

3.3 Orbital angular momentum
Masatsugu Sei Suzuki
Department of Physics, SUNY at Binghamton
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1. Orbital angular momentum

We discuss the connection between the differential operator \mathbf{L}^2 ($\hat{\mathbf{L}}$ is the orbital angular momentum in quantum mechanics) and the angular part of the Laplacian in the spherical coordinates.

Here we use the identity (epsilon-delta relation)

$$\sum_k \epsilon_{ijk} \epsilon_{lmk} = \delta_{i,l} \delta_{j,m} - \delta_{i,m} \delta_{j,l}.$$

Together with the commutation relations of the position and momentum operators and expression for the orbital angular momentum operators to verify that $\hat{\mathbf{L}}^2$ operator is expressed by

$$\hat{\mathbf{L}}^2 = (\hat{\mathbf{r}} \times \hat{\mathbf{p}}) \cdot (\hat{\mathbf{r}} \times \hat{\mathbf{p}}) = \hat{\mathbf{r}}^2 \hat{\mathbf{p}}^2 - (\hat{\mathbf{r}} \cdot \hat{\mathbf{p}})^2 + i\hbar \hat{\mathbf{r}} \cdot \hat{\mathbf{p}}.$$

((Proof))

The proof is straightforward. To this end, we use the epsilon-delta relation (the proof is given later). Thus, we get

$$\begin{aligned} \hat{\mathbf{L}}^2 &= (\hat{\mathbf{r}} \times \hat{\mathbf{p}}) \cdot (\hat{\mathbf{r}} \times \hat{\mathbf{p}}) \\ &= \sum_{i,j,k,l,m} \epsilon_{ijk} \epsilon_{lmk} \hat{x}_i \hat{p}_j \hat{x}_l \hat{p}_m \\ &= \sum_{i,j,l,m} (\delta_{i,l} \delta_{j,m} - \delta_{i,m} \delta_{j,l}) \hat{x}_i \hat{p}_j \hat{x}_l \hat{p}_m \\ &= \sum_{i,j,l,m} [\delta_{i,l} \delta_{j,m} \hat{x}_i \hat{p}_j \hat{x}_l \hat{p}_m - \delta_{i,m} \delta_{j,l} \hat{x}_i \hat{p}_j \hat{x}_l \hat{p}_m] \\ &= \sum_{i,j,l,m} [\delta_{i,l} \delta_{j,m} \hat{x}_i (\hat{x}_l \hat{p}_j - i\hbar \delta_{j,l}) \hat{p}_m - \delta_{i,m} \delta_{j,l} \hat{x}_i \hat{p}_j (\hat{p}_m \hat{x}_l + i\hbar \delta_{l,m})] \end{aligned}$$

or

$$\begin{aligned}
\hat{\mathbf{L}}^2 &= (\hat{\mathbf{r}} \times \hat{\mathbf{p}}) \cdot (\hat{\mathbf{r}} \times \hat{\mathbf{p}}) \\
&= \sum_{i,j,l,m} [\delta_{i,l}\delta_{j,m}\hat{x}_i(\hat{x}_l\hat{p}_j - i\hbar\delta_{j,l})\hat{p}_m - \delta_{i,m}\delta_{j,l}(\hat{x}_i\hat{p}_m\hat{p}_j\hat{x}_l + i\hbar\delta_{l,m}\hat{x}_i\hat{p}_j)] \\
&= \sum_{i,j,l,m} [\delta_{i,l}\delta_{j,m}(\hat{x}_i\hat{x}_l\hat{p}_j\hat{p}_m - i\hbar\delta_{j,l}\hat{x}_i\hat{p}_m) - \delta_{i,m}\delta_{j,l}(\hat{x}_i\hat{p}_m\hat{p}_j\hat{x}_l + i\hbar\delta_{l,m}\hat{x}_i\hat{p}_j)] \\
&= \hat{\mathbf{r}}^2\hat{\mathbf{p}}^2 - i\hbar\hat{\mathbf{r}} \cdot \hat{\mathbf{p}} - \sum_{i,j,l,m} \delta_{i,m}\delta_{j,l}[\hat{x}_i\hat{p}_m(\hat{x}_l\hat{p}_j - i\hbar\delta_{l,j}) + i\hbar\delta_{l,m}\hat{x}_i\hat{p}_j] \\
&= \hat{\mathbf{r}}^2\hat{\mathbf{p}}^2 - i\hbar\hat{\mathbf{r}} \cdot \hat{\mathbf{p}} - \sum_{i,j,l,m} \delta_{i,m}\delta_{j,l}(\hat{x}_i\hat{p}_m\hat{x}_l\hat{p}_j - i\hbar\delta_{l,j}\hat{x}_i\hat{p}_m + i\hbar\delta_{l,m}\hat{x}_i\hat{p}_j) \\
&= \hat{\mathbf{r}}^2\hat{\mathbf{p}}^2 - i\hbar\hat{\mathbf{r}} \cdot \hat{\mathbf{p}} - (\hat{\mathbf{r}} \cdot \hat{\mathbf{p}})^2 + 3i\hbar\hat{\mathbf{r}} \cdot \hat{\mathbf{p}} - i\hbar\hat{\mathbf{r}} \cdot \hat{\mathbf{p}} \\
&= \hat{\mathbf{r}}^2\hat{\mathbf{p}}^2 + i\hbar\hat{\mathbf{r}} \cdot \hat{\mathbf{p}} - (\hat{\mathbf{r}} \cdot \hat{\mathbf{p}})^2
\end{aligned}$$

