

**Sakurai Chapter 3**  
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 (Date: October 12, 2011)

((3-1))

1. Find the eigenvalues and eigenvectors of  $\sigma_y = \begin{pmatrix} 0 & -i \\ i & 0 \end{pmatrix}$ . Suppose an electron is in the spin state  $\begin{pmatrix} \alpha \\ \beta \end{pmatrix}$ . If  $s_y$  is measured, what is the probability of the result  $\hbar/2$ ?

We know that

$$|+\rangle_y = \frac{1}{\sqrt{2}}[|+\rangle + i|-\rangle] = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix}, \quad \text{and} \quad |-\rangle_y = \frac{1}{\sqrt{2}}[|+\rangle - i|-\rangle] = \frac{1}{\sqrt{2}}$$

$$|\psi\rangle = \begin{pmatrix} \alpha \\ \beta \end{pmatrix}, \quad \text{where } |\alpha|^2 + |\beta|^2 = 1$$

The probability of finding the state  $|+\rangle_y$  is

$$P = \left| \langle + | \psi \rangle \right|^2 = \left| \frac{1}{\sqrt{2}} (1 - i) \begin{pmatrix} \alpha \\ \beta \end{pmatrix} \right|^2 = \frac{1}{2} |\alpha - i\beta|^2 = \frac{1}{2} (\alpha - i\beta)(\alpha^* + i\beta^*)$$

((3-2))

2. Consider the  $2 \times 2$  matrix defined by

$$U = \frac{a_0 + i\boldsymbol{\sigma} \cdot \mathbf{a}}{a_0 - i\boldsymbol{\sigma} \cdot \mathbf{a}},$$

where  $a_0$  is a real number and  $\mathbf{a}$  is a three-dimensional vector with real components.

- a. Prove that  $U$  is unitary and unimodular.
- b. In general, a  $2 \times 2$  unitary unimodular matrix represents a rotation in three dimensions. Find the axis and angle of rotation appropriate for  $U$  in terms of  $a_0$ ,  $a_x$ ,  $a_y$ , and  $a_z$ .

(a)

$$\hat{U} = (a_0 \hat{1} + i\hat{\boldsymbol{\sigma}} \cdot \mathbf{a})(a_0 \hat{1} - i\hat{\boldsymbol{\sigma}} \cdot \mathbf{a})^{-1}$$

$$\hat{U}^\dagger = (a_0 \hat{1} - i\hat{\boldsymbol{\sigma}} \cdot \mathbf{a})(a_0 \hat{1} + i\hat{\boldsymbol{\sigma}} \cdot \mathbf{a})^{-1}$$

Then we have

$$\hat{U}^+\hat{U} = \hat{U}\hat{U}^+ = \hat{1}$$

So  $\hat{U}$  is the unitary operator.

$$\det \hat{U} = 1$$

from the Mathematica 5.2 (below).

Thus  $\hat{U}$  is unimodular.

(b)

$$U = \begin{pmatrix} \frac{a_0^2 - \mathbf{a}^2 + 2ia_0a_z}{a_0^2 + \mathbf{a}^2} & \frac{2a_0(ia_x + a_y)}{a_0^2 + \mathbf{a}^2} \\ \frac{2a_0(ia_x - a_y)}{a_0^2 + \mathbf{a}^2} & \frac{a_0^2 - \mathbf{a}^2 - 2ia_0a_z}{a_0^2 + \mathbf{a}^2} \end{pmatrix}$$

$$\exp\left(-\frac{i\bar{\sigma} \cdot \mathbf{n}\phi}{2}\right) = \begin{pmatrix} \cos \frac{\phi}{2} - in_z \sin \frac{\phi}{2} & (-in_x - n_y) \sin \frac{\phi}{2} \\ (-in_x + n_y) \sin \frac{\phi}{2} & \cos \frac{\phi}{2} - in_z \sin \frac{\phi}{2} \end{pmatrix}$$

$$\cos \frac{\phi}{2} = \frac{a_0^2 - \mathbf{a}^2}{a_0^2 + \mathbf{a}^2}$$

$$\sin^2 \frac{\phi}{2} = 1 - \cos^2 \frac{\phi}{2} = 1 - \left(\frac{a_0^2 - \mathbf{a}^2}{a_0^2 + \mathbf{a}^2}\right)^2 = \frac{(a_0^2 + \mathbf{a}^2)^2 - (a_0^2 - \mathbf{a}^2)^2}{(a_0^2 + \mathbf{a}^2)^2} = \frac{4a_0^2 \mathbf{a}^2}{(a_0^2 + \mathbf{a}^2)^2}$$

or

$$\sin \frac{\phi}{2} = \frac{2a_0|\mathbf{a}|}{a_0^2 + \mathbf{a}^2}$$

$$-n_z \sin \frac{\phi}{2} = \frac{2a_0a_z}{a_0^2 + \mathbf{a}^2},$$

$$-n_y \sin \frac{\phi}{2} = \frac{2a_0a_y}{a_0^2 + \mathbf{a}^2}$$

$$-n_x \sin \frac{\phi}{2} = \frac{2a_0a_x}{a_0^2 + \mathbf{a}^2}$$

Then we have

$$n_z = -\frac{a_z}{|\mathbf{a}|},$$

$$n_y = -\frac{a_y}{|\mathbf{a}|}$$

$$n_x = -\frac{a_x}{|\mathbf{a}|}$$

((Mathematica 5.2))

(\*Sakurai 3-2\*)

**conjugateRule =**

**{Complex[re\_, im\_] :=> Complex[re, -im]};**

**Unprotect [SuperStar];**

**SuperStar /: exp\_ \* := exp /. conjugateRule;**

**Protect [SuperStar]**

**{SuperStar}**

**$\sigma_x = \{\{0, 1\}, \{1, 0\}\}$**

**$\{\{0, 1\}, \{1, 0\}\}$**

**$\sigma_y = \{\{0, -i\}, \{i, 0\}\}$**

**$\{\{0, -i\}, \{i, 0\}\}$**

**$\sigma_z = \{\{1, 0\}, \{0, -1\}\}$**

**$\{\{1, 0\}, \{0, -1\}\}$**

**$\sigma_I = \{\{1, 0\}, \{0, 1\}\}$**

**$\{\{1, 0\}, \{0, 1\}\}$**

**P1=a0  $\sigma_I + i$  ( $\sigma_x ax + \sigma_y ay + \sigma_z az$ )//Simplify**

**$\{\{a0 + i az, i ax + ay\}, \{i ax - ay, a0 - i az\}\}$**

**P2=a0  $\sigma_I - i$  ( $\sigma_x ax + \sigma_y ay + \sigma_z az$ )//Simplify**

**$\{\{a0 - i az, -i ax - ay\}, \{-i ax + ay, a0 + i az\}\}$**

**P3=Inverse[P2]//Simplify**

**$\left\{ \left\{ \frac{a0 + i az}{a0^2 + ax^2 + ay^2 + az^2}, \frac{i ax + ay}{a0^2 + ax^2 + ay^2 + az^2} \right\}, \right.$**

**$\left. \left\{ \frac{i ax - ay}{a0^2 + ax^2 + ay^2 + az^2}, \frac{a0 - i az}{a0^2 + ax^2 + ay^2 + az^2} \right\} \right\}$**

**U=P1.P3//Simplify**

$$\left\{ \left\{ -\frac{-a_0^2 + ax^2 + ay^2 - 2i a_0 az + az^2}{a_0^2 + ax^2 + ay^2 + az^2}, \right. \right. \\ \left. \left. \frac{2 a_0 (i ax + ay)}{a_0^2 + ax^2 + ay^2 + az^2} \right\}, \left\{ \frac{2 i a_0 (ax + i ay)}{a_0^2 + ax^2 + ay^2 + az^2}, \right. \right. \\ \left. \left. -\frac{-a_0^2 + ax^2 + ay^2 + 2 i a_0 az + az^2}{a_0^2 + ax^2 + ay^2 + az^2} \right\} \right\}$$

**UH = Transpose[U\*] // Simplify**

$$\left\{ \left\{ -\frac{-a_0^2 + ax^2 + ay^2 + 2 i a_0 az + az^2}{a_0^2 + ax^2 + ay^2 + az^2}, \right. \right. \\ \left. \left. \frac{a_0 (-2 i ax - 2 ay)}{a_0^2 + ax^2 + ay^2 + az^2} \right\}, \left\{ \frac{2 a_0 (-i ax + ay)}{a_0^2 + ax^2 + ay^2 + az^2}, \right. \right. \\ \left. \left. -\frac{-a_0^2 + ax^2 + ay^2 - 2 i a_0 az + az^2}{a_0^2 + ax^2 + ay^2 + az^2} \right\} \right\}$$

**U.UH//Simplify**

**{{1,0},{0,1}}**

**Det[U]//Simplify**

**1**

$$\mathbf{T1 = MatrixExp\left[-\frac{i}{2} \phi (nx \sigma_x + ny \sigma_y + nz \sigma_z)\right];$$

**T2 =**

$$\mathbf{T1 /. \{nx^2 + ny^2 + nz^2 \to 1\} /. \{\sqrt{-nx^2 - ny^2 - nz^2} \to i\} /.}$$

$$\left\{ \frac{1}{\sqrt{-nx^2 - ny^2 - nz^2}} \to -i \right\} // \mathbf{ExpToTrig}$$

$$\left\{ \left\{ \cos\left[\frac{\phi}{2}\right] - i nz \sin\left[\frac{\phi}{2}\right], -i nx \sin\left[\frac{\phi}{2}\right] - ny \sin\left[\frac{\phi}{2}\right] \right\}, \right.$$

$$\left. \left\{ -i nx \sin\left[\frac{\phi}{2}\right] + ny \sin\left[\frac{\phi}{2}\right], \cos\left[\frac{\phi}{2}\right] + i nz \sin\left[\frac{\phi}{2}\right] \right\} \right\}$$

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**((3-3))**

3. The spin-dependent Hamiltonian of an electron-positron system in the presence of a uniform magnetic field in the  $z$ -direction can be written as

$$H = A\mathbf{S}^{(e^-)} \cdot \mathbf{S}^{(e^+)} + \left(\frac{eB}{mc}\right)(S_z^{(e^-)} - S_z^{(e^+)}).$$

Suppose the spin function of the system is given by  $\chi_+^{(e^-)}\chi_-^{(e^+)}$ .

a. Is this an eigenfunction of  $H$  in the limit  $A \rightarrow 0$ ,  $eB/mc \neq 0$ ? If it is, what is the energy eigenvalue? If it is not, what is the expectation value of  $H$ ?

b. Same problem when  $eB/mc \rightarrow 0$ ,  $A \neq 0$ .

We introduce the Dirac spin exchange operator:

$$\hat{P}_{12} = \frac{1}{2}(\hat{1} + \hat{\mathbf{g}}_1 \cdot \hat{\mathbf{g}}_2)$$

or

$$\hat{\mathbf{g}}_1 \cdot \hat{\mathbf{g}}_2 = 2\hat{P}_{12} - \hat{1}$$

The spin Hamiltonian  $\hat{H}$  is given by

$$\hat{H} = A\hat{\mathbf{S}}_1 \cdot \hat{\mathbf{S}}_2 + \frac{eB}{mc}(\hat{S}_{1z} - \hat{S}_{2z}) = \frac{A}{4}\hbar^2\hat{\mathbf{g}}_1 \cdot \hat{\mathbf{g}}_2 + \frac{e\hbar B}{2mc}(\hat{\sigma}_{1z} - \hat{\sigma}_{2z})$$

or

$$\hat{H} = \frac{A}{4}\hbar^2(2\hat{P}_{12} - \hat{1}) + \frac{e\hbar B}{2mc}(\hat{\sigma}_{1z} - \hat{\sigma}_{2z})$$

$$\hat{H}|+-\rangle = \frac{A}{4}\hbar^2(2\hat{P}_{12} - \hat{1})|+-\rangle + \frac{e\hbar B}{2mc}(\hat{\sigma}_{1z} - \hat{\sigma}_{2z})|+-\rangle$$

or

$$\hat{H}|+-\rangle = \frac{A}{4}\hbar^2(2\hat{P}_{12} - \hat{1})|+-\rangle + \frac{e\hbar B}{2mc}(\hat{\sigma}_{1z} - \hat{\sigma}_{2z})|+-\rangle$$

$$\hat{H}|+-\rangle = \frac{A}{4}\hbar^2[2| - + \rangle - | + - \rangle] + \frac{e\hbar B}{mc}| + - \rangle$$

(a)  $A \rightarrow 0$

$$\hat{H}|+-\rangle = \hat{H}|+-\rangle$$

Thus the state  $|+-\rangle$  is the eigenket of  $\hat{H}$  with the eigenvalue  $E = \frac{e\hbar B}{mc}$

(b)  $B = 0$ ,

$$\hat{H}|+-\rangle = \frac{A}{4}\hbar^2[2|-+\rangle - |+-\rangle]$$

Thus the state  $|+-\rangle$  is not the eigenket of  $\hat{H}$ .

$$\langle +-|\hat{H}|+-\rangle = -\frac{A}{4}\hbar^2$$

((3-4))

**4. Consider a spin 1 particle. Evaluate the matrix elements of**

$$S_z(S_z + \hbar)(S_z - \hbar) \quad \text{and} \quad S_x(S_x + \hbar)(S_x - \hbar).$$

$$f(x) = x(x - \hbar)(x + \hbar)$$

$|m\rangle$  and  $|m\rangle_x$  are the eigenkets of  $\hat{S}_z$  and  $\hat{S}_x$  with the eigenvalues  $\hbar m$  ( $m = 1, 0, \text{ and } -1$ ). Note that

$$|m\rangle_x = \hat{U}|m\rangle$$

where  $\hat{U}$  is the unitary operator.

$$f(\hat{S}_z)|m\rangle = f(\hbar m)|m\rangle = 0$$

Thus  $f(\hat{S}_z)$  is the zero operator.

$$f(\hat{S}_x)|m\rangle = \sum_{m'} f(\hat{S}_x)|m'\rangle_x \langle m'|m\rangle = \sum_{m'} f(m'\hbar)|m'\rangle_x \langle m'|m\rangle = \sum_{m'} f(m'\hbar)\hat{U}|m'\rangle \langle m'|\hat{U}^\dagger|m\rangle = 0$$

since  $m' = 1, 0, \text{ and } -1$ . Thus the operator is the zero operator.

