tau)\hat{\rho}(t_1)\hat{R}_z(-\Omega_0\tau) \\
&= \hat{R}_z(\Omega_0\tau)\left(\frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}\hat{I}_z\right)\hat{R}_z(-\Omega_0\tau) \\
&= \frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}\hat{R}_z(\Omega_0\tau)\hat{I}_z\hat{R}_z(-\Omega_0\tau) \\
&= \frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}\hat{I}_z\hat{R}_z(\Omega_0\tau)\hat{R}_z(-\Omega_0\tau) \\
&= \frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}\hat{I}_z \\
&= \hat{\rho}(t_1)
\end{aligned}$$

$$\begin{aligned}
\hat{\rho}_R(t_2) &= \hat{R}_z(-\Omega_0\tau)\hat{\rho}_R(t_1)\hat{R}_z(\Omega_0\tau) \\
&= \hat{R}_z(-\Omega_0\tau)\left(\frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}\hat{I}_z\right)\hat{R}_z(\Omega_0\tau) \\
&= \frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}\hat{R}_z(-\Omega_0\tau)\hat{I}_z\hat{R}_z(\Omega_0\tau) \\
&= \frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}\hat{I}_z\hat{R}_z(-\Omega_0\tau)\hat{R}_z(\Omega_0\tau) \\
&= \frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}\hat{I}_z \\
&= \hat{\rho}_R(t_1)
\end{aligned}$$

15. The magnetization vector using the density operator

$$M_x = \gamma\hbar\text{Tr}[\hat{I}_x\hat{\rho}] = \frac{\gamma\hbar}{2}(\rho_{12} + \rho_{21}) = \gamma\hbar\text{Re}[\rho_{12}]$$

$$M_y = \gamma\hbar\text{Tr}[\hat{I}_y\hat{\rho}] = \frac{\gamma\hbar}{2}i(\rho_{12} - \rho_{21}) = -\gamma\hbar\text{Im}[\rho_{12}]$$

$$M_z = \gamma\hbar\text{Tr}[\hat{I}_z\hat{\rho}] = \frac{\gamma\hbar}{2}(\rho_{11} - \rho_{22})$$

where

$$\text{Tr}[\hat{\rho}] = 1, \quad (\rho_{11} + \rho_{22} = 1)$$

$$\hat{\rho}^+ = \hat{\rho} \quad (\rho_{21} = \rho_{12}^*)$$

Thus we have

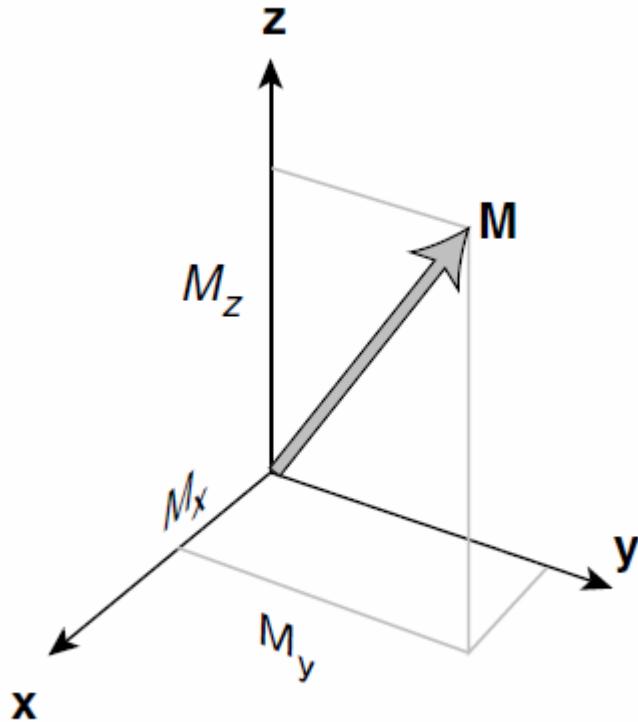
$$\rho_{11} = \frac{1}{2}(1 + \frac{2}{\gamma\hbar} M_z), \quad \rho_{22} = \frac{1}{2}(1 - \frac{2}{\gamma\hbar} M_z)$$

$$\rho_{12} = \frac{1}{\gamma\hbar}(M_x - iM_y), \quad \rho_{21} = \frac{1}{\gamma\hbar}(M_x + iM_y)$$

leading to the density matrix as

$$\hat{\rho} = \frac{1}{2}\hat{1} + \frac{1}{\gamma\hbar}(M_x \hat{\sigma}_x + M_z \hat{\sigma}_z + M_z \hat{\sigma}_z) = \frac{1}{2}\hat{1} + \frac{1}{\gamma\hbar} \mathbf{M} \cdot \hat{\boldsymbol{\sigma}}.$$

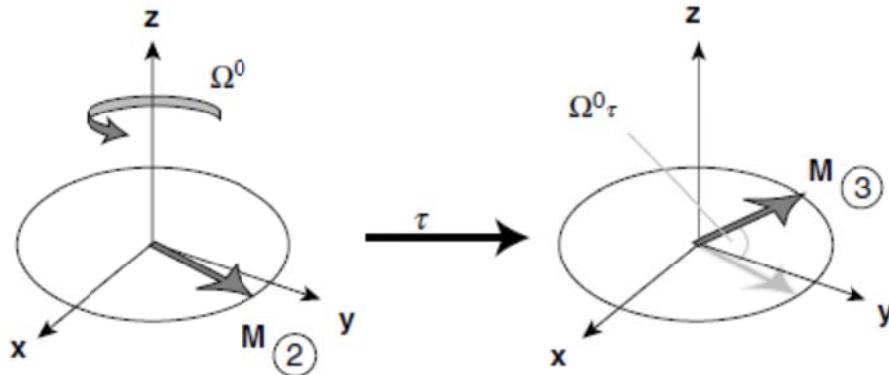
16. Magnetization vector (II) in general case