or

$$\hat{\mathbf{L}}^2 = (\hat{\mathbf{r}} \times \hat{\mathbf{p}}) \cdot (\hat{\mathbf{r}} \times \hat{\mathbf{p}}) = \hat{\mathbf{r}}^2\hat{\mathbf{p}}^2 + i\hbar\hat{\mathbf{r}} \cdot \hat{\mathbf{p}} - (\hat{\mathbf{r}} \cdot \hat{\mathbf{p}})^2.$$

Note that

$$\sum_{i,j,l,m} \delta_{i,l}\delta_{j,m}\hat{x}_i\hat{x}_l\hat{p}_j\hat{p}_m = \sum_{i,j} \hat{x}_i^2\hat{x}_i\hat{p}_j^2 = \hat{\mathbf{r}}^2\hat{\mathbf{p}}^2,$$

$$\sum_{i,j,l,m} \delta_{i,l}\delta_{j,m}\delta_{j,l}\hat{x}_i\hat{p}_m = \sum_{i,j,l} \delta_{i,l}\delta_{j,l}\hat{x}_i\hat{p}_j = \sum_{i,l} \delta_{i,l}\hat{x}_i\hat{p}_l = \sum_i \hat{x}_i\hat{p}_i = \hat{\mathbf{r}} \cdot \hat{\mathbf{p}},$$

$$\sum_{i,j,l,m} \delta_{i,m}\delta_{j,l}\delta_{l,j}\hat{x}_i\hat{p}_m = (\sum_{i,m} \delta_{i,m}\hat{x}_i\hat{p}_m) \sum_{j,l} \delta_{j,l}\delta_{l,j} = 3 \sum_i \hat{x}_i\hat{p}_i = 3(\hat{\mathbf{r}} \cdot \hat{\mathbf{p}}),$$

$$\sum_{j,l} \delta_{j,l}\delta_{l,j} = \sum_{j,l} \langle j | l \rangle \langle l | j \rangle = \sum_j \langle j | j \rangle = 3$$

2. $\varepsilon - \delta$ relation

In the above proof we use the relation given by

$$\sum_k \varepsilon_{ijk} \varepsilon_{lmk} = \delta_{i,l}\delta_{j,m} - \delta_{i,m}\delta_{j,l}$$

((Proof))

We use the formula in vector analysis (Cartesian coordinates, 3D)

$$(\mathbf{A} \times \mathbf{B}) \cdot (\mathbf{C} \times \mathbf{D}) = (\mathbf{A} \cdot \mathbf{C}) \cdot (\mathbf{B} \cdot \mathbf{D}) - (\mathbf{A} \cdot \mathbf{D}) \cdot (\mathbf{B} \cdot \mathbf{C})$$

where

$$(\mathbf{A} \times \mathbf{B})_k = \sum_{i,j} \epsilon_{ijk} A_i B_j ,$$

$$(\mathbf{C} \times \mathbf{D})_k = \sum_{l,m} \epsilon_{lmk} C_l D_m .$$

This we have

$$(\mathbf{A} \times \mathbf{B}) \cdot (\mathbf{C} \times \mathbf{D}) = \sum_{i,j,k,l,m} \epsilon_{ijk} \epsilon_{lmk} A_i B_j C_l D_m ,$$

$$\begin{aligned} (\mathbf{A} \cdot \mathbf{C}) \cdot (\mathbf{B} \cdot \mathbf{D}) &= \sum_{i,l} \delta_{i,l} A_i C_l \sum_{j,m} \delta_{j,m} B_j D_m \\ &= \sum_{i,j,l,m} \delta_{i,l} \delta_{j,m} A_i B_j C_l D_m \end{aligned}$$

$$\begin{aligned} (\mathbf{A} \cdot \mathbf{D}) \cdot (\mathbf{B} \cdot \mathbf{C}) &= \sum_{i,m} \delta_{i,m} A_i D_m \sum_{j,l} \delta_{j,l} B_j C_l \\ &= \sum_{i,j,l,m} \delta_{i,m} \delta_{j,l} A_i B_j C_l D_m \end{aligned}$$