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((3-6))

6. Let  $U = e^{iG_3\alpha}e^{iG_2\beta}e^{iG_3\gamma}$ , where  $(\alpha, \beta, \gamma)$  are the Eulerian angles. In order that  $U$  represent a rotation  $(\alpha, \beta, \gamma)$ , what are the commutation rules satisfied by the  $G_k$ ? Relate  $G$  to the angular momentum operators.

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The rotation operator for the Euler angles  $(\alpha, \beta, \gamma)$  is given by

$$\hat{R} = \hat{R}_z(\alpha)\hat{R}_y(\beta)\hat{R}_z(\gamma) = \exp\left(-\frac{i\hat{J}_z\alpha}{\hbar}\right)\exp\left(-\frac{i\hat{J}_y\beta}{\hbar}\right)\exp\left(-\frac{i\hat{J}_z\gamma}{\hbar}\right)$$

When this operator coincides with the unitary operator

$$\hat{U} = \exp(i\hat{G}_3\alpha)\exp(i\hat{G}_2\beta)\exp(i\hat{G}_3\gamma)$$

we find that

$$\hat{G}_i = -\frac{\hat{J}_i}{\hbar}$$

Since  $[\hat{J}_i, \hat{J}_j] = i\hbar\epsilon_{ijk}\hat{J}_k$

$$\hbar^2[\hat{G}_i, \hat{G}_j] = -i\hbar^2\epsilon_{ijk}\hat{G}_k$$

or

$$[\hat{G}_i, \hat{G}_j] = -i\epsilon_{ijk}\hat{G}_k$$

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((3-7))

7. What is the meaning of the following equation:

$$U^{-1}A_kU = \sum R_{kl}A_l,$$

where the three components of  $\mathbf{A}$  are matrices? From this equation show that matrix elements  $\langle m|A_k|n\rangle$  transform like vectors.

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We assume that the state vector changes from the old states  $|n\rangle$  and  $|m\rangle$  to the new states  $|n'\rangle$  and  $|m'\rangle$

$$|n'\rangle = \hat{R}|n\rangle, \quad \text{and} \quad |m'\rangle = \hat{R}|m\rangle$$

or

$$\langle n' | = \hat{R}^+ \langle n |, \quad \text{and} \quad \langle m' | = \hat{R}^+ \langle m |$$

A vector operator  $\hat{A}$  for the system is defined as an operator whose expectation is a vector that rotates together with the physical system.

$$\langle n' | \hat{A}_i | m' \rangle = \langle n | \hat{R}^+ \hat{A}_i \hat{R} | m \rangle = \sum_j \mathfrak{R}_{ij} \langle n | \hat{A}_j | m \rangle$$

thus the matrix elements transform like vectors.

since

$$\hat{R}^+ \hat{A}_i \hat{R} = \sum_j \mathfrak{R}_{ij} \hat{A}_j$$

((3-8))

8. Consider a sequence of Euler rotations represented by

$$\begin{aligned} \mathcal{D}^{(1/2)}(\alpha, \beta, \gamma) &= \exp\left(\frac{-i\sigma_3\alpha}{2}\right) \exp\left(\frac{-i\sigma_2\beta}{2}\right) \exp\left(\frac{-i\sigma_3\gamma}{2}\right) \\ &= \begin{pmatrix} e^{-i(\alpha+\gamma)/2} \cos \frac{\beta}{2} & -e^{-i(\alpha-\gamma)/2} \sin \frac{\beta}{2} \\ e^{i(\alpha-\gamma)/2} \sin \frac{\beta}{2} & e^{i(\alpha+\gamma)/2} \cos \frac{\beta}{2} \end{pmatrix}. \end{aligned}$$

Because of the group properties of rotations, we expect that this sequence of operations is equivalent to a *single* rotation about some axis by an angle  $\theta$ . Find  $\theta$ .

From the Mathematica 5.2

$$\exp\left(-\frac{i}{2} \hat{\mathbf{c}} \cdot \mathbf{n} \theta\right) = \begin{pmatrix} \cos \frac{\theta}{2} - in_z \sin \frac{\theta}{2} & -in_x \sin \frac{\theta}{2} - n_y \sin \frac{\theta}{2} \\ -in_x \sin \frac{\theta}{2} + n_y \sin \frac{\theta}{2} & \cos \frac{\theta}{2} + in_z \sin \frac{\theta}{2} \end{pmatrix}$$

where



$$\hat{\mathbf{g}} \cdot \mathbf{n} = \hat{\sigma}_x n_x + \hat{\sigma}_y n_y + \hat{\sigma}_z n_z$$

$$\exp\left(-\frac{i}{2}\sigma_z\alpha\right)\exp\left(-\frac{i}{2}\sigma_y\beta\right)\exp\left(-\frac{i}{2}\sigma_z\gamma\right) = \begin{pmatrix} e^{-\frac{i(\alpha+\gamma)}{2}} \cos\frac{\beta}{2} & -e^{-\frac{i(\alpha-\gamma)}{2}} \sin\frac{\beta}{2} \\ e^{\frac{i(\alpha-\gamma)}{2}} \sin\frac{\beta}{2} & e^{\frac{i(\alpha+\gamma)}{2}} \cos\frac{\beta}{2} \end{pmatrix}$$

Then we have

$$\cos\frac{\beta}{2}\cos\frac{\alpha+\gamma}{2} = \cos\frac{\theta}{2}$$

$$\cos\frac{\beta}{2}\sin\frac{\alpha+\gamma}{2} = n_z \sin\frac{\theta}{2}$$

$$\sin\frac{\beta}{2}\cos\frac{\alpha-\gamma}{2} = n_y \sin\frac{\theta}{2}$$

$$-\sin\frac{\beta}{2}\sin\frac{\alpha-\gamma}{2} = n_x \sin\frac{\theta}{2}$$

(\*Matrix representation of Rotation operator\*)

$$\sigma_x = \{\{0, 1\}, \{1, 0\}\}$$

$$\{\{0, 1\}, \{1, 0\}\}$$

$$\sigma_y = \{\{0, -i\}, \{i, 0\}\}$$

$$\{\{0, -i\}, \{i, 0\}\}$$

$$\sigma_z = \{\{1, 0\}, \{0, -1\}\}$$

$$\{\{1, 0\}, \{0, -1\}\}$$

$$\mathbf{J}_n = (\sigma_x n_x + \sigma_y n_y + \sigma_z n_z)$$

$$\{\{n_z, n_x - i n_y\}, \{n_x + i n_y, -n_z\}\}$$

$$\mathbf{I}_1 = \mathbf{R} \mathbf{J}_n = \text{MatrixExp}[-i \mathbf{J}_n \theta / 2]$$

$$\left\{ \left\{ -\frac{e^{-\frac{1}{2}\sqrt{-nx^2-ny^2-nz^2}} \theta \left(-i nz - \sqrt{-nx^2-ny^2-nz^2}\right)}{2\sqrt{-nx^2-ny^2-nz^2}} + \frac{e^{\frac{1}{2}\sqrt{-nx^2-ny^2-nz^2}} \theta \left(-i nz + \sqrt{-nx^2-ny^2-nz^2}\right)}{2\sqrt{-nx^2-ny^2-nz^2}} \right. \right. \\
- \frac{e^{-\frac{1}{2}\sqrt{-nx^2-ny^2-nz^2}} \theta \left(-i nx - ny\right)}{2\sqrt{-nx^2-ny^2-nz^2}} + \frac{e^{\frac{1}{2}\sqrt{-nx^2-ny^2-nz^2}} \theta \left(-i nx - ny\right)}{2\sqrt{-nx^2-ny^2-nz^2}} \left. \right\}, \\
\left\{ -\frac{e^{-\frac{1}{2}\sqrt{-nx^2-ny^2-nz^2}} \theta \left(-i nx + ny\right)}{2\sqrt{-nx^2-ny^2-nz^2}} + \frac{e^{\frac{1}{2}\sqrt{-nx^2-ny^2-nz^2}} \theta \left(-i nx + ny\right)}{2\sqrt{-nx^2-ny^2-nz^2}} \right. \\
- \frac{e^{-\frac{1}{2}\sqrt{-nx^2-ny^2-nz^2}} \theta \left(i nz - \sqrt{-nx^2-ny^2-nz^2}\right)}{2\sqrt{-nx^2-ny^2-nz^2}} + \frac{e^{\frac{1}{2}\sqrt{-nx^2-ny^2-nz^2}} \theta \left(i nz + \sqrt{-nx^2-ny^2-nz^2}\right)}{2\sqrt{-nx^2-ny^2-nz^2}} \left. \right\} \}$$

$$\text{Rule1} = \left\{ \sqrt{-nx^2-ny^2-nz^2} \rightarrow i, \frac{1}{\sqrt{-nx^2-ny^2-nz^2}} \rightarrow -i \right\} \\
\left\{ \sqrt{-nx^2-ny^2-nz^2} \rightarrow i, \frac{1}{\sqrt{-nx^2-ny^2-nz^2}} \rightarrow -i \right\}$$

**I2=I1/.Rule1//ExpToTrig**

$$\left\{ \left\{ \text{Cos}\left[\frac{\theta}{2}\right] - i nz \text{Sin}\left[\frac{\theta}{2}\right], -i nx \text{Sin}\left[\frac{\theta}{2}\right] - ny \text{Sin}\left[\frac{\theta}{2}\right] \right\}, \right. \\
\left. \left\{ -i nx \text{Sin}\left[\frac{\theta}{2}\right] + ny \text{Sin}\left[\frac{\theta}{2}\right], \text{Cos}\left[\frac{\theta}{2}\right] + i nz \text{Sin}\left[\frac{\theta}{2}\right] \right\} \right\}$$

**MatrixExp[-i sz alpha/2]. MatrixExp[-i sy beta/2]. MatrixExp[-i sz gamma/2]//Simplify**

$$\left\{ \left\{ e^{-\frac{1}{2} i (\alpha+\gamma)} \cos \left[ \frac{\beta}{2} \right], -e^{-\frac{1}{2} i (\alpha-\gamma)} \sin \left[ \frac{\beta}{2} \right] \right\}, \right. \\ \left. \left\{ e^{\frac{1}{2} i (\alpha-\gamma)} \sin \left[ \frac{\beta}{2} \right], e^{\frac{1}{2} i (\alpha+\gamma)} \cos \left[ \frac{\beta}{2} \right] \right\} \right\}$$

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((3-12))

12. An angular-momentum eigenstate  $|j, m = m_{\max} = j\rangle$  is rotated by an infinitesimal angle  $\varepsilon$  about the  $y$ -axis. Without using the explicit form of the  $d_{m'm}^{(j)}$  function, obtain an expression for the probability for the new rotated state to be found in the original state up to terms of order  $\varepsilon^2$ .

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$$\hat{J}_y = \frac{1}{2i}(\hat{J}_+ - \hat{J}_-)$$

$$\hat{J}_y^2 = -\frac{1}{4}(\hat{J}_+^2 + \hat{J}_-^2 - \hat{J}_+\hat{J}_- - \hat{J}_-\hat{J}_+)$$

$$\langle j, m = j | \hat{J}_y | j, m = j \rangle = 0$$

$$\langle j, m = j | \hat{J}_y^2 | j, m = j \rangle = \frac{1}{4} \langle j, m = j | \hat{J}_+ \hat{J}_- | j, m = j \rangle = \frac{1}{4} (j+j)(j-j+1)\hbar^2 = \frac{1}{2} j\hbar^2$$

The new state after the rotation is

$$|\psi'\rangle = \exp\left(-\frac{i\hat{J}_y}{\hbar}\varepsilon\right)|j, m = j\rangle = \left[1 + \left(-\frac{i\hat{J}_y}{\hbar}\varepsilon\right) + \frac{1}{2!}\left(-\frac{i\hat{J}_y}{\hbar}\varepsilon\right)^2 + \dots\right]|j, m = j\rangle$$

The function

$$d_{m=j, m'=j}^{(j)}(\varepsilon) = \langle j, m = j | \psi' \rangle = \langle j, m = j | \exp\left(-\frac{i\hat{J}_y}{\hbar}\varepsilon\right) | j, m = j \rangle$$

$$= \langle j, m = j | \hat{1} + \left(-\frac{i\hat{J}_y}{\hbar}\varepsilon\right) + \frac{1}{2!}\left(-\frac{i\hat{J}_y}{\hbar}\varepsilon\right)^2 | j, m = j \rangle$$

$$= 1 + \frac{1}{2}\left(\frac{i}{\hbar}\right)^2 \varepsilon^2 \frac{1}{2} j\hbar^2 = 1 - \frac{1}{4} j\varepsilon^2$$

Then the probability  $P(\varepsilon)$  of finding the original state  $|j, m = j\rangle$  in the system is

$$P(\varepsilon) = \left| d_{m=j, m'=j}^{(j)}(\varepsilon) \right|^2 = \left( 1 - \frac{1}{4} j \varepsilon^2 \right)^2 = 1 - \frac{1}{2} j \varepsilon^2$$

((3-13))

13. Show that the  $3 \times 3$  matrices  $G_i$  ( $i = 1, 2, 3$ ) whose elements are given by

$$(G_i)_{jk} = -i\hbar \varepsilon_{ijk},$$

where  $j$  and  $k$  are the row and column indices, satisfy the angular momentum commutation relations. What is the physical (or geometric) significance of the transformation matrix that connects  $G_i$  to the more usual  $3 \times 3$  representations of the angular-momentum operator  $J_i$  with  $J_3$  taken to be diagonal? Relate your result to

$$\mathbf{V} \rightarrow \mathbf{V} + \hat{\mathbf{n}} \delta\phi \times \mathbf{V}$$

under infinitesimal rotations. (*Note:* This problem may be helpful in understanding the photon spin.)