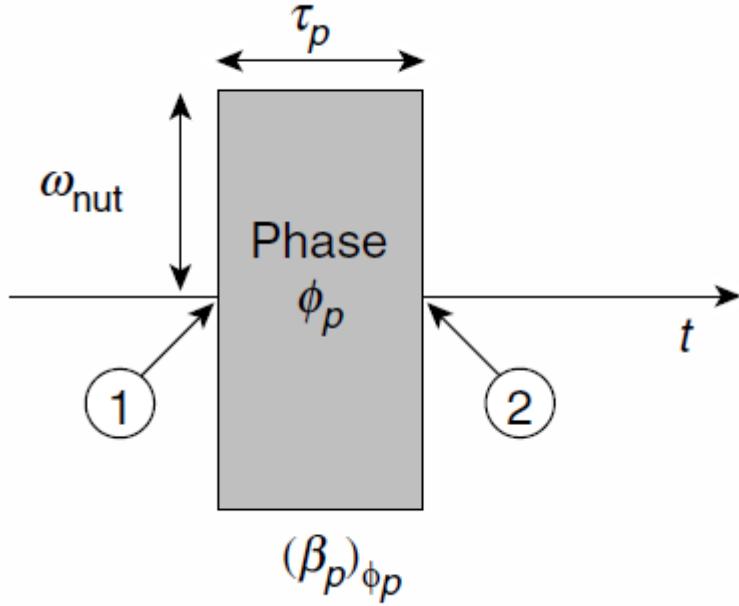
$$\begin{aligned}
M_x(t_3) &= \gamma\hbar \operatorname{Re}[\rho_{12}(t_3)] \\
&= \gamma\hbar \operatorname{Re}[\rho_{12}(t_2)e^{-i\omega_0\tau}] \\
&= \gamma\hbar \operatorname{Re}\{[(\operatorname{Re}\rho_{12}(t_2) + i\operatorname{Im}\rho_{12}(t_2))[\cos(\omega_0\tau) - i\sin(\omega_0\tau)]\} \\
&= \gamma\hbar[\operatorname{Re}\rho_{12}(t_2)\cos(\omega_0\tau) + \operatorname{Im}\rho_{12}(t_2)\sin(\omega_0\tau)] \\
&= M_x(t_2)\cos(\omega_0\tau) - M_y(t_2)\sin(\omega_0\tau)
\end{aligned}$$

$$\begin{aligned}
M_y(t_3) &= -\gamma\hbar \operatorname{Im}[\rho_{12}(t_3)] \\
&= -\gamma\hbar \operatorname{Im}[\rho_{12}(t_2)e^{-i\omega_0\tau}] \\
&= -\gamma\hbar \operatorname{Im}\{[(\operatorname{Re}\rho_{12}(t_2) + i\operatorname{Im}\rho_{12}(t_2))[\cos(\omega_0\tau) - i\sin(\omega_0\tau)]\} \\
&= -\gamma\hbar[\operatorname{Im}\rho_{12}(t_2)\cos(\omega_0\tau) - \operatorname{Re}\rho_{12}(t_2)\sin(\omega_0\tau)] \\
&= M_x(t_2)\sin(\omega_0\tau) + M_y(t_2)\cos(\omega_0\tau)
\end{aligned}$$

$$\begin{aligned}
M_z(t_3) &= \frac{\gamma\hbar}{2}[\rho_{11}(t_3) - \rho_{22}(t_3)] \\
&= \frac{\gamma\hbar}{2}[\rho_{11}(t_2) - \rho_{22}(t_2)] \\
&= M_z(t_2)
\end{aligned}$$



17. Strong radio-frequency pulse



$$|\psi(t_2)\rangle_R = \hat{R}_{\phi_p}(\beta_p)|\psi(t_1)\rangle_R$$

$$\hat{\rho}_R(t_2) = \hat{R}_{\phi_p}(\beta_p) \hat{\rho}_R(t_1) \hat{R}_{\phi_p}(-\beta_p)$$

where

$$\begin{aligned}\hat{\rho}_R(t) &= \hat{R}_z[-\Phi(t)] \hat{\rho}(t) \hat{R}_z[\Phi(t)] \\ &= \begin{pmatrix} e^{\frac{i}{2}\Phi(t)} & 0 \\ 0 & e^{-\frac{i}{2}\Phi(t)} \end{pmatrix} \begin{pmatrix} \rho_{11}(t) & \rho_{12}(t) \\ \rho_{21}(t) & \rho_{22}(t) \end{pmatrix} \begin{pmatrix} e^{-\frac{i}{2}\Phi(t)} & 0 \\ 0 & e^{\frac{i}{2}\Phi(t)} \end{pmatrix} \\ &= \begin{pmatrix} \rho_{11}(t) & e^{i\Phi(t)}\rho_{12}(t) \\ e^{-i\Phi(t)}\rho_{21}(t) & \rho_{22}(t) \end{pmatrix}\end{aligned}$$

or

$$\hat{\rho}_R(t) = \begin{pmatrix} \rho_{11}(t) & e^{i\Phi(t)}\rho_{12}(t) \\ e^{-i\Phi(t)}\rho_{21}(t) & \rho_{22}(t) \end{pmatrix}$$

where

$$\hat{R}_z[\Phi(t)] = \exp\left[-\frac{i}{\hbar}\Phi(t)\hbar\hat{I}_z\right] = \exp\left[-\frac{i}{2}\Phi(t)\hat{\sigma}_z\right] = \begin{pmatrix} e^{-\frac{i}{2}\Phi(t)} & 0 \\ 0 & e^{\frac{i}{2}\Phi(t)} \end{pmatrix}$$

and

$$\begin{aligned}\hat{\rho}(t) &= \hat{R}_z[\Phi(t)]\hat{\rho}_R(t)\hat{R}_z[-\Phi(t)] \\ &= \begin{pmatrix} \rho_{R11}(t) & e^{-i\Phi(t)}\rho_{R12}(t) \\ e^{i\Phi(t)}\rho_{R21}(t) & \rho_{R22}(t) \end{pmatrix}\end{aligned}$$