So that, we get the epsilon-delta relation

$$\sum_k \epsilon_{ijk} \epsilon_{lmk} = \delta_{i,l} \delta_{j,m} - \delta_{i,m} \delta_{j,l} .$$

3. The expression: $\mathbf{p}^2 = p_r^2 + \frac{\mathbf{L}^2}{r^2}$

We note that

$$\hat{\mathbf{L}}^2 = (\hat{\mathbf{r}} \times \hat{\mathbf{p}}) \cdot (\hat{\mathbf{r}} \times \hat{\mathbf{p}}) = \hat{\mathbf{r}}^2 \hat{\mathbf{p}}^2 + i\hbar \hat{\mathbf{r}} \cdot \hat{\mathbf{p}} - (\hat{\mathbf{r}} \cdot \hat{\mathbf{p}})^2$$

In the $|\mathbf{r}\rangle$ representation, we get the following expressions,

$$\langle \mathbf{r} | \hat{\mathbf{L}}^2 | \psi \rangle = \mathbf{L}^2 \langle \mathbf{r} | \psi \rangle = \mathbf{L}^2 \psi(\mathbf{r})$$

where \mathbf{L}^2 is the differential operator.

$$\begin{aligned}\langle \mathbf{r} | \hat{\mathbf{r}}^2 \hat{\mathbf{p}}^2 | \psi \rangle &= -\hbar^2 \mathbf{r}^2 \nabla^2 \langle \mathbf{r} | \psi \rangle \\ &= -\hbar^2 \mathbf{r}^2 \nabla^2 \psi(\mathbf{r})\end{aligned}$$

where $\mathbf{p} = \frac{\hbar}{i} \nabla$ is the differential operator of the momentum $\hat{\mathbf{p}}$ of quantum mechanics.

$$\begin{aligned}\langle \mathbf{r} | i\hbar \hat{\mathbf{r}} \cdot \hat{\mathbf{p}} | \psi \rangle &= i\hbar \mathbf{r} \cdot \frac{\hbar}{i} \nabla \langle \mathbf{r} | \psi \rangle \\ &= \hbar^2 (\mathbf{r} \cdot \nabla) \langle \mathbf{r} | \psi \rangle \\ &= \hbar^2 r \frac{\partial}{\partial r} \psi(\mathbf{r})\end{aligned}$$

$$\begin{aligned}\langle \mathbf{r} | (\hat{\mathbf{r}} \cdot \hat{\mathbf{p}})(\hat{\mathbf{r}} \cdot \hat{\mathbf{p}}) | \psi \rangle &= (\mathbf{r} \cdot \frac{\hbar}{i} \nabla)(\mathbf{r} \cdot \frac{\hbar}{i} \nabla) \langle \mathbf{r} | \psi \rangle \\ &= -\hbar^2 (r \frac{\partial}{\partial r})(r \frac{\partial}{\partial r}) \langle \mathbf{r} | \psi \rangle \\ &= -\hbar^2 (r^2 \frac{\partial^2}{\partial r^2} + r \frac{\partial}{\partial r}) \psi(\mathbf{r})\end{aligned}$$

Thus, we have

$$\mathbf{L}^2 \psi(\mathbf{r}) = -\hbar^2 r^2 \nabla^2 \psi(\mathbf{r}) + \hbar^2 (r^2 \frac{\partial^2}{\partial r^2} + 2r \frac{\partial}{\partial r}) \psi(\mathbf{r})$$

or

$$\begin{aligned}\frac{\mathbf{p}^2}{2\mu} &= -\frac{\hbar^2}{2\mu} \nabla^2 \psi(\mathbf{r}) \\ &= -\frac{\hbar^2}{2\mu} (\frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r}) \psi(\mathbf{r}) + \frac{1}{2\mu r^2} \mathbf{L}^2 \psi(\mathbf{r}) \\ &= \frac{1}{2\mu} (p_r^2 + \frac{1}{r^2} \mathbf{L}^2) \psi(\mathbf{r})\end{aligned}$$

where μ is the mass of particle and p_r is the radial linear momentum.

$$\begin{aligned}
p_r^2 \psi(\mathbf{r}) &= \frac{\hbar}{ir} \frac{\partial}{\partial r} \left(r \frac{\hbar}{ir} \frac{\partial}{\partial r} r \right) \psi(\mathbf{r}) \\
&= -\frac{\hbar^2}{r} \frac{\partial^2}{\partial r^2} [r \psi(\mathbf{r})] \\
&= -\frac{\hbar^2}{r} \frac{\partial}{\partial r} \left[r \frac{\partial}{\partial r} \psi(\mathbf{r}) + \psi(\mathbf{r}) \right] \\
&= -\hbar^2 \left(\frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} \right) \psi(\mathbf{r})
\end{aligned}$$