The matrices

$$\hat{G}_1 = -i\hbar \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix}$$

$$\hat{G}_2 = -i\hbar \begin{pmatrix} 0 & 0 & -1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

$$\hat{G}_3 = -i\hbar \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Using Mathematica 5.2, we can show that

$$[\hat{G}_i, \hat{G}_j] = i\hbar \varepsilon_{ijk} \hat{G}_k$$

((Mathematica 5.2))

(\*Sakurai 3-13\*)

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G1=-i ħ {{0,0,0},{0,0,1},{0,-1,0}}
  {{0,0,0},{0,0,-i ħ},{0,i ħ,0}}
G2=-i ħ {{0,0,-1},{0,0,0},{1,0,0}}
  {{0,0,i ħ},{0,0,0},{-i ħ,0,0}}
G3=-i ħ{{0,1,0},{-1,0,0},{0,0,0}}
  {{0,-i ħ,0},{i ħ,0,0},{0,0,0}}
G1//MatrixForm
  ( 0 0 0
    0 0 -i ħ
    0 i ħ 0 )
G2//MatrixForm
  ( 0 0 i ħ
    0 0 0
   -i ħ 0 0 )
G3//MatrixForm
  ( 0 -i ħ 0
    i ħ 0 0
    0 0 0 )
G1.G2-G2.G1-i ħ G3//Simplify
  {{0,0,0},{0,0,0},{0,0,0}}
G2.G3-G3.G2-i ħ G1//Simplify
  {{0,0,0},{0,0,0},{0,0,0}}
G3.G1-G1.G3-i ħ G2//Simplify
  {{0,0,0},{0,0,0},{0,0,0}}
Eigensystem[G3]
  {{0,-ħ,ħ},{0,0,1},{i,1,0},{-i,1,0}}

```

We consider the unitary operator  $\hat{U}$

$$|1\rangle = \hat{U}|\varphi_1\rangle, \quad |1,0\rangle = \hat{U}|\varphi_2\rangle, \quad |-1\rangle = \hat{U}|\varphi_3\rangle$$

where

$$\hat{G}_3|1\rangle = \hbar|1\rangle$$

$$\hat{G}_3|0\rangle = 0$$

$$\hat{G}_3|-1\rangle = -\hbar|-1\rangle$$

or

$|1\rangle, |0\rangle, |-1\rangle$  are the eigenkets of  $\hat{G}_3$ .

Then we have

$$\hat{U}^+ \hat{G}_3 \hat{U} |\varphi_1\rangle = \hbar |\varphi_1\rangle$$

$$\hat{U}^+ \hat{G}_3 \hat{U} |\varphi_0\rangle = 0$$

$$\hat{U}^+ \hat{G}_3 \hat{U} |\varphi_{-1}\rangle = -\hbar |\varphi_{-1}\rangle$$

where

$$\hat{U} = \begin{pmatrix} \frac{1}{\sqrt{2}} & \frac{1}{\sqrt{2}} & 0 \\ \frac{i}{\sqrt{2}} & -\frac{i}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

$$\hat{U}^+ \hat{G}_3 \hat{U} = \hbar \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

under the basis of  $|\varphi_i\rangle$

$$\hat{G}_3 |1\rangle = \hbar |1\rangle$$

$$\hat{G}_3 |0\rangle = 0$$

$$\hat{G}_3 |-1\rangle = -\hbar |-1\rangle$$

$$\hat{G}_3 = \hbar \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

under the basis of  $|1\rangle, |0\rangle, |-1\rangle$

We consider the rotation operator  $\hat{R}$

$$|\psi'\rangle = \hat{R} |\psi\rangle$$

$$\hat{R}_3(\varepsilon) = \exp\left(-\frac{i}{\hbar} \varepsilon \hat{G}_3\right)$$

$$\hat{U}^+ \hat{R}_3(\varepsilon) \hat{U} = \exp\left[-\frac{i}{\hbar} \varepsilon \hat{U}^+ \hat{G}_3(\varepsilon) \hat{U}\right] = \begin{pmatrix} e^{-i\varepsilon} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & e^{i\varepsilon} \end{pmatrix} = \begin{pmatrix} 1-i\varepsilon & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1+i\varepsilon \end{pmatrix}$$

$$\hat{R}_3(\varepsilon) = \hat{U} \begin{pmatrix} 1-i\varepsilon & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1+i\varepsilon \end{pmatrix} \hat{U}^+ = \begin{pmatrix} 1 & -\varepsilon & 0 \\ \varepsilon & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} =$$

$$|\varphi_1'\rangle = \hat{R}_3(\varepsilon)|\varphi_1\rangle = \begin{pmatrix} 1 & -\varepsilon & 0 \\ \varepsilon & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ \varepsilon \\ 0 \end{pmatrix} = |\varphi_1\rangle + \varepsilon|\varphi_2\rangle$$

$$|\varphi_2'\rangle = \hat{R}_3(\varepsilon)|\varphi_2\rangle = \begin{pmatrix} 1 & -\varepsilon & 0 \\ \varepsilon & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix} = \begin{pmatrix} -\varepsilon \\ 1 \\ 0 \end{pmatrix} = -\varepsilon|\varphi_1\rangle + |\varphi_2\rangle$$

$$|\varphi_3'\rangle = \hat{R}_3(\varepsilon)|\varphi_3\rangle = \begin{pmatrix} 1 & -\varepsilon & 0 \\ \varepsilon & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix} = |\varphi_3\rangle$$

These relations are similar to the rotation of vectors around the z axis by angle  $\varepsilon$ .

$$\mathbf{V} \rightarrow \mathbf{V}' = \mathbf{V} + \varepsilon \mathbf{n} \times \mathbf{V}$$

$$\begin{pmatrix} V_x' \\ V_y'' \\ V_z \end{pmatrix} = \begin{pmatrix} 1 & -\varepsilon & 0 \\ \varepsilon & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix} \begin{pmatrix} V_x \\ V_y \\ V_z \end{pmatrix}$$

$$\mathbf{n} \times \mathbf{V} = \begin{vmatrix} \mathbf{e}_x & \mathbf{e}_y & \mathbf{e}_z \\ 0 & 0 & 1 \\ V_x & V_y & V_z \end{vmatrix} = (-V_y, V_x, 0) = \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \begin{pmatrix} V_x \\ V_y \\ V_z \end{pmatrix}$$

14. a. Let  $\mathbf{J}$  be angular momentum. It may stand for orbital  $\mathbf{L}$ , spin  $\mathbf{S}$ , or  $\mathbf{J}_{\text{total}}$ . Using the fact that  $J_x, J_y, J_z$  ( $J_{\pm} \equiv J_x \pm iJ_y$ ) satisfy the usual angular-momentum commutation relations, prove

$$\mathbf{J}^2 = J_z^2 + J_+ J_- - \hbar J_z.$$

- b. Using (a) (or otherwise), derive the “famous” expression for the coefficient  $c_-$  that appears in

$$J_- \psi_{jm} = c_- \psi_{j, m-1}.$$

(a)

$$\hat{J}_{\pm} = \hat{J}_x \pm i\hat{J}_y$$

$$\hat{J}_+ \hat{J}_- = (\hat{J}_x + i\hat{J}_y)(\hat{J}_x - i\hat{J}_y) = \hat{J}_x^2 + \hat{J}_y^2 - i[\hat{J}_x, \hat{J}_y]$$

$$\text{Since } [\hat{J}_x, \hat{J}_y] = i\hbar\hat{J}_z$$

$$\hat{J}_+ \hat{J}_- = \hat{J}_x^2 + \hat{J}_y^2 + \hbar\hat{J}_z = \hat{\mathbf{J}}^2 - \hat{J}_z^2 + \hbar\hat{J}_z$$

or

$$\hat{\mathbf{J}}^2 = \hat{J}_z^2 + \hat{J}_+ \hat{J}_- - \hbar\hat{J}_z$$

(b)

$$\hat{\mathbf{J}}^2 |j, m\rangle = \hat{J}_z^2 |j, m\rangle + \hat{J}_+ \hat{J}_- |j, m\rangle - \hbar\hat{J}_z |j, m\rangle$$

$$\hbar^2 j(j+1) |j, m\rangle = m^2 \hbar^2 |j, m\rangle + \hat{J}_+ \hat{J}_- |j, m\rangle - m\hbar^2 |j, m\rangle$$

or

$$\langle j, m | \hat{J}_+ \hat{J}_- |j, m\rangle = \hbar^2 [j(j+1) - m^2 + m]$$

We assume that

$$\hat{J}_- |j, m\rangle = c_- |j, m-1\rangle$$

or

$$\langle j, m | \hat{J}_+ = c_-^* \langle j, m-1 |$$



From these we have

$$|c_-| = \hbar \sqrt{j(j+1) - m^2 + m}$$

When we choose a real  $c_-$  then we have

$$c_- = \hbar \sqrt{j(j+1) - m^2 + m} = \sqrt{(j+m)(j-m+1)}$$

**((3-15))**

15. The wave function of a particle subjected to a spherically symmetrical potential  $V(r)$  is given by

$$\psi(\mathbf{x}) = (x + y + 3z)f(r).$$

- Is  $\psi$  an eigenfunction of  $\mathbf{L}^2$ ? If so, what is the  $l$ -value? If not, what are the possible values of  $l$  we may obtain when  $\mathbf{L}^2$  is measured?
- What are the probabilities for the particle to be found in various  $m_l$  states?
- Suppose it is known somehow that  $\psi(\mathbf{x})$  is an energy eigenfunction with eigenvalue  $E$ . Indicate how we may find  $V(r)$ .

(a)

$$\psi(\mathbf{r}) = (x + y + 3z)f(r)$$

$$\frac{x}{r} = \sqrt{\frac{2\pi}{3}} [Y_1^{-1}(\theta, \phi) - Y_1^1(\theta, \phi)]$$

$$\frac{y}{r} = i \sqrt{\frac{2\pi}{3}} [Y_1^1(\theta, \phi) + Y_1^{-1}(\theta, \phi)]$$

$$\frac{z}{r} = \sqrt{\frac{4\pi}{3}} Y_1^0(\theta, \phi)$$

$$\frac{x + y + 3z}{r} = \sqrt{\frac{2\pi}{3}} [(1+i)Y_1^{-1}(\theta, \phi) - (1-i)Y_1^1(\theta, \phi) + 3\sqrt{2}Y_1^0(\theta, \phi)]$$

$$\psi(x, y, z) = \sqrt{\frac{2\pi}{3}} [(1+i)Y_1^{-1}(\theta, \phi) - (1-i)Y_1^1(\theta, \phi) + 3\sqrt{2}Y_1^0(\theta, \phi)] r f(r)$$

$$|\psi\rangle = \frac{1}{\sqrt{11}} \left[ -\frac{(1-i)}{\sqrt{2}} |1,1\rangle + 3|1,0\rangle + \frac{(1+i)}{\sqrt{2}} |1,-1\rangle \right]$$

(b)

$$P(l=1, m=1) = \frac{1}{11},$$

$$P(l=1, m=0) = \frac{9}{11},$$

$$P(l=1, m=-1) = \frac{1}{22},$$

(c)

Schrödinger equation

$$H = -\frac{\hbar^2}{2m}\nabla^2 + V(r) = \frac{1}{2m}(p_r^2 + \frac{\mathbf{L}^2}{r^2})$$

$$p_r = \frac{\hbar}{i} \frac{1}{r} \frac{\partial}{\partial r} r$$

$$\left[ -\frac{\hbar^2}{2m} \frac{1}{r} \frac{\partial}{\partial r} \left( \frac{\partial}{\partial r} r \right) + \frac{\hbar^2 l(l+1)}{2mr^2} + V(r) \right] r f(r) = E r f(r)$$

with  $l=1$ .

Then we have

$$V(r) = E + \frac{\hbar^2}{2m} \left( \frac{r f''(r) + 4 f'(r)}{r f(r)} \right)$$

$$\hat{L}_x = \frac{1}{2}(\hat{L}_+ + \hat{L}_-)$$

$$\hat{L}_x = \frac{1}{2i}(\hat{L}_+ - \hat{L}_-)$$

$$\hat{L}_x^2 = \frac{1}{4}(\hat{L}_+ + \hat{L}_-)(\hat{L}_+ + \hat{L}_-) = \frac{1}{4}(\hat{L}_+^2 + \hat{L}_-^2 + \hat{L}_+ \hat{L}_- + \hat{L}_- \hat{L}_+)$$

$$\hat{L}_x^2 = \frac{1}{4}(\hat{L}_+ + \hat{L}_-)(\hat{L}_+ + \hat{L}_-) = \frac{1}{4}(\hat{L}_+^2 + \hat{L}_-^2 + \hat{L}_+ \hat{L}_- + \hat{L}_- \hat{L}_+)$$

$$\hat{L}_+ |lm\rangle = \hbar \sqrt{(l-m)(l+m+1)} |l, m-1\rangle$$

$$\langle lm | \hat{L}_- \hat{L}_+ | lm \rangle = \hbar^2 (l - m)(l + m + 1)$$

$$\hat{L}_- | lm \rangle = \hbar \sqrt{(l + m)(l - m + 1)} | l, m - 1 \rangle$$

$$\langle lm | \hat{L}_+ \hat{L}_- | lm \rangle = \hbar^2 (l + m)(l - m + 1)$$

$$\langle lm | \hat{L}_z | lm \rangle = m\hbar$$

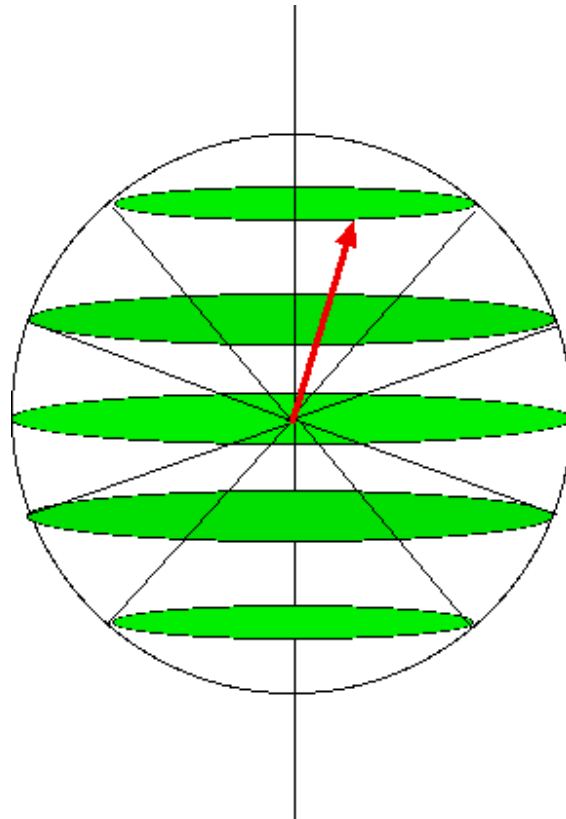
$$\langle lm | \hat{L}_x | lm \rangle = \langle lm | \hat{L}_y | lm \rangle = 0$$