((Diagram))

$$\hat{\rho}_1 = \hat{\rho}_{eq} = \frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}\hat{I}_z$$

$$\downarrow \quad (\beta_p)_{\phi_p}$$

$$\hat{\rho}_2 = \frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}\hat{R}_{\phi_p}(\beta_p)\hat{I}_z\hat{R}_{\phi_p}(-\beta_p)$$

where

$$\begin{aligned}\hat{R}_{\phi_p}(\beta_p)\hat{I}_z\hat{R}_{\phi_p}(-\beta_p) &= \frac{1}{2} \begin{pmatrix} e^{-i\phi_p}(\cos\phi_p + i\cos\beta_p\sin\phi_p) & \sin\beta_p\sin\phi_p \\ \sin\beta_p\sin\phi_p & e^{i\phi_p}(-\cos\phi_p + i\cos\beta_p\sin\phi_p) \end{pmatrix} \\ &= (\cos^2\phi_p + \cos\beta_p\sin^2\phi_p)\hat{I}_z + i\sin\phi_p\cos\phi_p(-1 + \cos\beta_p)\hat{1} + \sin\beta_p\sin\phi_p\hat{I}_x\end{aligned}$$

18. Example: $\left(\frac{\pi}{2}\right)_x$ pulse with $\phi_p = 0$

For the $(\pi/2)_x$ with $\phi_p = 0$, we have

$$\hat{R}_{\phi_p=0}(\beta_p) = \hat{R}_x(\beta_p) = \exp(-i\beta_p\hat{I}_x)$$

with

$$\beta_p = \omega_{nut}\tau = \frac{\pi}{2}$$

At $t = t_1$,

$$\hat{\rho}(t_1) = \hat{\rho}_R(t_1) = \hat{\rho}_{eq} = \frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}\hat{I}_z \quad (\text{in thermal equilibrium})$$

$$\hat{R}_x(\beta_p = \frac{\pi}{2}) = \exp(-i\frac{\pi}{2}\hat{I}_x)$$

The density operator in the rotating frame is

$$\begin{aligned} \hat{\rho}_R(t_2) &= \hat{R}_x\left(\frac{\pi}{2}\right)\hat{\rho}_R(t_1)\hat{R}_x\left(-\frac{\pi}{2}\right) \\ &= \hat{R}_x\left(\frac{\pi}{2}\right)\left(\frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}\hat{I}_z\right)\hat{R}_x\left(-\frac{\pi}{2}\right) \\ &= \frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}\hat{R}_x\left(\frac{\pi}{2}\right)\hat{I}_z\hat{R}_x\left(-\frac{\pi}{2}\right) \\ &= \frac{1}{2}\hat{1} - \frac{1}{2}\tilde{B}\hat{I}_y \end{aligned}$$

or

$$\hat{\rho}_R(t_2) = \frac{1}{2}\hat{1} - \frac{1}{2}\tilde{B}\hat{I}_y.$$

where

$$\hat{R}_x\left(\frac{\pi}{2}\right)\hat{I}_z\hat{R}_x\left(-\frac{\pi}{2}\right) = -\hat{I}_y \quad (\text{using Mathematica})$$

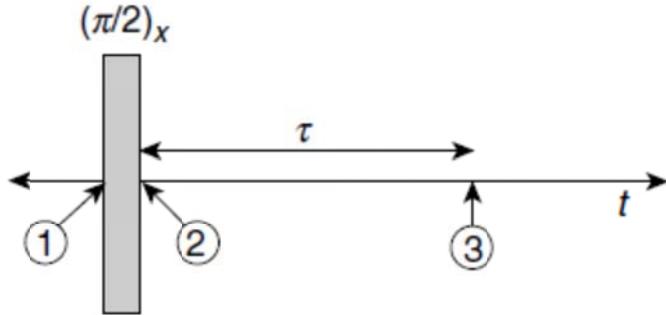
We note that

$$\begin{aligned}
\hat{\rho}(t_2) &= \hat{R}_z[\Phi(t_2)]\hat{\rho}_R(t_2)\hat{R}_z[-\Phi(t_2)] \\
&= \hat{R}_z[\Phi(t_2)]\left(\frac{1}{2}\hat{1} - \frac{1}{2}\tilde{B}\hat{I}_y\right)\hat{R}_z[-\Phi(t_2)] \\
&= \frac{1}{2}\hat{1} - \frac{1}{2}\tilde{B}\hat{R}_z[\Phi(t_2)]\hat{I}_y\hat{R}_z[-\Phi(t_2)] \\
&= \frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}[\sin(\omega_{ref}t_2)\hat{I}_x - \cos(\omega_{ref}t_2)\hat{I}_y]
\end{aligned}$$

where

$$\hat{R}_z[\Phi(t)]\hat{\sigma}_y\hat{R}_z[-\Phi(t)] = \begin{pmatrix} 0 & -ie^{-i\omega_{ref}t} \\ ie^{i\omega_{ref}t} & 0 \end{pmatrix} = -\sin(\omega_{ref}t)\hat{\sigma}_x + \cos(\omega_{ref}t)\hat{\sigma}_y$$