4. Proof using the Mathematica

Using the Mathematica (the differential operator in the spherical coordinate) we show that

$$\mathbf{p}^2 = -\hbar^2 \nabla^2 = p_r^2 + \frac{1}{r^2} \mathbf{L}^2$$

or

$$\nabla^2 = \frac{\partial^2}{\partial r^2} + \frac{2}{r} \frac{\partial}{\partial r} - \frac{\mathbf{L}^2}{\hbar^2 r^2}$$

with $p_r = \frac{\hbar}{ir} \frac{\partial}{\partial r} r$

((Mathematica))

Orbital angular momentum in the spherical coordinates|

```
Clear["Global`"];
ux = {Sin[\theta] Cos[\phi], Cos[\theta] Cos[\phi], -Sin[\phi]};
uy = {Sin[\theta] Sin[\phi], Cos[\theta] Sin[\phi], Cos[\phi]};
uz = {Cos[\theta], -Sin[\theta], 0};
ur = {1, 0, 0};
Lap := Laplacian[#, {r, \theta, \phi}, "Spherical"] &;
Gra := Grad[#, {r, \theta, \phi}, "Spherical"] &;
Diva := Div[#, {r, \theta, \phi}, "Spherical"] &;
Curla := Curl[#, {r, \theta, \phi}, "Spherical"] &;
L := (-I \hbar (Cross[(ur r), Gra[#]]) &) // Simplify;
Lx := (ux.L[#] &) // Simplify;
Ly := (uy.L[#] &) // Simplify;
Lz := (uz.L[#] &) // Simplify;
LP := (Lx[#] + I Ly[#]) & // Simplify;
LM = (Lx[#] - I Ly[#]) & // Simplify;
prq :=  $\left( \frac{-I \hbar}{2} ur . Gra[\#] + \frac{-I \hbar}{2} Diva[\# ur] \right) \&;$ 
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$$\text{prq} := \left(\frac{-i\hbar}{2} \text{ur} . \text{Gra}[\#] + \frac{-i\hbar}{2} \text{Diva}[\# \text{ur}] \right) \&;$$

$\text{eq1} = \text{prq}^2 \psi(r, \theta, \phi); \text{prq is the radial linear momentum}$

$\text{eq1} = \text{Nest}[\text{prq}, \psi[r, \theta, \phi], 2] // \text{FullSimplify}$

$$-\frac{\hbar^2 (2 \psi^{(1,0,0)}[r, \theta, \phi] + r \psi^{(2,0,0)}[r, \theta, \phi])}{r}$$

$$\text{eq2} = \frac{1}{r^2} L^2 \psi(r, \theta, \phi)$$

$\text{eq2} =$

$$\begin{aligned} & \frac{1}{r^2} (\text{Nest}[\text{Lx}, \psi[r, \theta, \phi], 2] + \text{Nest}[\text{Ly}, \psi[r, \theta, \phi], 2] + \\ & \quad \text{Nest}[\text{Lz}, \psi[r, \theta, \phi], 2]) // \text{Simplify} \\ & - \frac{1}{r^2} \hbar^2 (\text{Csc}[\theta]^2 \psi^{(0,0,2)}[r, \theta, \phi] + \\ & \quad \text{Cot}[\theta] \psi^{(0,1,0)}[r, \theta, \phi] + \psi^{(0,2,0)}[r, \theta, \phi]) \end{aligned}$$

$$\text{eq3} = -\hbar^2 \Delta \psi(r, \theta, \phi)$$

$\text{eq3} = -\hbar^2 \text{Lap}[\psi[r, \theta, \phi]] // \text{Simplify}$

$$\begin{aligned} & -\frac{1}{r^2} \hbar^2 (\text{Csc}[\theta]^2 \psi^{(0,0,2)}[r, \theta, \phi] + \text{Cot}[\theta] \psi^{(0,1,0)}[r, \theta, \phi] + \\ & \quad \psi^{(0,2,0)}[r, \theta, \phi] + 2r \psi^{(1,0,0)}[r, \theta, \phi] + r^2 \psi^{(2,0,0)}[r, \theta, \phi]) \end{aligned}$$

$\text{eq1} = \text{eq2} - \text{eq3} = 0; \text{Proof of } p^2 = \text{prq}^2 + L^2/r^2$

$\text{eq1} + \text{eq2} - \text{eq3} // \text{FullSimplify}$

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REFERENCES

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