$$\langle lm | \hat{L}_x^2 | lm \rangle = \langle lm | \hat{L}_y^2 | lm \rangle = \frac{1}{4} \langle lm | \hat{L}_+ \hat{L}_- + \hat{L}_- \hat{L}_+ | lm \rangle = \frac{1}{4} \langle lm | \hat{L}_+ \hat{L}_- | lm \rangle + \frac{1}{4} \langle lm | \hat{L}_- \hat{L}_+ | lm \rangle$$

or

$$\langle lm | \hat{L}_x^2 | lm \rangle = \langle lm | \hat{L}_y^2 | lm \rangle = \frac{\hbar^2}{2} [l(l + 1) - m^2]$$

Consequently, the angular momentum of a particle in the state  $|l, m\rangle$  behaves, in so far as the mean values of its components and their squares are concerned, like a classical angular momentum of magnitude  $\hbar\sqrt{l(l + 1)}$  having a projection  $m\hbar$  along the z axis, but the angle  $\phi$  is a random variable evenly distributed between 0 and  $2\pi$ .




---

((3-17))

17. Suppose a half-integer  $l$ -value, say  $\frac{1}{2}$ , were allowed for orbital angular momentum. From

$$L_+ Y_{1/2, 1/2}(\theta, \phi) = 0,$$

we may deduce, as usual,

$$Y_{1/2, 1/2}(\theta, \phi) \propto e^{i\phi/2} \sqrt{\sin \theta}.$$

Now try to construct  $Y_{1/2, -1/2}(\theta, \phi)$ ; by (a) applying  $L_-$  to  $Y_{1/2, 1/2}(\theta, \phi)$ ; and (b) using  $L_- Y_{1/2, -1/2}(\theta, \phi) = 0$ . Show that the two procedures lead to contradictory results. (This gives an argument against half-integer  $l$ -values for orbital angular momentum.)

---

Let us suppose  $Y_l^m(\theta, \phi)$  with a half-integer  $l$  were possible. We choose the simplest case ( $l = 1/2$ ).

From the definition,

$$L_+ Y_{1/2}^{1/2} = \hbar e^{i\phi} \left( \frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \phi} \right) e^{i\phi/2} \Theta_{1/2,1/2}(\theta) = 0$$

From this equation, we have

$$\frac{d\Theta_{1/2,1/2}(\theta)}{d\theta} = \frac{1}{2} \cot \theta \Theta_{1/2,1/2}(\theta)$$

or

$$\Theta_{1/2,1/2}(\theta) = C_1 \sqrt{\sin \theta}$$

or

$$Y_{1/2}^{1/2}(\theta, \phi) = C_2 e^{i\phi/2} \sqrt{\sin \theta}$$

This expression is not permissible because it is singular at  $\theta = 0$  and  $\pi$ .

(a)

From the property of  $L_-$

$$L_- Y_{1/2}^{1/2} = \hbar e^{-i\phi} \left( -\frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \phi} \right) C_2 e^{i\phi/2} \sqrt{\sin \theta}$$

or

$$L_- Y_{1/2}^{1/2} \propto Y_{1/2}^{-1/2} = C_3 \frac{e^{-i\phi/2}}{\sqrt{\sin \theta}} \cos \theta \quad (1)$$

(b)

$$L_- Y_{1/2}^{-1/2} = \hbar e^{-i\phi} \left( -\frac{\partial}{\partial \theta} + i \cot \theta \frac{\partial}{\partial \phi} \right) e^{-i\phi/2} \Theta_{1/2,-1/2}(\theta) = 0$$

From this we have

$$\frac{d\Theta_{1/2,-1/2}(\theta)}{d\theta} = \frac{1}{2} \cot \theta \Theta_{1/2,-1/2}(\theta)$$

or

$$Y_{1/2}^{-1/2}(\theta, \phi) = C_4 e^{-i\phi/2} \sqrt{\sin \theta}, \quad (2)$$

Thus the two procedures lead to contradictory results.

(\*Sakurai 3-17

We define the ladder operators

\*)

$$\text{OGD} := \text{Exp}[-i\phi] (-D[\#, \theta] + i \text{Cot}[\theta] D[\#, \phi]) \&$$

$$\text{OGU} := \text{Exp}[i\phi] (D[\#, \theta] + i \text{Cot}[\theta] D[\#, \phi]) \&$$

$$\text{eq1} = \text{OGU} \left[ \text{Exp} \left[ i \frac{\phi}{2} \right] X[\theta] \right]$$

$$e^{i\phi} \left( -\frac{1}{2} e^{\frac{i\phi}{2}} \text{Cot}[\theta] X[\theta] + e^{\frac{i\phi}{2}} X'[\theta] \right)$$

$$\text{DSolve}[\text{eq1}==0, X[\theta], \theta]$$

$$\left\{ \left\{ X[\theta] \rightarrow C[1] \sqrt{\text{Sin}[\theta]} \right\} \right\}$$

$$\text{OGD} \left[ \text{Exp} \left[ i \frac{\phi}{2} \right] \sqrt{\text{Sin}[\theta]} \right]$$

$$\frac{e^{-\frac{i\phi}{2}} \text{Cos}[\theta]}{\sqrt{\text{Sin}[\theta]}}$$

$$\text{eq2} = \text{OGD} \left[ \text{Exp} \left[ -i \frac{\phi}{2} \right] Y[\theta] \right] // \text{Simplify}$$

$$\frac{1}{2} e^{-\frac{3i\phi}{2}} (\text{Cot}[\theta] Y[\theta] - 2 Y'[\theta])$$

$$\text{DSolve}[\text{eq2}==0, Y[\theta], \theta]$$

$$\left\{ \left\{ Y[\theta] \rightarrow C[1] \sqrt{\text{Sin}[\theta]} \right\} \right\}$$

((3-18))

18. Consider an orbital angular-momentum eigenstate  $|l=2, m=0\rangle$ . Suppose this state is rotated by an angle  $\beta$  about the  $y$ -axis. Find the probability for the new state to be found in  $m=0, \pm 1$ , and  $\pm 2$ . (The spherical harmonics for  $l=0, 1$ , and  $2$  given in Appendix A may be useful.)

$$\hat{R} = Y_{l=2}^0(\theta=0, \phi) \hat{R}_y(\theta)$$

$$|\psi'\rangle = \hat{R}_z(\phi) \hat{R}_y(\theta) |l=2, m=0\rangle$$

$$\langle l=2, m|\psi'\rangle = \langle l=2, m|\hat{R}_z(\phi) \hat{R}_y(\theta) |l=2, m=0\rangle$$

From the Note-1 we have

$$[Y_{l=2}^m(\theta, \phi)]^* = \langle l=2, m | \hat{R}_z(\phi) \hat{R}_y(\theta) | l=2, 0 \rangle Y_{l=2}^0(\theta=0, \phi)$$

$$Y_{l=2}^0(\theta=0, \phi) = \sqrt{\frac{5}{4\pi}} \quad (\text{which is independent of } \phi)$$

Thus we have

$$\langle l=2, m | \hat{R}_z(\phi) \hat{R}_y(\theta) | l=2, 0 \rangle = \frac{[Y_{l=2}^m(\theta, \phi)]^*}{Y_{l=2}^0(\theta=0, \phi)} = \sqrt{\frac{4\pi}{5}} [Y_{l=2}^m(\theta, \phi)]^*$$

We consider the case of  $\phi = 0$ .

$$\langle l=2, m | \hat{R}_y(\theta) | l=2, 0 \rangle = \sqrt{\frac{4\pi}{5}} [Y_{l=2}^m(\theta, \phi=0)]^*$$

The probability of finding the state  $|l=2, m\rangle : P(m)$

$$P(m=0) = \frac{4\pi}{5} |Y_2^0(\theta, 0)|^2 = \frac{1}{4} (3\cos^2 \theta - 1)^2$$

$$P(m=\pm 1) = \frac{4\pi}{5} |Y_2^{\pm 1}(\theta, 0)|^2 = \frac{3}{2} \sin^2 \theta \cos^2 \theta$$

$$P(m=\pm 2) = \frac{4\pi}{5} |Y_2^{\pm 2}(\theta, 0)|^2 = \frac{3}{8} \sin^4 \theta$$

((Note-1))

$$|\mathbf{n}\rangle = |\mathfrak{R}\mathbf{e}_z\rangle = \hat{R}_z(\phi) \hat{R}_y(\theta) |\mathbf{e}_z\rangle$$

$$= \sum_{m'} \hat{R}_z(\phi) \hat{R}_y(\theta) |lm'\rangle \langle lm' | \mathbf{e}_z \rangle$$

$$\langle lm | \mathbf{n} \rangle = \sum_{m'} \langle lm | \hat{R}_z(\phi) \hat{R}_y(\theta) | lm' \rangle \langle lm' | \mathbf{e}_z \rangle = \sum_{m'} \langle lm | \hat{R}_z(\phi) \hat{R}_y(\theta) | lm' \rangle \delta_{m',0} Y_l^0(\theta=0, \phi)$$

$$[Y_l^m(\theta, \phi)]^* = \langle lm | \hat{R}_z(\phi) \hat{R}_y(\theta) | l0 \rangle Y_l^0(\theta=0, \phi)$$

where

$$\langle \mathbf{n} | lm \rangle = Y_\ell^m(\mathbf{n}) = Y_\ell^m(\theta, \phi)$$

and

$$\langle \mathbf{e}_z | lm \rangle = Y_\ell^m(\mathbf{e}_z) = \delta_{m,0} Y_\ell^0(\theta = 0, \phi) \text{ with } \phi \text{ undetermined}$$

((Note-2)) Mathematica 5.2

`Table[{m, SphericalHarmonicY[2, m, \theta, \phi]}, {m, -2, 2, 1}] // TableForm`

$$\begin{array}{r} -2 \\ -1 \\ 0 \\ 1 \\ 2 \end{array} \quad \begin{array}{l} \frac{1}{4} e^{-2i\phi} \sqrt{\frac{15}{2\pi}} \sin^2[\theta] \\ \frac{1}{2} e^{-i\phi} \sqrt{\frac{15}{2\pi}} \cos[\theta] \sin[\theta] \\ \frac{1}{4} \sqrt{\frac{5}{\pi}} (-1 + 3 \cos^2[\theta]) \\ -\frac{1}{2} e^{i\phi} \sqrt{\frac{15}{2\pi}} \cos[\theta] \sin[\theta] \\ \frac{1}{4} e^{2i\phi} \sqrt{\frac{15}{2\pi}} \sin^2[\theta] \end{array}$$

$$P[0] = \frac{1}{4} (-1 + 3 \cos^2[\theta])^2$$

$$\frac{1}{4} (-1 + 3 \cos^2[\theta])^2$$

$$P[1] = \frac{3}{2} \sin^2[\theta] \cos^2[\theta]$$

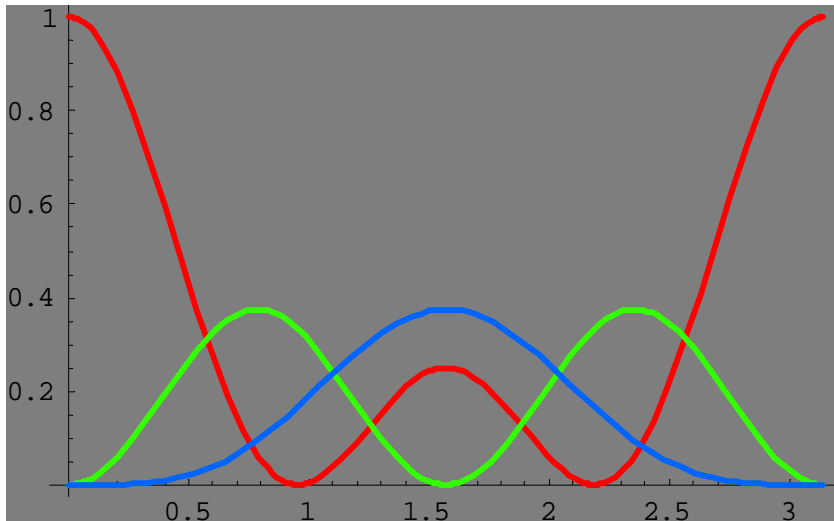
$$\frac{3}{2} \cos^2[\theta] \sin^2[\theta]$$

$$P[2] = \frac{3}{8} \sin^4[\theta]$$

$$\frac{3 \sin^4[\theta]}{8}$$

`Plot[Evaluate[{P[0], P[1], P[2]}], {\theta, 0, \pi}, PlotStyle -> Table[Hue[0.3 i], {i, 0, 3}], Prolog -> AbsoluteThickness[2], Background -> GrayLevel[0.5]]`





-Graphics-

((3-20))

20. We are to add angular momenta  $j_1 = 1$  and  $j_2 = 1$  to form  $j = 2, 1,$  and  $0$  states. Using either the ladder operator method or the recursion relation, express all (nine)  $\{j, m\}$  eigenkets in terms of  $|j_1 j_2; m_1 m_2\rangle$ . Write your answer as

$$|j = 1, m = 1\rangle = \frac{1}{\sqrt{2}}|+, 0\rangle - \frac{1}{\sqrt{2}}|0, +\rangle, \dots,$$

where  $+$  and  $0$  stand for  $m_{1,2} = 1, 0$ , respectively.

We use the relation by Clebsch-Gordan.

$$j_1 = 1, j_2 = 1 \quad (|m_1| \leq 1, |m_2| \leq 1)$$

$$D_1 \times D_1 = D_2 + D_1 + D_0$$

(i)  $j = 2$  ( $|m| \leq 2$ )

$$m = m_1 + m_2$$

$$|1, 1\rangle|1, 1\rangle \quad (m = 2)$$

$$\frac{|1, 1\rangle|1, 0\rangle + |1, 0\rangle|1, 1\rangle}{\sqrt{2}} \quad (m = 1)$$

$$\frac{|1,1\rangle|1,-1\rangle + 2|1,0\rangle|1,0\rangle + |1,-1\rangle|1,1\rangle}{\sqrt{6}} \quad (m=0)$$

$$\frac{|1,1\rangle|1,-1\rangle + |1,-1\rangle|1,0\rangle}{\sqrt{2}} \quad (m=-1)$$

$$|1,-1\rangle|1,-1\rangle \quad (m=-2)$$

(ii)  $j=1$  ( $|m| \leq 1$ )

$$\frac{|1,1\rangle|1,0\rangle - |1,0\rangle|1,1\rangle}{\sqrt{2}} \quad (m=1)$$

$$\frac{|1,1\rangle|1,-1\rangle - |1,-1\rangle|1,1\rangle}{\sqrt{2}} \quad (m=0)$$

$$\frac{|1,0\rangle|1,-1\rangle - |1,-1\rangle|1,0\rangle}{\sqrt{2}} \quad (m=-1)$$

(iii)  $j=0$  ( $m=0$ )

$$\frac{|1,1\rangle|1,-1\rangle - |1,0\rangle|1,0\rangle + |1,-1\rangle|1,1\rangle}{\sqrt{3}}$$

((Mathematica 5.2))

(\*Determination of CG co-efficient

\*)

(\* j1=1/2, j2=1/2\*)