19. Example: $\left(\frac{\pi}{2}\right)_x$ pulse, followed by a free precession interval



From the above discussion,

$$\hat{\rho}_R(t_2) = \frac{1}{2}\hat{1} - \frac{1}{2}\tilde{B}\hat{I}_y$$

We note that

$$\hat{\rho}_R(t_2) = \hat{\rho}(t_2) = \frac{1}{2}\hat{1} - \frac{1}{2}\tilde{B}\hat{I}_y$$

since there is no r.f. field in the period between t_2 and t_3 ,

$$\Phi = \omega_{ref} t = 0.$$

$$|\psi(t)\rangle_R = \hat{R}_z[\Phi(t)]|\psi(t)\rangle = |\psi(t)\rangle$$

Then we have

$$\begin{aligned}\hat{\rho}(t_3) &= \hat{R}_z(\Omega_0\tau_{23})\hat{\rho}(t_2)\hat{R}_z(-\Omega_0\tau_{23}) \\ &= \frac{1}{2}\hat{1} - \frac{1}{2}\tilde{B}\hat{R}_z(\Omega_0\tau_{23})\hat{I}_y\hat{R}_z(-\Omega_0\tau_{23}) \\ &= \frac{1}{2}\hat{1} - \frac{1}{4}\tilde{B}\begin{pmatrix} 0 & -ie^{-i\Omega_0\tau_{23}} \\ ie^{i\Omega_0\tau_{23}} & 0 \end{pmatrix} \\ &= \frac{1}{2}\hat{1} + \frac{1}{4}\tilde{B}[\sin(\Omega_0\tau_{23})\hat{\sigma}_x - \cos(\Omega_0\tau_{23})\hat{\sigma}_y] \\ &= \frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}[\sin(\Omega_0\tau_{23})\hat{I}_x - \cos(\Omega_0\tau_{23})\hat{I}_y]\end{aligned}$$

or

$$\hat{\rho}(t_3) = \frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}[\sin(\omega_0\tau_{23})\hat{I}_x - \cos(\omega_0\tau_{23})\hat{I}_y]$$

((Diagram))

$$\hat{\rho}_1 = \hat{\rho}_{eq} = \frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}\hat{I}_z$$

$$\downarrow \quad \left(\frac{\pi}{2}\right)_x$$

$$\hat{\rho}_2 = \frac{1}{2}\hat{1} - \frac{1}{2}\tilde{B}\hat{I}_y$$

$$\downarrow \quad \tau$$

$$\hat{\rho}_3 = \frac{1}{2}\tilde{B}[-\hat{I}_y \cos(\Omega_0\tau) + \hat{I}_x \sin(\Omega_0\tau)].$$

where

$$\hat{R}_x\left(\frac{\pi}{2}\right)\hat{I}_z\hat{R}_x\left(-\frac{\pi}{2}\right) = -\hat{I}_y$$

$$\hat{R}_z(\theta)\hat{I}_x\hat{R}_z(-\theta) = \hat{I}_x \cos \theta + \hat{I}_y \sin \theta$$

$$\hat{R}_z(\theta)\hat{I}_y\hat{R}_z(-\theta) = -\hat{I}_x \sin \theta + \hat{I}_y \cos \theta$$

In the case of the presence of transverse relaxation and longitudinal relaxation,

$$\hat{\rho}(t) = \frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}(1 - e^{-t/T_1})\hat{I}_z + \frac{1}{2}\tilde{B}[\sin(\omega_0\tau_{23})\hat{I}_x - \cos(\omega_0\tau_{23})\hat{I}_y]e^{-t/T_2}$$

((Diagram))

$$\hat{\rho}_1 = \hat{\rho}_{eq} = \frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}\hat{I}_z$$

$$\downarrow \quad (\frac{\pi}{2})_x$$

$$\hat{\rho}_2 = \frac{1}{2}\hat{1} - \frac{1}{2}\tilde{B}\hat{I}_y$$

$$\downarrow \quad \tau$$

$$\hat{\rho}_3 = \frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}(1 - e^{-\tau/T_1})\hat{I}_z - \frac{1}{2}\tilde{B}[\cos(\Omega_0\tau)\hat{I}_y - \sin(\Omega_0\tau)\hat{I}_x]e^{-\frac{\tau}{T_2}}$$

where

$$\hat{R}_z(\Omega_0\tau)\hat{I}_y\hat{R}_z(-\Omega_0\tau) = -\sin(\Omega_0\tau)\hat{I}_x + \cos(\Omega_0\tau)\hat{I}_y$$

20. Example: $\phi_p = 0 \cdot (\pi)_x$ pulse

For the $(\pi)_x$ with $\phi_p = 0$, we have

$$\hat{R}_{\phi_p=0}(\beta_p) = \hat{R}_x(\pi) = \exp(-i\pi\hat{I}_x)$$

The density operator in the rotation frame is

$$\begin{aligned}\hat{\rho}_R(t_2) &= \hat{R}_x(\pi)\left(\frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}\hat{I}_z\right)\hat{R}_x(-\pi) \\ &= \frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}\hat{R}_x(\pi)\hat{I}_z\hat{R}_x(-\pi) \\ &= \frac{1}{2}\hat{1} - \frac{1}{2}\tilde{B}\hat{I}_z\end{aligned}$$

where

$$\hat{R}_x(\pi)\hat{I}_z\hat{R}_x(-\pi) = -\hat{I}_z \quad (\text{using Mathematica}).$$