```
CG[j1_, j2_, j_] := Table[Sum[ClebschGordan[{j1, k1}, {j2, k2}, {j, k1+k2}], a[j1, k1] b[j2, k2] KroneckerDelta[k1+k2, m], {k1, -j1, j1}, {k2, -j2, j2}], {m, -j, j}]
```

```
CG[1/2, 1/2, 1] // TableForm
```

$$a\left[\frac{1}{2}, -\frac{1}{2}\right] b\left[\frac{1}{2}, -\frac{1}{2}\right]$$

$$\frac{a\left[\frac{1}{2}, \frac{1}{2}\right] b\left[\frac{1}{2}, -\frac{1}{2}\right]}{\sqrt{2}} + \frac{a\left[\frac{1}{2}, -\frac{1}{2}\right] b\left[\frac{1}{2}, \frac{1}{2}\right]}{\sqrt{2}}$$

$$a\left[\frac{1}{2}, \frac{1}{2}\right] b\left[\frac{1}{2}, \frac{1}{2}\right]$$

```
CG[1/2, 1/2, 0] // TableForm
```

$$\frac{a\left[\frac{1}{2}, \frac{1}{2}\right] b\left[\frac{1}{2}, -\frac{1}{2}\right]}{\sqrt{2}} - \frac{a\left[\frac{1}{2}, -\frac{1}{2}\right] b\left[\frac{1}{2}, \frac{1}{2}\right]}{\sqrt{2}}$$

(\*j1=1, j2=1\*)

```
CG[1, 1, 2] // TableForm
```

$$\begin{aligned}
& a[1, -1] b[1, -1] \\
& \frac{a[1,0] b[1,-1]}{\sqrt{2}} + \frac{a[1,-1] b[1,0]}{\sqrt{2}} \\
& \frac{a[1,1] b[1,-1]}{\sqrt{6}} + \sqrt{\frac{2}{3}} a[1, 0] b[1, 0] + \frac{a[1,-1] b[1,1]}{\sqrt{6}} \\
& \frac{a[1,1] b[1,0]}{\sqrt{2}} + \frac{a[1,0] b[1,1]}{\sqrt{2}} \\
& a[1, 1] b[1, 1] \\
\mathbf{CG[1,1,1]//TableForm} \\
& \frac{a[1,0] b[1,-1]}{\sqrt{2}} - \frac{a[1,-1] b[1,0]}{\sqrt{2}} \\
& \frac{a[1,1] b[1,-1]}{\sqrt{2}} - \frac{a[1,-1] b[1,1]}{\sqrt{2}} \\
& \frac{a[1,1] b[1,0]}{\sqrt{2}} - \frac{a[1,0] b[1,1]}{\sqrt{2}} \\
\mathbf{CG[1,1,0]//TableForm} \\
& \frac{a[1,1] b[1,-1]}{\sqrt{3}} - \frac{a[1,0] b[1,0]}{\sqrt{3}} + \frac{a[1,-1] b[1,1]}{\sqrt{3}}
\end{aligned}$$

**((3-21))**

21. a. Evaluate

$$\sum_{m=-j}^j |d_{mm}^{(j)}(\beta)|^2 m$$

for *any*  $j$  (integer or half-integer); then check your answer for  $j = \frac{1}{2}$ .

b. Prove, for any  $j$ ,

$$\sum_{m=-j}^j m^2 |d_{m'm}^{(j)}(\beta)|^2 = \frac{1}{2} j(j+1) \sin^2 \beta + m'^2 \frac{1}{2} (3 \cos^2 \beta - 1).$$

[*Hint:* This can be proved in many ways. You may, for instance, examine the rotational properties of  $J_z^2$  using the spherical (irreducible) tensor language.]

(a) For any  $j$ ,

$$\sum_{m=-j}^j m |d_{m'm}^{(j)}(\beta)|^2 = \sum_{m=-j}^j m d_{m'm}^{(j)*}(\beta) d_{m'm}^{(j)}(\beta)$$

$$\begin{aligned}
&= \sum_{m=-j}^j \langle j, m' | \exp(\frac{i\hat{J}_y\beta}{\hbar}) | j, m \rangle m \langle j, m | \exp(-\frac{i\hat{J}_y\beta}{\hbar}) | j, m' \rangle \\
&= \frac{1}{\hbar} \sum_{m=-j}^j \langle j, m' | \exp(\frac{i\hat{J}_y\beta}{\hbar}) \hat{J}_z | j, m \rangle \langle j, m | \exp(-\frac{i\hat{J}_y\beta}{\hbar}) | j, m' \rangle \\
&= \frac{1}{\hbar} \langle j, m' | \exp(\frac{i\hat{J}_y\beta}{\hbar}) \hat{J}_z \exp(-\frac{i\hat{J}_y\beta}{\hbar}) | j, m' \rangle
\end{aligned}$$

(closure relation)

$$\sum_{m=-j}^j m |d_{m,m'}^{(j)}(\beta)|^2 = \frac{1}{\hbar} \langle j, m' | \hat{J}_z \cos \beta - \hat{J}_x \sin \beta | j, m' \rangle = m' \cos \beta$$

Note that

$$\langle j, m' | \hat{J}_z | j, m' \rangle = m', \quad \langle j, m' | \hat{J}_x | j, m' \rangle = 0$$

since  $\hat{J}_x = \frac{1}{2}(\hat{J}_+ + \hat{J}_-)$  and  $\langle j, m' | \hat{J}_\pm | j, m' \rangle = 0$

((Note))

The proof of the formula  $\hat{I} = \exp(\frac{i\hat{J}_y\beta}{\hbar}) \hat{J}_z \exp(-\frac{i\hat{J}_y\beta}{\hbar}) = \hat{J}_z \cos \beta - \hat{J}_x \sin \beta$

We use the relation

$$\exp(x\hat{A})\hat{B}\exp(-x\hat{A}) = \hat{B} + \frac{x}{1!}[\hat{A}, \hat{B}] + \frac{x^2}{2!}[\hat{A}, [\hat{A}, \hat{B}]] + \frac{x^3}{3!}[\hat{A}, [\hat{A}, [\hat{A}, \hat{B}]]] + \dots$$

where  $x = \frac{i\beta}{\hbar}$ ,  $\hat{A} = \hat{J}_y$ , and  $\hat{B} = \hat{J}_z$ .

Then we have

$$\hat{I} = \exp(\frac{i\hat{J}_y\beta}{\hbar}) \hat{J}_z \exp(-\frac{i\hat{J}_y\beta}{\hbar}) = \hat{J}_z + \frac{1}{1!} \frac{i\beta}{\hbar} [\hat{J}_y, \hat{J}_z] + \frac{1}{2!} \left(\frac{i\beta}{\hbar}\right)^2 [\hat{J}_y, [\hat{J}_y, \hat{J}_z]] + \dots$$

$$\begin{aligned}
&= \hat{J}_z + \frac{1}{1!} \frac{i\beta}{\hbar} [\hat{J}_y, \hat{J}_z] + \frac{1}{2!} \left( \frac{i\beta}{\hbar} \right)^2 [\hat{J}_y, [\hat{J}_y, \hat{J}_z]] + \frac{1}{3!} \left( \frac{i\beta}{\hbar} \right)^3 [\hat{J}_y, [\hat{J}_y, [\hat{J}_y, \hat{J}_z]]] + \dots \\
&= \hat{J}_z \left[ 1 - \frac{1}{2} (\beta)^2 + \dots \right] - \hat{J}_x \left[ \beta - \frac{1}{3!} \left( \frac{\beta}{\hbar} \right)^3 + \dots \right] = \hat{J}_z \cos \phi - \hat{J}_x \sin \beta
\end{aligned}$$

(b)

$$\begin{aligned}
\sum_{m=-j}^j m^2 \left| d_{m,m'}^{(j)}(\beta) \right|^2 &= \sum_{m=-j}^j m^2 d_{m,m'}^{(j)*}(\beta) d_{m,m'}^{(j)}(\beta) \\
&= \sum_{m=-j}^j \langle j, m' | \exp\left(\frac{i\hat{J}_y \beta}{\hbar}\right) | j, m \rangle m^2 \langle j, m | \exp\left(-\frac{i\hat{J}_y \beta}{\hbar}\right) | j, m' \rangle \\
&= \frac{1}{\hbar^2} \sum_{m=-j}^j \langle j, m' | \exp\left(\frac{i\hat{J}_y \beta}{\hbar}\right) \hat{J}_z^2 | j, m \rangle \langle j, m | \exp\left(-\frac{i\hat{J}_y \beta}{\hbar}\right) | j, m' \rangle \\
&= \frac{1}{\hbar^2} \langle j, m' | \exp\left(\frac{i\hat{J}_y \beta}{\hbar}\right) \hat{J}_z^2 \exp\left(-\frac{i\hat{J}_y \beta}{\hbar}\right) | j, m' \rangle \\
&= \frac{1}{\hbar^2} \langle j, m' | \exp\left(\frac{i\hat{J}_y \beta}{\hbar}\right) \hat{J}_z \exp\left(-\frac{i\hat{J}_y \beta}{\hbar}\right) \exp\left(\frac{i\hat{J}_y \beta}{\hbar}\right) \hat{J}_z \exp\left(-\frac{i\hat{J}_y \beta}{\hbar}\right) | j, m' \rangle \\
&= \frac{1}{\hbar^2} \langle j, m' | \left[ \exp\left(\frac{i\hat{J}_y \beta}{\hbar}\right) \hat{J}_z \exp\left(-\frac{i\hat{J}_y \beta}{\hbar}\right) \right]^2 | j, m' \rangle \\
&= \frac{1}{\hbar^2} \langle j, m' | [\hat{J}_z \cos \beta - \hat{J}_x \sin \beta]^2 | j, m' \rangle \\
&= \frac{1}{\hbar^2} \langle j, m' | [\hat{J}_z^2 \cos^2 \beta + \hat{J}_x^2 \sin^2 \beta - \sin \beta \cos \beta (\hat{J}_x \hat{J}_z + \hat{J}_z \hat{J}_x)] | j, m' \rangle \\
&= m^2 \cos^2 \beta + \frac{1}{2} [j(j+1) - m^2] \sin^2 \beta
\end{aligned}$$

Since

$$\hat{J}_x \hat{J}_z + \hat{J}_z \hat{J}_x = \frac{1}{2}(\hat{J}_+ + \hat{J}_-)\hat{J}_z + \hat{J}_z(\hat{J}_+ + \hat{J}_-)$$

$$\langle j, m' | \hat{J}_x \hat{J}_z + \hat{J}_z \hat{J}_x | j, m' \rangle = 0.$$

$$\langle j, m' | \hat{J}_x^2 | j, m' \rangle = \langle j, m' | \hat{J}_x^2 | j, m' \rangle = \frac{1}{4} \langle j, m' | \hat{J}_+ \hat{J}_- + \hat{J}_- \hat{J}_+ | j, m' \rangle = \frac{1}{2} \hbar^2 [j(j+1) - m'^2]$$

((3-22))

22. a. Consider a system with  $j=1$ . Explicitly write

$$\langle j=1, m' | J_y | j=1, m \rangle$$

in  $3 \times 3$  matrix form.

b. Show that for  $j=1$  only, it is legitimate to replace  $e^{-iJ_y\beta/\hbar}$  by

$$1 - i \left( \frac{J_y}{\hbar} \right) \sin \beta - \left( \frac{J_y}{\hbar} \right)^2 (1 - \cos \beta).$$

c. Using (b), prove

$$d^{(j=1)}(\beta) =$$

$$\begin{pmatrix} \left(\frac{1}{2}\right)(1 + \cos \beta) & -\left(\frac{1}{\sqrt{2}}\right) \sin \beta & \left(\frac{1}{2}\right)(1 - \cos \beta) \\ \left(\frac{1}{\sqrt{2}}\right) \sin \beta & \cos \beta & -\left(\frac{1}{\sqrt{2}}\right) \sin \beta \\ \left(\frac{1}{2}\right)(1 - \cos \beta) & \left(\frac{1}{\sqrt{2}}\right) \sin \beta & \left(\frac{1}{2}\right)(1 + \cos \beta) \end{pmatrix}.$$

(a)

$$\hat{J}_x = \hbar \begin{pmatrix} 0 & \frac{1}{\sqrt{2}} & 0 \\ \frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ 0 & \frac{1}{\sqrt{2}} & 0 \end{pmatrix}, \quad \hat{J}_y = \hbar \begin{pmatrix} 0 & -\frac{i}{\sqrt{2}} & 0 \\ \frac{i}{\sqrt{2}} & 0 & -\frac{i}{\sqrt{2}} \\ 0 & \frac{i}{\sqrt{2}} & 0 \end{pmatrix}, \quad \hat{J}_z = \hbar \begin{pmatrix} 1 & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -1 \end{pmatrix}$$

(b) and (c)

Taylor expansion:

$$\exp\left(-\frac{i}{\hbar}\theta\hat{J}_y\right) = 1 + \frac{1}{1!}\left(-\frac{i}{\hbar}\theta\hat{J}_y\right) + \frac{1}{2!}\left(-\frac{i}{\hbar}\theta\hat{J}_y\right)^2 + \frac{1}{3!}\left(-\frac{i}{\hbar}\theta\hat{J}_y\right)^3 + \frac{1}{4!}\left(-\frac{i}{\hbar}\theta\hat{J}_y\right)^4 + \dots$$

where

$$\hat{J}_y = \frac{\hat{J}_+ - \hat{J}_-}{2i}$$

Note that

$$\hat{J}_+|1\rangle = 0, \quad \hat{J}_+|0\rangle = \sqrt{2\hbar}|1\rangle, \quad \hat{J}_+|-1\rangle = \sqrt{2\hbar}|0\rangle$$

$$\hat{J}_-|1\rangle = \sqrt{2\hbar}|0\rangle, \quad \hat{J}_-|0\rangle = \sqrt{2\hbar}|-1\rangle, \quad \hat{J}_-|-1\rangle = 0$$

$$\hat{J}_y|1\rangle = \frac{i\hbar}{\sqrt{2}}|0\rangle, \quad \hat{J}_y|0\rangle = \frac{-i\hbar}{\sqrt{2}}(|1\rangle - |-1\rangle), \quad \hat{J}_y|-1\rangle = -\frac{i\hbar}{\sqrt{2}}|0\rangle$$

$$\hat{J}_y = \hbar \begin{pmatrix} 0 & -\frac{i}{\sqrt{2}} & 0 \\ \frac{i}{\sqrt{2}} & 0 & -\frac{i}{\sqrt{2}} \\ 0 & \frac{i}{\sqrt{2}} & 0 \end{pmatrix}, \quad \hat{J}_y^2 = -\hbar^2 \begin{pmatrix} -1 & 0 & 1 \\ 0 & -2 & 0 \\ 1 & 0 & -1 \end{pmatrix}$$

$$\hat{J}_y^3 = \hbar^2 \hat{J}_y, \quad \hat{J}_y^4 = \hat{J}_y^3 \hat{J}_y = \hbar^2 \hat{J}_y \hat{J}_y = \hbar^2 \hat{J}_y^2,$$

$$\hat{J}_y^5 = \hat{J}_y^4 \hat{J}_y = \hbar^2 \hat{J}_y^2 \hat{J}_y = \hbar^2 \hat{J}_y^3 = \hbar^4 \hat{J}_y$$

Therefore

$$\begin{aligned} \exp\left(-\frac{i}{\hbar}\theta\hat{J}_y\right) &= 1 + \frac{\hat{J}_y}{\hbar} [(-\theta) + \frac{1}{3!}(-i\theta)^3 + \frac{1}{5!}(-i\theta)^5 + \dots] \\ &\quad + \frac{\hat{J}_y^2}{\hbar^2} \left[ \frac{1}{2!}(-i\theta)^2 + \frac{1}{4!}(-i\theta)^4 + \dots \right] \\ &= 1 - \frac{\hat{J}_y}{\hbar} (i\sin\theta) + \frac{\hat{J}_y^2}{\hbar^2} (\cos\theta - 1) \end{aligned}$$

$$= \begin{pmatrix} \frac{1+\cos\theta}{2} & -\frac{\sin\theta}{\sqrt{2}} & \frac{1-\cos\theta}{2} \\ \frac{\sin\theta}{\sqrt{2}} & \cos\theta & -\frac{\sin\theta}{\sqrt{2}} \\ \frac{1-\cos\theta}{2} & \frac{\sin\theta}{\sqrt{2}} & \frac{1+\cos\theta}{2} \end{pmatrix}$$

We also get

$$\exp\left(-\frac{i}{\hbar}\phi\hat{J}_z\right) = \begin{pmatrix} e^{-i\phi} & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & e^{i\phi} \end{pmatrix}$$

which is a diagonal matrix.

(a) We use Mathematica to derive the matrix expression for the angular momentum with  $j = 1$ .

(\*Sakurai 3-22\*)

(\*a\*)

`Jx[l_, n_, m_] :=`

$$\frac{1}{2} \hbar \sqrt{(l-m)(l+m+1)} \text{KroneckerDelta}[n, m+1] +$$

$$\frac{1}{2} \hbar \sqrt{(l+m)(l-m+1)} \text{KroneckerDelta}[n, m-1]$$

`Jy[l_, n_, m_] :=`

$$-\frac{1}{2} i \hbar \sqrt{(l-m)(l+m+1)} \text{KroneckerDelta}[n, m+1] +$$

$$\frac{1}{2} i \hbar \sqrt{(l+m)(l-m+1)} \text{KroneckerDelta}[n, m-1]$$

`Jz[l_, n_, m_] := m \hbar \text{KroneckerDelta}[n, m]`

(\*Matrices j = 1\*)

`J1=Table[Jx[1,n,m],{n,1,-1,-1},{m,1,-1,-1}]`

$$\left\{ \left\{ 0, \frac{\hbar}{\sqrt{2}}, 0 \right\}, \left\{ \frac{\hbar}{\sqrt{2}}, 0, \frac{\hbar}{\sqrt{2}} \right\}, \left\{ 0, \frac{\hbar}{\sqrt{2}}, 0 \right\} \right\}$$

`J2=Table[Jy[1,n,m],{n,1,-1,-1},{m,1,-1,-1}]`

$$\left\{ \left\{ 0, -\frac{i\hbar}{\sqrt{2}}, 0 \right\}, \left\{ \frac{i\hbar}{\sqrt{2}}, 0, -\frac{i\hbar}{\sqrt{2}} \right\}, \left\{ 0, \frac{i\hbar}{\sqrt{2}}, 0 \right\} \right\}$$



**J3=Table[Jz[1,n,m],{n,1,-1,-1},{m,1,-1,-1}]**  
**{{ħ,0,0},{0,0,0},{0,0,-ħ}}**

**J1//MatrixForm**

$$\begin{pmatrix} 0 & \frac{\hbar}{\sqrt{2}} & 0 \\ \frac{\hbar}{\sqrt{2}} & 0 & \frac{\hbar}{\sqrt{2}} \\ 0 & \frac{\hbar}{\sqrt{2}} & 0 \end{pmatrix}$$

**J2//MatrixForm**

$$\begin{pmatrix} 0 & -\frac{i\hbar}{\sqrt{2}} & 0 \\ \frac{i\hbar}{\sqrt{2}} & 0 & -\frac{i\hbar}{\sqrt{2}} \\ 0 & \frac{i\hbar}{\sqrt{2}} & 0 \end{pmatrix}$$

**J3//MatrixForm**

$$\begin{pmatrix} \hbar & 0 & 0 \\ 0 & 0 & 0 \\ 0 & 0 & -\hbar \end{pmatrix}$$

**(\*b\*)**

**I1={{1,0,0},{0,1,0},{0,0,1}}**  
**{{1,0,0},{0,1,0},{0,0,1}}**

**I1//MatrixForm**

$$\begin{pmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{pmatrix}$$

**P1 = I1 - i  $\frac{J2}{\hbar}$  Sin[β] -  $\frac{1}{\hbar^2}$  J2.J2 (1 - Cos[β]) // Simplify**

$$\left\{ \left\{ \cos\left[\frac{\beta}{2}\right]^2, -\frac{\sin[\beta]}{\sqrt{2}}, \sin\left[\frac{\beta}{2}\right]^2 \right\}, \right.$$

$$\left. \left\{ \frac{\sin[\beta]}{\sqrt{2}}, \cos[\beta], -\frac{\sin[\beta]}{\sqrt{2}} \right\}, \left\{ \sin\left[\frac{\beta}{2}\right]^2, \frac{\sin[\beta]}{\sqrt{2}}, \cos\left[\frac{\beta}{2}\right]^2 \right\} \right\}$$

**P1//MatrixForm**

$$\begin{pmatrix} \cos\left[\frac{\beta}{2}\right]^2 & -\frac{\sin[\beta]}{\sqrt{2}} & \sin\left[\frac{\beta}{2}\right]^2 \\ \frac{\sin[\beta]}{\sqrt{2}} & \cos[\beta] & -\frac{\sin[\beta]}{\sqrt{2}} \\ \sin\left[\frac{\beta}{2}\right]^2 & \frac{\sin[\beta]}{\sqrt{2}} & \cos\left[\frac{\beta}{2}\right]^2 \end{pmatrix}$$