21. Transverse relaxation time T_2

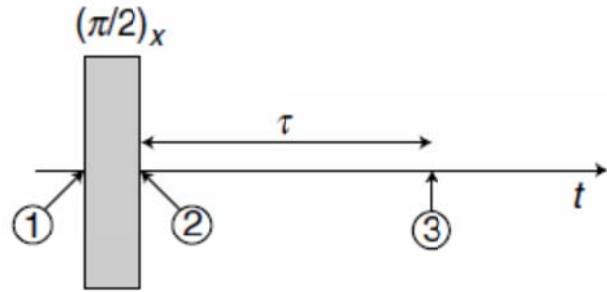
The phenomenological equation for the population is given by

$$\rho_{21}(t_2) = \rho_{21}(t_1) \exp\left[i\Omega_0 - \frac{1}{T_2}\right]\tau]$$

$$\rho_{12}(t_2) = \rho_{12}(t_1) \exp\left[-i\Omega_0 - \frac{1}{T_2}\right]\tau]$$

We consider the following case. At $t = t_1$, $\hat{\rho} = \hat{\rho}_{eq}$. the $\left(\frac{\pi}{2}\right)_x$ pulse is applied between t_1 and t_2 .

After that the r.f. pulse is turned off.



$$\hat{\rho}^{eq} = \frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}\hat{I}_z = \begin{pmatrix} \frac{1}{2} + \frac{1}{4}\tilde{B} & 0 \\ 0 & \frac{1}{2} - \frac{1}{4}\tilde{B} \end{pmatrix}$$

Just after the $\left(\frac{\pi}{2}\right)_x$ pulse is turned off,

$$\hat{\rho}(t_2) = \frac{1}{2}\hat{1} - \frac{1}{2}\tilde{B}\hat{I}_y = \begin{pmatrix} \frac{1}{2} & \frac{i}{4}\tilde{B} \\ -\frac{i}{4}\tilde{B} & \frac{1}{2} \end{pmatrix}$$

So we get

$$\rho_{12}(t_3 = t_2 + \tau) = \frac{i}{4}\tilde{B} \exp\left[-i\Omega_0 - \frac{1}{T_2}\right]\tau = \frac{i}{4}\tilde{B}e^{-\frac{\tau}{T_2}}[\cos(\Omega_0\tau) - i\sin(\Omega_0\tau)]$$

$$\rho_{21}(t_3 = t_2 + \tau) = -\frac{i}{4}\tilde{B} \exp\left[i\Omega_0 - \frac{1}{T_2}\right]\tau = -\frac{i}{4}\tilde{B}e^{-\frac{\tau}{T_2}}[\cos(\Omega_0\tau) + i\sin(\Omega_0\tau)]$$

$$\rho_{11}(t_3 = t_2 + \tau) = \frac{1}{2}, \quad \rho_{22}(t_3 = t_2 + \tau) = \frac{1}{2}$$

or

$$\hat{\rho}(t_3 = t_2 + \tau) = \begin{pmatrix} \frac{1}{2} & \frac{1}{4} \tilde{B} e^{-\frac{\tau}{T_2}} [i \cos(\Omega_0 \tau) + \sin(\Omega_0 \tau)] \\ \frac{1}{4} \tilde{B} e^{-\frac{\tau}{T_2}} [-i \cos(\Omega_0 \tau) + \sin(\Omega_0 \tau)] & \frac{1}{2} \end{pmatrix}$$

or

$$\hat{\rho}(t_3 = t_2 + \tau) = \frac{1}{2} \hat{I} + \frac{1}{2} \tilde{B} e^{-\frac{\tau}{T_2}} [-\cos(\Omega_0 \tau) \hat{I}_y + \sin(\Omega_0 \tau) \hat{I}_x]$$

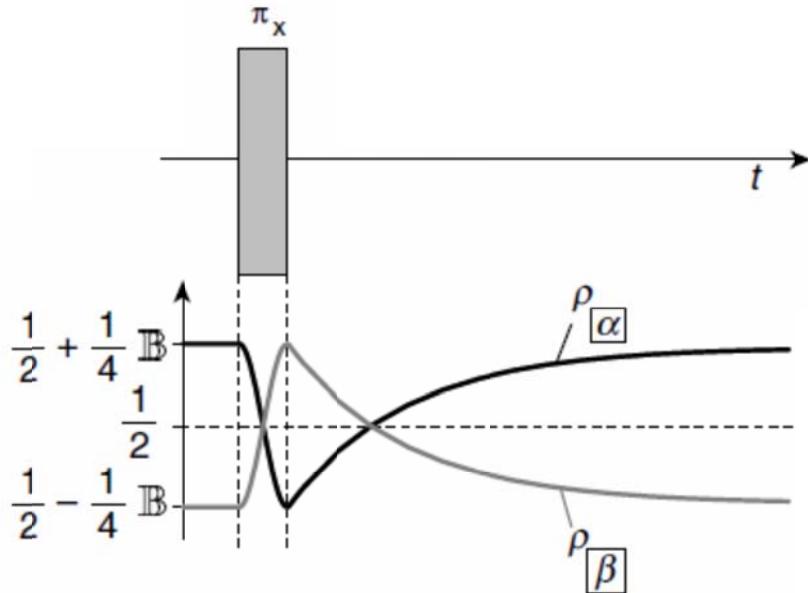
22. Longitudinal relaxation time T_1

The phenomenological equation for the population is given by

$$\rho_{11}(t_2) = [\rho_{11}(t_1) - \rho_{11}^{eq}] \exp(-\frac{\tau}{T_1}) + \rho_{11}^{eq}$$

$$\rho_{22}(t_2) = [\rho_{22}(t_1) - \rho_{22}^{eq}] \exp(-\frac{\tau}{T_1}) + \rho_{22}^{eq}$$

We consider the following case. At $t = t_1$, $\hat{\rho} = \hat{\rho}_{eq}$. the $(\pi)_x$ pulse is applied between t_1 and t_2 . After that the r.f. pulse is turned off.



$$\hat{\rho}^{eq} = \frac{1}{2}\hat{I} + \frac{1}{2}\tilde{B}\hat{I}_z = \begin{pmatrix} \frac{1}{2} + \frac{1}{4}\tilde{B} & 0 \\ 0 & \frac{1}{2} - \frac{1}{4}\tilde{B} \end{pmatrix}$$

Just after the $(\pi)_x$ pulse is turned off,

$$\hat{\rho}(t_2) = \frac{1}{2}\hat{I} - \frac{1}{2}\tilde{B}\hat{I}_z = \begin{pmatrix} \frac{1}{2} - \frac{1}{4}\tilde{B} & 0 \\ 0 & \frac{1}{2} + \frac{1}{4}\tilde{B} \end{pmatrix}$$

Using the above equations

$$\begin{aligned} \rho_{11}(t_3 = t_2 + \tau) &= \left\{ \left(\frac{1}{2} - \frac{1}{4}\tilde{B} \right) - \left(\frac{1}{2} + \frac{1}{4}\tilde{B} \right) \right\} e^{-\frac{\tau}{T_1}} + \left(\frac{1}{2} + \frac{1}{4}\tilde{B} \right) \\ &= \frac{1}{2} + \frac{1}{4}\tilde{B}(1 - 2e^{-\frac{\tau}{T_1}}) \end{aligned}$$

Similarly, we have $\rho_{22}(t_3)$ as

$$\begin{aligned} \rho_{22}(t_3) &= \left\{ \left(\frac{1}{2} + \frac{1}{4}\tilde{B} \right) - \left(\frac{1}{2} - \frac{1}{4}\tilde{B} \right) \right\} e^{-\frac{\tau}{T_1}} + \left(\frac{1}{2} - \frac{1}{4}\tilde{B} \right) \\ &= \frac{1}{2} - \frac{1}{4}\tilde{B}(1 - 2e^{-\frac{\tau}{T_1}}) \end{aligned}$$