**(\*c\*)**

**MJ2 = MatrixExp[- $\frac{i}{\hbar}$  J2 β] // Simplify**

$$\left\{ \left\{ \cos \left[ \frac{\beta}{2} \right]^2, -\frac{\sin[\beta]}{\sqrt{2}}, \sin \left[ \frac{\beta}{2} \right]^2 \right\}, \right. \\ \left. \left\{ \frac{\sin[\beta]}{\sqrt{2}}, \cos[\beta], -\frac{\sin[\beta]}{\sqrt{2}} \right\}, \left\{ \sin \left[ \frac{\beta}{2} \right]^2, \frac{\sin[\beta]}{\sqrt{2}}, \cos \left[ \frac{\beta}{2} \right]^2 \right\} \right\}$$

**MJ2//MatrixForm**

$$\begin{pmatrix} \cos \left[ \frac{\beta}{2} \right]^2 & -\frac{\sin[\beta]}{\sqrt{2}} & \sin \left[ \frac{\beta}{2} \right]^2 \\ \frac{\sin[\beta]}{\sqrt{2}} & \cos[\beta] & -\frac{\sin[\beta]}{\sqrt{2}} \\ \sin \left[ \frac{\beta}{2} \right]^2 & \frac{\sin[\beta]}{\sqrt{2}} & \cos \left[ \frac{\beta}{2} \right]^2 \end{pmatrix}$$

**((3-24))**

24. Consider a system made up of two spin  $\frac{1}{2}$  particles. Observer A specializes in measuring the spin components of one of the particles ( $s_{1z}, s_{1x}$  and so on), while observer B measures the spin components of the other particle. Suppose the system is known to be in a spin-singlet state, that is,  $S_{\text{total}} = 0$ .

- What is the probability for observer A to obtain  $s_{1z} = \hbar/2$  when observer B makes no measurement? Same problem for  $s_{1x} = \hbar/2$ .
- Observer B determines the spin of particle 2 to be in the  $s_{2z} = \hbar/2$  state with certainty. What can we then conclude about the outcome of observer A's measurement if (i) A measures  $s_{1z}$  and (ii) A measures  $s_{1x}$ ? Justify your answer.

The singlet state is given by

$$|\psi\rangle = \frac{1}{\sqrt{2}}[|+-\rangle - |-+\rangle] \quad (1)$$

$$|+\rangle_x = \frac{1}{\sqrt{2}}[|+\rangle + |-\rangle] \quad \text{and} \quad |-\rangle_x = \frac{1}{\sqrt{2}}[|+\rangle - |-\rangle]$$

or

$$|+\rangle = \frac{1}{\sqrt{2}}[|+\rangle_x + |-\rangle_x]$$

$$|-\rangle = \frac{1}{\sqrt{2}}[|+\rangle_x - |-\rangle_x]$$

Therefore  $|\psi\rangle$  can be rewritten as

$$\begin{aligned} |\psi\rangle &= \frac{1}{\sqrt{2}}\left(\frac{1}{\sqrt{2}}[|+\rangle_x + |-\rangle_x]\right)\left(\frac{1}{\sqrt{2}}[|+\rangle_x - |-\rangle_x]\right) - \frac{1}{\sqrt{2}}\left(\frac{1}{\sqrt{2}}[|+\rangle_x - |-\rangle_x]\right)\left(\frac{1}{\sqrt{2}}[|+\rangle_x + |-\rangle_x]\right) \\ &= -\frac{1}{\sqrt{2}}(|+\rangle_x|-\rangle_x + |-\rangle_x|+\rangle_x) \end{aligned}$$

Apart from the overall sign, which in any case is a matter of convention, we could have guessed this from Eq.(1), because spin-singlet states have no preferred direction in space.

(a) Observer A specializes in measuring the spin components of one of the particles (1), while the observer M measures the spin components of the other particle.

What is the probability for the observer A to obtain  $S_{1z} = \hbar/2$  when the observer B makes no measurement? Same problem for  $S_{1x} = \hbar/2$ .

$$P(S_{1z} = \hbar/2) = |\langle ++|\psi\rangle|^2 + |\langle +-|\psi\rangle|^2 = \frac{1}{2}$$

$$P(S_{1x} = \hbar/2) = \left| \langle +_x | \langle +_x | \psi \rangle \right|^2 + \left| \langle +_x | \langle -_x | \psi \rangle \right|^2 = \frac{1}{2}$$

(b) Observer B determines the spin of particles 2 to be in the  $S_{2z} = \hbar/2$  state with certainty. What can we then conclude about the outcome of the observer A's measurement if (i) A measures  $S_{1z}$  and (ii) A measures  $S_{1x}$ ? Justify your answer.

After the measurement of  $S_{2z} = \hbar/2$  by observer B, the state becomes

$$|\psi'\rangle = -|--\rangle$$

(i)

$$P(S_{1z} = \frac{\hbar}{2}) = |\langle ++|\psi'\rangle|^2 + |\langle +-|\psi'\rangle|^2 = 0$$

$$P(S_{1z} = -\frac{\hbar}{2}) = |\langle -+|\psi'\rangle|^2 + |\langle --|\psi'\rangle|^2 = 1$$

(ii)

$$P(S_{1x} = \frac{\hbar}{2}) = \left| \langle + | \langle + | \psi' \rangle \right|^2 + \left| \langle + | \langle - | \psi' \rangle \right|^2 = \frac{1}{2}$$

$$P(S_{1x} = -\frac{\hbar}{2}) = \left| \langle - | \langle + | \psi' \rangle \right|^2 + \left| \langle - | \langle - | \psi' \rangle \right|^2 = \frac{1}{2}$$

((3-25))

25. Consider a spherical tensor of rank 1 (that is, a vector)

$$V_{\pm 1}^{(1)} = \mp \frac{V_x \pm iV_y}{\sqrt{2}}, \quad V_0^{(1)} = V_z.$$

Using the expression for  $d^{(j=1)}$  given in Problem 22, evaluate

$$\sum_{q'} d_{qq'}^{(1)}(\beta) V_{q'}^{(1)}$$

and show that your results are just what you expect from the transformation properties of  $V_{x,y,z}$  under rotations about the  $y$ -axis.

$$\begin{pmatrix} V_1^{(1)} \\ V_0^{(1)} \\ V_{-1}^{(1)} \end{pmatrix} = \begin{pmatrix} \frac{1+\cos\theta}{2} & -\frac{\sin\theta}{\sqrt{2}} & \frac{1-\cos\theta}{2} \\ \frac{\sin\theta}{\sqrt{2}} & \cos\theta & -\frac{\sin\theta}{\sqrt{2}} \\ \frac{1-\cos\theta}{2} & \frac{\sin\theta}{\sqrt{2}} & \frac{1+\cos\theta}{2} \end{pmatrix} \begin{pmatrix} V_1^{(1)} \\ V_0^{(1)} \\ V_{-1}^{(1)} \end{pmatrix}$$

On the other hand,

$$\mathfrak{R} = \begin{pmatrix} \mathfrak{R}_{11} & \mathfrak{R}_{12} & \mathfrak{R}_{13} \\ \mathfrak{R}_{21} & \mathfrak{R}_{22} & \mathfrak{R}_{23} \\ \mathfrak{R}_{31} & \mathfrak{R}_{32} & \mathfrak{R}_{33} \end{pmatrix} = \begin{pmatrix} \cos\beta & 0 & \sin\beta \\ 0 & 1 & 0 \\ -\sin\beta & 0 & \cos\beta \end{pmatrix}$$

$$\begin{pmatrix} V_x' \\ V_y' \\ V_z' \end{pmatrix} = \begin{pmatrix} \cos\beta & 0 & \sin\beta \\ 0 & 1 & 0 \\ -\sin\beta & 0 & \cos\beta \end{pmatrix} \begin{pmatrix} V_x \\ V_y \\ V_z \end{pmatrix}$$

$$\begin{pmatrix} V_1^{(1)} \\ V_0^{(1)} \\ V_{-1}^{(1)} \end{pmatrix} = \begin{pmatrix} -\frac{V_x + iV_y}{\sqrt{2}} \\ V_z \\ \frac{V_x - iV_y}{\sqrt{2}} \end{pmatrix} = \begin{pmatrix} -\frac{1}{\sqrt{2}} & -\frac{i}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \\ \frac{1}{\sqrt{2}} & -\frac{i}{\sqrt{2}} & 0 \end{pmatrix} \begin{pmatrix} V_x \\ V_y \\ V_z \end{pmatrix}$$

$$\begin{pmatrix} V_1^{(1)} \\ V_0^{(1)} \\ V_{-1}^{(1)} \end{pmatrix} = \begin{pmatrix} -\frac{1}{\sqrt{2}} & -\frac{i}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \\ \frac{1}{\sqrt{2}} & -\frac{i}{\sqrt{2}} & 0 \end{pmatrix} \begin{pmatrix} V_x' \\ V_y' \\ V_z' \end{pmatrix} = \begin{pmatrix} -\frac{1}{\sqrt{2}} & -\frac{i}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \\ \frac{1}{\sqrt{2}} & -\frac{i}{\sqrt{2}} & 0 \end{pmatrix} \begin{pmatrix} \cos \beta & 0 & \sin \beta \\ 0 & 1 & 0 \\ -\sin \beta & 0 & \cos \beta \end{pmatrix} \begin{pmatrix} V_x \\ V_y \\ V_z \end{pmatrix} \text{ or}$$

or

$$\begin{pmatrix} V_1^{(1)} \\ V_0^{(1)} \\ V_{-1}^{(1)} \end{pmatrix} = \begin{pmatrix} -\frac{1}{\sqrt{2}} & -\frac{i}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \\ \frac{1}{\sqrt{2}} & -\frac{i}{\sqrt{2}} & 0 \end{pmatrix} \begin{pmatrix} \cos \beta & 0 & \sin \beta \\ 0 & 1 & 0 \\ -\sin \beta & 0 & \cos \beta \end{pmatrix} \begin{pmatrix} -\frac{1}{\sqrt{2}} & -\frac{i}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \\ \frac{1}{\sqrt{2}} & -\frac{i}{\sqrt{2}} & 0 \end{pmatrix}^{-1} \begin{pmatrix} V_1^{(1)} \\ V_0^{(1)} \\ V_{-1}^{(1)} \end{pmatrix}$$

Using Mathematica 5.2, we have

$$\begin{pmatrix} V_1^{(1)} \\ V_0^{(1)} \\ V_{-1}^{(1)} \end{pmatrix} = \begin{pmatrix} \frac{1 + \cos \theta}{2} & -\frac{\sin \theta}{\sqrt{2}} & \frac{1 - \cos \theta}{2} \\ \frac{\sin \theta}{\sqrt{2}} & \cos \theta & -\frac{\sin \theta}{\sqrt{2}} \\ \frac{1 - \cos \theta}{2} & \frac{\sin \theta}{\sqrt{2}} & \frac{1 + \cos \theta}{2} \end{pmatrix} \begin{pmatrix} V_1^{(1)} \\ V_0^{(1)} \\ V_{-1}^{(1)} \end{pmatrix}$$

**((Mathematica 5.2))**

$$\mathbf{A} = \left\{ \left\{ -\frac{1}{\sqrt{2}}, -\frac{i}{\sqrt{2}}, 0 \right\}, \{0, 0, 1\}, \left\{ \frac{1}{\sqrt{2}}, -\frac{i}{\sqrt{2}}, 0 \right\} \right\}$$

$$\left\{ \left\{ -\frac{1}{\sqrt{2}}, -\frac{i}{\sqrt{2}}, 0 \right\}, \right. \\ \left. \left\{ 0, 0, 1 \right\}, \left\{ \frac{1}{\sqrt{2}}, -\frac{i}{\sqrt{2}}, 0 \right\} \right\}$$

**A//MatrixForm**

$$\begin{pmatrix} -\frac{1}{\sqrt{2}} & -\frac{i}{\sqrt{2}} & 0 \\ 0 & 0 & 1 \\ \frac{1}{\sqrt{2}} & -\frac{i}{\sqrt{2}} & 0 \end{pmatrix}$$

**Inverse[A]//MatrixForm**

$$\begin{pmatrix} -\frac{1}{\sqrt{2}} & 0 & \frac{1}{\sqrt{2}} \\ \frac{i}{\sqrt{2}} & 0 & \frac{i}{\sqrt{2}} \\ 0 & 1 & 0 \end{pmatrix}$$

**M={{Cos[β], 0, Sin[β]}, {0, 1, 0}, {-Sin[β], 0, Cos[β]}}**  
**{{Cos[β], 0, Sin[β]}, {0, 1, 0}, {-Sin[β], 0, Cos[β]}}**

**M//MatrixForm**

$$\begin{pmatrix} \text{Cos}[\beta] & 0 & \text{Sin}[\beta] \\ 0 & 1 & 0 \\ -\text{Sin}[\beta] & 0 & \text{Cos}[\beta] \end{pmatrix}$$

**A.M.Inverse[A]//Simplify**

$$\left\{ \left\{ \text{Cos}\left[\frac{\beta}{2}\right]^2, -\frac{\text{Sin}[\beta]}{\sqrt{2}}, \text{Sin}\left[\frac{\beta}{2}\right]^2 \right\}, \right. \\ \left. \left\{ \frac{\text{Sin}[\beta]}{\sqrt{2}}, \text{Cos}[\beta], -\frac{\text{Sin}[\beta]}{\sqrt{2}} \right\}, \right. \\ \left. \left\{ \text{Sin}\left[\frac{\beta}{2}\right]^2, \frac{\text{Sin}[\beta]}{\sqrt{2}}, \text{Cos}\left[\frac{\beta}{2}\right]^2 \right\} \right\}$$

**((3-26))**

26. a. Construct a spherical tensor of rank 1 out of two different vectors  $\mathbf{U} = (U_x, U_y, U_z)$  and  $\mathbf{V} = (V_x, V_y, V_z)$ . Explicitly write  $T_{\pm 1, 0}^{(1)}$  in terms of  $U_{x, y, z}$  and  $V_{x, y, z}$ .
- b. Construct a spherical tensor of rank 2 out of two different vectors  $\mathbf{U}$  and  $\mathbf{V}$ . Write down explicitly  $T_{\pm 2, \pm 1, 0}^{(2)}$  in terms of  $U_{x, y, z}$  and  $V_{x, y, z}$ .

(a)

The spherical tensor of rank-1:

The quantity

$$P_{l,m}(x, y, z) = r^l Y_l^m(\theta, \phi)$$

is a homogeneous polynomial of order  $l$ .

The quantity  $P_{1,q}(x, y, z) = \sqrt{\frac{4\pi}{3}} r Y_1^q(\theta, \phi)$  is a first order homogeneous polynomial in  $x$ ,  $y$ , and  $z$ .

$$P_{1,1}(x, y, z) = \sqrt{\frac{4\pi}{3}} r Y_1^1(\theta, \phi) = -\frac{x + iy}{\sqrt{2}}$$

$$T_1^{(1)} = -\frac{\hat{V}_x + i\hat{V}_y}{\sqrt{2}}, \quad T_1^{(1)} = -\frac{\hat{U}_x + i\hat{U}_y}{\sqrt{2}}$$

$$P_{1,0}(x, y, z) = \sqrt{\frac{4\pi}{3}} r Y_1^0(\theta, \phi) = z$$

$$T_0^{(1)} = \hat{V}_z, \quad T_0^{(1)} = \hat{U}_z$$

$$P_{1,-1}(x, y, z) = \sqrt{\frac{4\pi}{3}} r Y_1^{-1}(\theta, \phi) = \frac{x - iy}{\sqrt{2}}$$

$$T_{-1}^{(1)} = \frac{\hat{V}_x - i\hat{V}_y}{\sqrt{2}}, \quad T_{-1}^{(1)} = \frac{\hat{U}_x - i\hat{U}_y}{\sqrt{2}}$$

(b)

The spherical tensor of rank-2:

We use the following theorem.

When  $\hat{U}_{q_1}^{(k_1)}$  and  $\hat{V}_{q_2}^{(k_2)}$  be irreducible spherical tensors of rank  $k_1$  and  $k_2$ , respectively.

Then

$$\hat{T}_q^{(k)} = \sum_{q_1, q_2} \langle k_1, k_2; q_1, q_2 | k_1, k_2; k, q \rangle \hat{U}_{q_1}^{(k_1)} V_{q_2}^{(k_2)}$$

is a spherical (irreducible) tensor of rank  $k$ .

$\langle k_1, k_2; q_1, q_2 | k_1, k_2; k, q \rangle$  is the Clebsch-Gordan coefficient.

Using the Mathematica 5.2 we get

$$T_2^{(2)} = X_1^{(1)} Z_1^{(1)} = U_1 V_1$$

$$T_1^{(2)} = \frac{X_1^{(1)} Z_0^{(1)} + X_0^{(1)} Z_1^{(1)}}{\sqrt{2}} = \frac{U_1 V_0 + U_0 V_1}{\sqrt{2}}$$

$$T_0^{(2)} = \frac{X_1^{(1)} Z_{-1}^{(1)} + 2X_0^{(1)} Z_0^{(1)} + X_{-1}^{(1)} Z_1^{(1)}}{\sqrt{6}} = \frac{U_1 V_{-1} + 2U_0 V_0 + U_{-1} V_1}{\sqrt{6}}$$

$$T_{-1}^{(2)} = \frac{X_0^{(1)} Z_{-1}^{(1)} + X_{-1}^{(1)} Z_0^{(1)}}{\sqrt{2}} = \frac{U_0 V_{-1} + U_{-1} V_1}{\sqrt{2}}$$

$$T_{-2}^{(2)} = X_{-1}^{(1)} Z_{-1}^{(1)} = U_{-1} V_{-1}$$

((Mathematica 5.2))

(\*Determination of CG co-efficient  
\*)