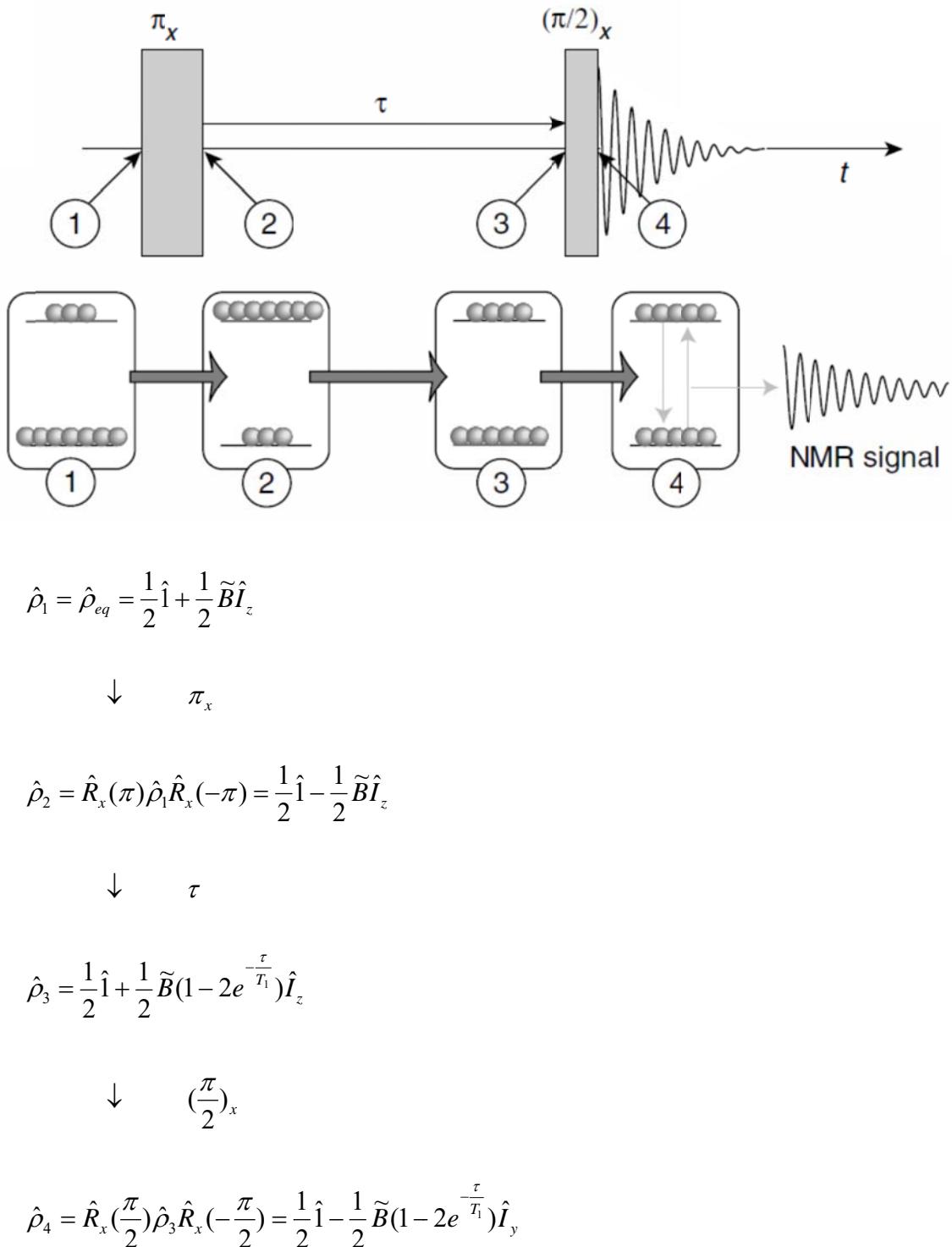
where

$$\tau = t_3 - t_2$$

In summary we get the expression

$$\hat{\rho}(t_3) = \frac{1}{2}\hat{I} + \frac{1}{2}\tilde{B}(1 - 2e^{-\frac{\tau}{T_1}})\hat{I}_z$$

23. rf spin echo method for determination of T1

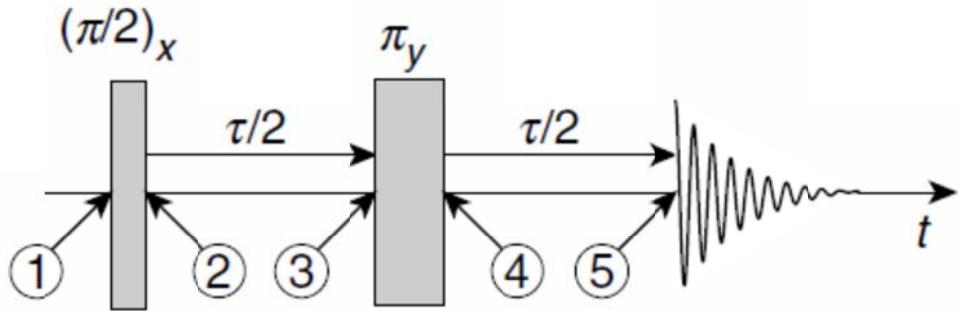


where

$$\hat{R}_x(\pi)\hat{I}_z\hat{R}_x(-\pi) = -\hat{I}_z$$

$$\hat{R}_x\left(\frac{\pi}{2}\right)\hat{I}_z\hat{R}_x\left(-\frac{\pi}{2}\right) = -\hat{I}_y$$

24. r.f. spin echo for determination of T_2



$$\hat{\rho}_1 = \hat{\rho}_{eq} = \frac{1}{2}\hat{1} + \frac{1}{2}\tilde{B}\hat{I}_z$$

$$\downarrow \quad \left(\frac{\pi}{2}\right)_x$$

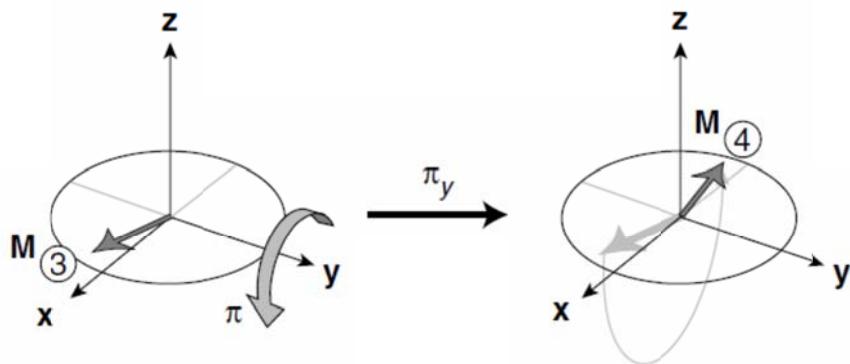
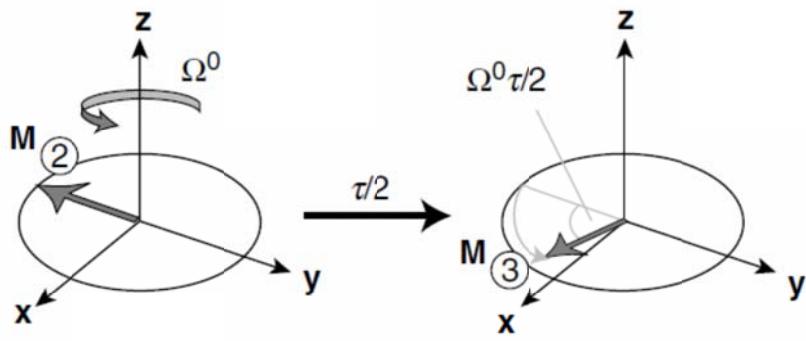
$$\hat{\rho}_2 = \frac{1}{2}\hat{1} - \frac{1}{2}\tilde{B}\hat{I}_y$$

$$\downarrow \quad \frac{1}{2}\tau$$

$$\hat{\rho}_3 = \frac{1}{2}\tilde{B}[-\hat{I}_y \cos(\frac{1}{2}\Omega_0\tau) + \hat{I}_x \sin(\frac{1}{2}\Omega_0\tau)]e^{-\frac{\tau}{2T_2}}$$

$$\downarrow \quad (\pi)_y$$

$$\hat{\rho}_4 = \frac{1}{2}\tilde{B}[-\hat{I}_y \cos(\frac{1}{2}\Omega_0\tau) - \hat{I}_x \sin(\frac{1}{2}\Omega_0\tau)]e^{-\frac{\tau}{2T_2}}$$



where

$$\hat{R}_x\left(\frac{\pi}{2}\right)\hat{I}_z\hat{R}_x\left(-\frac{\pi}{2}\right) = -\hat{I}_y$$

$$\hat{R}_y(\pi)\hat{I}_x\hat{R}_y(-\pi) = -\hat{I}_x$$

$$\hat{R}_y(\pi)\hat{I}_y\hat{R}_y(-\pi) = \hat{I}_y$$

REFERENCES

M.H. Levitt, Spin Dynamics, Basics of Nuclear Magnetic Resonance, second edition (John Wiley & Sons).