```
CG[j1_, j2_, j_] := Table[Sum[ClebschGordan[{j1, k1}, {j2, k2}, {j, k1+k2}], {k1, -j1, j1}, {k2, -j2, j2}], {m, -j, j}]
CG[1, 1, 2] // TableForm
```

```
X[1, -1] Z[1, -1]
```

$$\frac{X[1, 0] Z[1, -1]}{\sqrt{2}} + \frac{X[1, -1] Z[1, 0]}{\sqrt{2}}$$

$$\frac{X[1, 1] Z[1, -1]}{\sqrt{6}} + \sqrt{\frac{2}{3}} X[1, 0] Z[1, 0] + \frac{X[1, -1] Z[1, 1]}{\sqrt{6}}$$

$$\frac{X[1, 1] Z[1, 0]}{\sqrt{2}} + \frac{X[1, 0] Z[1, 1]}{\sqrt{2}}$$

```
X[1, 1] Z[1, 1]
```



---

((3-27))

27. Consider a spinless particle bound to a fixed center by a central force potential.

a. Relate, as much as possible, the matrix elements

$$\langle n', l', m' | \mp \frac{1}{\sqrt{2}} (x \pm iy) | n, l, m \rangle \quad \text{and} \quad \langle n', l', m' | z | n, l, m \rangle$$

using *only* the Wigner-Eckart theorem. Make sure to state under what conditions the matrix elements are nonvanishing.

b. Do the same problem using wave functions  $\psi(\mathbf{x}) = R_{nl}(r)Y_l^m(\theta, \phi)$ .

---

$$\langle n', l' m' | \mp \frac{1}{\sqrt{2}} (\hat{x} + i\hat{y}) | n, l, m \rangle = \langle n', l' m' | T_{\pm 1}^{(1)} | n, l, m \rangle$$

$$\langle n', l' m' | \hat{z} | n, l, m \rangle = \langle n', l' m' | T_0^{(1)} | n, l, m \rangle$$

We now consider the matrix element

$$\langle n', l' m' | T_q^{(1)} | n, l, m \rangle$$

with  $q = 0$  and  $1$ . According to the Wigner-Eckart theorem, this matrix element is equal to zero unless

$$m' = m \pm q$$

$$l' = l + 1, l - 1$$

However, we know that

$$\hat{\pi} T_{\pm 1}^{(1)} \hat{\pi} = -T_{\pm 1}^{(1)} \quad \text{and} \quad \hat{\pi} | n, l, m \rangle = (-1)^l | n, l, m \rangle$$

where  $\hat{\pi}$  is the parity operator.

$$\langle n', l', m' | T_{\pm 1}^{(1)} | n, l, m \rangle = 0$$

when  $l' = l$ .

Thus the matrix element is equal to zero unless

$$m' = m \pm q$$

$$l' = l + 1, l - 1$$

((Note))

$$\hat{T}_1^{(1)} = -\frac{\hat{x} + i\hat{y}}{\sqrt{2}}, \quad \hat{T}_0^{(1)} = \hat{z}, \quad \hat{T}_{-1}^{(1)} = \frac{\hat{x} - i\hat{y}}{\sqrt{2}}$$

---

((3-28))

28. a. Write  $xy$ ,  $xz$ , and  $(x^2 - y^2)$  as components of a spherical (irreducible) tensor of rank 2.

b. The expectation value

$$Q \equiv e \langle \alpha, j, m = j | (3z^2 - r^2) | \alpha, j, m = j \rangle$$

is known as the *quadrupole moment*. Evaluate

$$e \langle \alpha, j, m' | (x^2 - y^2) | \alpha, j, m = j \rangle,$$

(where  $m' = j, j-1, j-2, \dots$ ) in terms of  $Q$  and appropriate Clebsch-Gordan coefficients.

---

(a)

$$\hat{x}\hat{y} = \frac{\hat{T}_2^{(2)} - \hat{T}_{-2}^{(2)}}{2i}$$

$$\hat{x}\hat{z} = \frac{-\hat{T}_1^{(2)} + \hat{T}_{-1}^{(2)}}{2}$$

$$\hat{x}^2 - \hat{y}^2 = \hat{T}_2^{(2)} + \hat{T}_{-2}^{(2)}$$

(b)

$$Q = e \langle \alpha; j, m' = j | 2\hat{z}^2 - \hat{x}^2 - \hat{y}^2 | \alpha; j, m = j \rangle = e\sqrt{6} \langle \alpha; j, m' = j | \hat{T}_0^{(2)} | \alpha; j, m = j \rangle$$

$$e \langle \alpha; j, m' | \hat{x}^2 - \hat{y}^2 | \alpha; j, m = j \rangle = e \langle \alpha; j, m' | \hat{T}_2^{(2)} + \hat{T}_{-2}^{(2)} | \alpha; j, m = j \rangle$$

$$= e \langle \alpha; j, j-2 | \hat{T}_{-2}^{(2)} | \alpha; j, m = j \rangle$$

from the Wigner-Eckart theorem

$$Q = e\sqrt{6} \langle \alpha; j, m' = j | \hat{T}_0^{(2)} | \alpha; j, m = j \rangle = e\sqrt{6} \langle j, 2; j, 0 | j, 2; j, j \rangle \frac{\langle \alpha' j | \hat{T}^{(k)} | \alpha j \rangle}{\sqrt{2j+1}}$$

$$e\langle \alpha; j, j-2 | \hat{T}_{-2}^{(2)} | \alpha; j, m = j \rangle = e\langle j, 2; j, -2 | j, 2; j, j-2 \rangle \frac{\langle \alpha j | \hat{T}^{(k)} | \alpha j \rangle}{\sqrt{2j+1}}$$

Then we have

$$\frac{e\langle \alpha; j, j-2 | \hat{T}_{-2}^{(2)} | \alpha; j, m = j \rangle}{Q} = \frac{e\langle j, 2; j, -2 | j, 2; j, j-2 \rangle \frac{\langle \alpha j | \hat{T}^{(k)} | \alpha j \rangle}{\sqrt{2j+1}}}{e\sqrt{6}\langle j, 2; j, 0 | j, 2; j, j \rangle \frac{\langle \alpha' j | \hat{T}^{(k)} | \alpha j \rangle}{\sqrt{2j+1}}}$$

or

$$\frac{e\langle \alpha; j, j-2 | \hat{T}_{-2}^{(2)} | \alpha; j, m = j \rangle}{Q} = \frac{\langle j, 2; j, -2 | j, 2; j, j-2 \rangle}{\sqrt{6}\langle j, 2; j, 0 | j, 2; j, j \rangle} = \frac{1}{\sqrt{j(2j-1)}}$$

((Note-1))

$$\hat{x}^2 - \hat{y}^2 = \hat{T}_2^{(2)} + \hat{T}_{-2}^{(2)}$$

$$\hat{x}\hat{y} = \frac{\hat{T}_2^{(2)} - \hat{T}_{-2}^{(2)}}{2i}$$

$$\hat{y}\hat{z} = \frac{\hat{T}_1^{(2)} + \hat{T}_{-1}^{(2)}}{-2i}$$

$$\hat{x}\hat{z} = \frac{\hat{T}_1^{(2)} - \hat{T}_{-1}^{(2)}}{-2}$$

$$\left( \frac{\hat{x}^2 + \hat{y}^2 - 2\hat{z}^2}{\sqrt{6}} \right) = -\hat{T}_0^{(2)}$$

((Note-2))

$$\langle \alpha'; j', m' | \hat{T}_q^{(k)} | \alpha; j, m \rangle = \langle j, k; m, q | j, k; j', m' \rangle \frac{\langle \alpha' j' | \hat{T}^{(k)} | \alpha j \rangle}{\sqrt{2j+1}}$$

((3-29))

29. A spin  $\frac{3}{2}$  nucleus situated at the origin is subjected to an external inhomogeneous electric field. The basic electric quadrupole interaction may be taken to be

$$H_{\text{int}} = \frac{eQ}{2s(s-1)\hbar^2} \left[ \left( \frac{\partial^2 \phi}{\partial x^2} \right)_0 S_x^2 + \left( \frac{\partial^2 \phi}{\partial y^2} \right)_0 S_y^2 + \left( \frac{\partial^2 \phi}{\partial z^2} \right)_0 S_z^2 \right],$$

where  $\phi$  is the electrostatic potential satisfying Laplace's equation and the coordinate axes are so chosen that

$$\left( \frac{\partial^2 \phi}{\partial x \partial y} \right)_0 = \left( \frac{\partial^2 \phi}{\partial y \partial z} \right)_0 = \left( \frac{\partial^2 \phi}{\partial x \partial z} \right)_0 = 0.$$

Show that the interaction energy can be written as

$$A(3S_z^2 - \mathbf{S}^2) + B(S_+^2 + S_-^2),$$

and express  $A$  and  $B$  in terms of  $(\partial^2 \phi / \partial x^2)_0$  and so on. Determine the energy eigenkets (in terms of  $|m\rangle$ , where  $m = \pm \frac{3}{2}, \pm \frac{1}{2}$ ) and the corresponding energy eigenvalues. Is there any degeneracy?

We solve the last part of the problem using Mathematica 5.2.

(\* Sakurai 3-29 Spin 3/2 matrix elements\*)

$$\mathbf{Sx} = \frac{1}{2} \left\{ \{0, \sqrt{3}, 0, 0\}, \{\sqrt{3}, 0, 2, 0\}, \right.$$

$$\left. \{0, 2, 0, \sqrt{3}\}, \{0, 0, \sqrt{3}, 0\} \right\}$$

$$\left\{ \left\{ 0, \frac{\sqrt{3}}{2}, 0, 0 \right\}, \left\{ \frac{\sqrt{3}}{2}, 0, 1, 0 \right\}, \right.$$

$$\left. \left\{ 0, 1, 0, \frac{\sqrt{3}}{2} \right\}, \left\{ 0, 0, \frac{\sqrt{3}}{2}, 0 \right\} \right\}$$

**Sx//MatrixForm**

$$\begin{pmatrix} 0 & \frac{\sqrt{3}}{2} & 0 & 0 \\ \frac{\sqrt{3}}{2} & 0 & 1 & 0 \\ 0 & 1 & 0 & \frac{\sqrt{3}}{2} \\ 0 & 0 & \frac{\sqrt{3}}{2} & 0 \end{pmatrix}$$

**Sy =**

$$\frac{1}{2} \left\{ \{0, -\sqrt{3}i, 0, 0\}, \{\sqrt{3}i, 0, -2i, 0\}, \right. \\ \left. \{0, 2i, 0, -\sqrt{3}i\}, \{0, 0, \sqrt{3}i, 0\} \right\} \\ \left\{ \left\{ 0, -\frac{i\sqrt{3}}{2}, 0, 0 \right\}, \left\{ \frac{i\sqrt{3}}{2}, 0, -i, 0 \right\}, \right. \\ \left. \left\{ 0, i, 0, -\frac{i\sqrt{3}}{2} \right\}, \left\{ 0, 0, \frac{i\sqrt{3}}{2}, 0 \right\} \right\}$$

**Sy//MatrixForm**

$$\begin{pmatrix} 0 & -\frac{i\sqrt{3}}{2} & 0 & 0 \\ \frac{i\sqrt{3}}{2} & 0 & -i & 0 \\ 0 & i & 0 & -\frac{i\sqrt{3}}{2} \\ 0 & 0 & \frac{i\sqrt{3}}{2} & 0 \end{pmatrix}$$

$$\mathbf{Sz} = \frac{1}{2} \left\{ \{3, 0, 0, 0\}, \{0, 1, 0, 0\}, \right.$$

$$\left. \{0, 0, -1, 0\}, \{0, 0, 0, -3\} \right\} \\ \left\{ \left\{ \frac{3}{2}, 0, 0, 0 \right\}, \left\{ 0, \frac{1}{2}, 0, 0 \right\}, \right. \\ \left. \left\{ 0, 0, -\frac{1}{2}, 0 \right\}, \left\{ 0, 0, 0, -\frac{3}{2} \right\} \right\}$$

**Sz//MatrixForm**

$$\begin{pmatrix} \frac{3}{2} & 0 & 0 & 0 \\ 0 & \frac{1}{2} & 0 & 0 \\ 0 & 0 & -\frac{1}{2} & 0 \\ 0 & 0 & 0 & -\frac{3}{2} \end{pmatrix}$$

$$\mathbf{Sp} = \mathbf{Sx} + i \mathbf{Sy}$$

$$\left\{ \left\{ 0, \sqrt{3}, 0, 0 \right\}, \left\{ 0, 0, 2, 0 \right\}, \right. \\ \left. \left\{ 0, 0, 0, \sqrt{3} \right\}, \left\{ 0, 0, 0, 0 \right\} \right\}$$

$$\mathbf{Sm} = \mathbf{Sx} - i \mathbf{Sy}$$

$$\left\{ \left\{ 0, 0, 0, 0 \right\}, \left\{ \sqrt{3}, 0, 0, 0 \right\}, \right. \\ \left. \left\{ 0, 2, 0, 0 \right\}, \left\{ 0, 0, \sqrt{3}, 0 \right\} \right\}$$

$$\mathbf{H} = \mathbf{A} (3 \mathbf{Sz} \cdot \mathbf{Sz} - \mathbf{Sx} \cdot \mathbf{Sx} - \mathbf{Sy} \cdot \mathbf{Sy} - \mathbf{Sz} \cdot \mathbf{Sz}) + \mathbf{B} (\mathbf{Sp} \cdot \mathbf{Sp} + \mathbf{Sm} \cdot \mathbf{Sm})$$

$$\left\{ \left\{ 3 \mathbf{A}, 0, 2 \sqrt{3} \mathbf{B}, 0 \right\}, \left\{ 0, -3 \mathbf{A}, 0, 2 \sqrt{3} \mathbf{B} \right\}, \right. \\ \left. \left\{ 2 \sqrt{3} \mathbf{B}, 0, -3 \mathbf{A}, 0 \right\}, \left\{ 0, 2 \sqrt{3} \mathbf{B}, 0, 3 \mathbf{A} \right\} \right\}$$

$$\mathbf{H} // \text{MatrixForm}$$

$$\begin{pmatrix} 3 \mathbf{A} & 0 & 2 \sqrt{3} \mathbf{B} & 0 \\ 0 & -3 \mathbf{A} & 0 & 2 \sqrt{3} \mathbf{B} \\ 2 \sqrt{3} \mathbf{B} & 0 & -3 \mathbf{A} & 0 \\ 0 & 2 \sqrt{3} \mathbf{B} & 0 & 3 \mathbf{A} \end{pmatrix}$$

$$\mathbf{Eigensystem}[\mathbf{H}] // \text{Simplify}$$

$$\left\{ \left\{ -\sqrt{9 \mathbf{A}^2 + 12 \mathbf{B}^2}, -\sqrt{9 \mathbf{A}^2 + 12 \mathbf{B}^2}, \right. \right. \\ \left. \left. \sqrt{9 \mathbf{A}^2 + 12 \mathbf{B}^2}, \sqrt{9 \mathbf{A}^2 + 12 \mathbf{B}^2} \right\}, \right. \\ \left\{ \left\{ 0, -\frac{\sqrt{3} \mathbf{A} + \sqrt{3 \mathbf{A}^2 + 4 \mathbf{B}^2}}{2 \mathbf{B}}, 0, 1 \right\}, \right. \\ \left\{ \frac{\sqrt{3} \mathbf{A} - \sqrt{3 \mathbf{A}^2 + 4 \mathbf{B}^2}}{2 \mathbf{B}}, 0, 1, 0 \right\}, \\ \left\{ 0, \frac{-\sqrt{3} \mathbf{A} + \sqrt{3 \mathbf{A}^2 + 4 \mathbf{B}^2}}{2 \mathbf{B}}, 0, 1 \right\}, \\ \left. \left. \left\{ \frac{\sqrt{3} \mathbf{A} + \sqrt{3 \mathbf{A}^2 + 4 \mathbf{B}^2}}{2 \mathbf{B}}, 0, 1, 0 \right\} \right\} \right\}$$