APPENDIX

Mathematica

```

Clear["Global`*"];
σx = PauliMatrix[1];
σy = PauliMatrix[2];
σz = PauliMatrix[3];

Rx[θ_] := MatrixExp[ $\frac{-i\theta}{2} \sigma_x$ ];
Ry[θ_] := MatrixExp[ $\frac{-i\theta}{2} \sigma_y$ ];
Rz[θ_] := MatrixExp[ $\frac{-i\theta}{2} \sigma_z$ ];

```

Rz[θ]

$$\left\{ \left\{ e^{-\frac{i\theta}{2}}, 0 \right\}, \left\{ 0, e^{\frac{i\theta}{2}} \right\} \right\}$$

Rx[θ]

$$\left\{ \left\{ \cos\left[\frac{\theta}{2}\right], -i \sin\left[\frac{\theta}{2}\right] \right\}, \left\{ -i \sin\left[\frac{\theta}{2}\right], \cos\left[\frac{\theta}{2}\right] \right\} \right\}$$

Ry[θ]

$$\left\{ \left\{ \cos\left[\frac{\theta}{2}\right], -\sin\left[\frac{\theta}{2}\right] \right\}, \left\{ \sin\left[\frac{\theta}{2}\right], \cos\left[\frac{\theta}{2}\right] \right\} \right\}$$

Rxy[θ] := MatrixExp[-i βp $\left(\frac{\cos[\theta]}{2} \sigma_x + \frac{\sin[\theta]}{2} \sigma_y \right)$];

```

k1 = Rxy[φp] // ExpToTrig // FullSimplify;
k1 // MatrixForm

```

$$\left(\begin{array}{cc} \cos\left[\frac{\beta p}{2}\right] & \sin\left[\frac{\beta p}{2}\right] (-i \cos[\phi p] - \sin[\phi p]) \\ \sin\left[\frac{\beta p}{2}\right] (-i \cos[\phi p] + \sin[\phi p]) & \cos\left[\frac{\beta p}{2}\right] \end{array} \right)$$


```

k11 = Rxy[π / 2] // ExpToTrig // FullSimplify;
k11 // MatrixForm

```

$$\left(\begin{array}{cc} \cos\left[\frac{\beta p}{2}\right] & -\sin\left[\frac{\beta p}{2}\right] \\ \sin\left[\frac{\beta p}{2}\right] & \cos\left[\frac{\beta p}{2}\right] \end{array} \right)$$


```

k12 = Rxy[0] // ExpToTrig // FullSimplify;
k12 // MatrixForm

```

$$\left(\begin{array}{cc} \cos\left[\frac{\beta p}{2}\right] & -i \sin\left[\frac{\beta p}{2}\right] \\ -i \sin\left[\frac{\beta p}{2}\right] & \cos\left[\frac{\beta p}{2}\right] \end{array} \right)$$


```

k13 = Rxy[π] // ExpToTrig // FullSimplify;
k13 // MatrixForm

```

$$\left(\begin{array}{cc} \cos\left[\frac{\beta p}{2}\right] & i \sin\left[\frac{\beta p}{2}\right] \\ i \sin\left[\frac{\beta p}{2}\right] & \cos\left[\frac{\beta p}{2}\right] \end{array} \right)$$

Roff [θ] :=

$$\text{MatrixExp}\left[-i \beta p \left(\frac{\cos[\theta]}{2} \sigma_x + \frac{\sin[\theta]}{2} \sigma_y\right) - i \frac{\Omega_0 \tau p}{2} \sigma_z\right];$$

Roff [θ] :=

$$\text{MatrixExp}\left[-i \beta p \left(\frac{\cos[\theta]}{2} \sigma_x + \frac{\sin[\theta]}{2} \sigma_y\right) - i \frac{\Omega_0 \tau p}{2} \sigma_z\right];$$

s1 =

$$\begin{aligned} \text{Roff}[\phi p] /. \left\{ \sqrt{\beta p^2 + \tau p^2 \Omega_0^2} \rightarrow \tau p \omega_{\text{eff}}, \right. \\ \left. \frac{1}{\sqrt{\beta p^2 + \tau p^2 \Omega_0^2}} \rightarrow \frac{1}{\tau p \omega_{\text{eff}}} \right\} // \text{FullSimplify}; \end{aligned}$$

s1 // **MatrixForm**

$$\left(\begin{array}{cc} \cos\left[\frac{\tau p \omega_{\text{eff}}}{2}\right] - \frac{i \Omega_0 \sin\left[\frac{\tau p \omega_{\text{eff}}}{2}\right]}{\omega_{\text{eff}}} & \frac{\beta p (-i \cos[\phi p] - \sin[\phi p]) \sin\left[\frac{\tau p \omega_{\text{eff}}}{2}\right]}{\tau p \omega_{\text{eff}}} \\ \frac{\beta p (-i \cos[\phi p] + \sin[\phi p]) \sin\left[\frac{\tau p \omega_{\text{eff}}}{2}\right]}{\tau p \omega_{\text{eff}}} & \cos\left[\frac{\tau p \omega_{\text{eff}}}{2}\right] + \frac{i \Omega_0 \sin\left[\frac{\tau p \omega_{\text{eff}}}{2}\right]}{\omega_{\text{eff}}} \end{array} \right)$$

((From Lecture Note on rf spin echo method))

